GEFRAN

40B96

POSITION, FORCE and PRESSURE INDICATOR-INTERCEPTOR with INPUT for STRAIN-GAUGE and POTENTIOMETER



INSTRUCTIONS FOR USE **AND WARNINGS**

Software Version 3.2x

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The contents of each section are summarized immediately following the section heading

Graphic symbols used

To distinguish between the type and importance of the information provided in these instructions for use, graphic symbols have been used as a reference to make interpreting the information clearer.



Indicates the contents of the various manual sections, the general warnings, notes, and other points to which the reader's attention should be drawn.



Indicates a particularly delicate situation that could affect the safety and correct working operation of the instrument, or a rule that must be strictly observed to avoid dangerous situations



Indicates a suggestion based on the experience of the GEFRAN Technical Staff, which could prove especially useful under given circumstances



Indicates a reference to Detailed Technical Documents available on the GEFRAN web site www.gefran.com



Indicates a condition of risk for the safety of the user, due to the presence of dangerous voltages at the points shown



In the programming and configuration flows for the controller, indicates **all** the parameters that can be set in the configuration.

1 · PRELIMINARY INSTRUCTIONS

This section contains information and warnings of a general nature which should be read before proceeding with instrument installation, configuration and use.

- transmitter power supply
- analog retransmission output
- a maximum of 4 outputs
- RS485 interface

General Description

GEFRAN series 40B96 digital controllers have been designed for temperature control in any applications involving heating or cooling processes. They represent an exclusive combination of performance, reliability and applicational flexibility. In particular, this new line of Gefran temperature controllers is the ideal solution for application in sectors where performance and service continuity are important, including:

- extrusion lines
- presses for rubber
- · test benches
- honing machines
- · processing plant for the food industry
- weighing
- manostat
- positioner
- motopotentiometer
- etc.

The 40B96 series interceptors are made on an extremely versatile hardware and software platform, that allows the most suitable I/O composition for the plant to be chosen from a series of options, up to a maximum of:

- variable input
- digital input

Alarm unit in basic version

- 1 input that allows connection of most popular sensor types
- potentiometer with 100 ohm minimum resistance
- load cells with autoranging sensitivity from 1.5 to 3.3 mV/V
- strain-gauge pressure probes accuracy better than 0.2% f.s.
- output for sensor or transmitter power supply
- 1.2 Vdc for potentiometer
- 5Vdc, 10Vdc max 120 mA for strain-gauge
- 15Vdc, 24Vdc max 50 mA for transmitter
- 2 standard outputs: one relay type and the other relay/logic, or

1 triac output

- display functions with setting of engineering scale and possible linearization, settable decimal point position, sampling time from 30 to 120 msec
- trip point values can be set in a range differing from scale limits, different modalities, hysteresis settable in scale points or time, with or without latch.
- service **serial line** for configuration via PC (Winstrum)

Options

- 3rd relay output
- 4th relay output (alternative to analog retransmission output)
- 1 digital input
- 1 analog retransmission output in current 0/4...20mA or voltage 0...10V (alternative to 4th relay output)
- RS485 optically isolated serial interface

Operator Interface

All the operator interface devices are concentrated on the controller faceplate, suitably protected by membrane in Lexan that guarantees IP65 level а protection.

- 3 buttons to be used for manual configuration/selection
- 1 red five-digit displays (Process Variable)
- 4 red LEDs for status indication of same number of relay/logic outputs

Electrical Interface

All connection terminals (power supply, inputs, outputs, options) are grouped together on the back of the instrument.

For technical specifications and performance details refer to Section 5 "Technical Specifications".

Preliminary Warnings

The following preliminary warnings should be read before installing and using the series 40B ceptor. This will allow the controller to be put vice more quickly and will avoid certain problems nay mistakenly be interpreted as malfunctions or ns of the interceptor.

· Immediately after unpacking the controller, make a note of the order code and the other identification data given on the label affixed to the outside of the container and copy them to the table below.

These details must always be kept close at hand and referred to the personnel involved in the event of help from Gefran Customer Service Assistance.

| SN: | (Serial no.) |
|---------|---------------------------------------|
| | (Finished product code) |
| TYPE: | (Order Code) |
| SUPPLY: | (Type of electrical power supply) |
| VERS: | (Software version) |

Check also that the controller is complete and has not been damaged at all during transit, and that the package contains not only the instrument and these Instructions for Use, but also the two brackets for fixing to the panel and the dust protection seal - see: Installation with Panel Fixing in Section 2.

- Any inconsistencies, omissions or evident signs of damage should be reported immediately to your Gefran sales agent.
- Check that the order code corresponds with the configuration requested for the application the controller is needed for, referring to Section 7: "Technical - Commercial Information".
 - No. and Type of Inputs/Outputs available
 - Presence of the necessary options and accessories
 - Mains voltage supply

Ex: 40B - 24 - RR - 00 - 1 - 2 - 1 Model 40B96 alarm unit

24 V output for transmitter power supply

Output 1 - Relay; Output 2 - Relay,

Output 3 - none

Digital Input - no analog retransmission

RS485 Digital Communication

Power supply 100...240Vac/dc

- Before installing the series 40B96 instrument on the control panel of the machine or host system, refer to the paragraph "Dimensions and Cut-out" in Section 2 "Installation and Connection".
- Where configuration by PC is provided for, make sure the interface RS232 cable is available and the CD- ROM containing the WINSTRUM software. For the order code refer to Section 7 "Technical -Commercial Information"...



ıd/or system integrators who wish to know more encepts of serial communication between standard PC and/or Gefran Industrial PC and Gefran Programmable Instruments, can access the various technical reference Documents in crobat format available in the Download section efran Web Site www.gefran.com including:

- · Serial Communication
- MODBus Protocol

In the same Download section of the Gefran Web Site www.gefran.com the reference s available in Adobe Acrobat format. In the event of presumed instrument malfunction, before contacting Gefran Technical Service Assistance, refer to the Troubleshooting Guide given in Section 6 "Maintenance", and if necessary refer to the F.A.Q. Section (Frequently Asked Questions) on the Gefran Web Site www.gefran.com

NSTALLATION AND CONNECTION



This section contains the instructions necessary for correct installation of the 40B96 instrument into the machine control panel or the host system and for correct connection of the interceptor power supply, inputs, outputs and interfaces.



Before proceeding with installation read the following warnings carefully!

Remember that lack of observation of these warnings could lead to problems of electrical safety and electromagnetic compatibility, as well as invalidating the warranty.

Electrical power supply

• the instrument is NOT equipped with an On/Off switch: the user must provide a two-phase disconnecting switch that conforms to the required safety standards (CE marking), to cut off the power supply upstream of the instrument.

The switch must be located in the immediate vicinity of the instrument and must be within easy reach of the

One switch may control more than one instrument.

· if the instrument is connected to NOT isolated electrical equipment (e.g. thermocouples), the earth connection must be made with a specific conductor to prevent the connection itself from coming directly through the machine structure.

• if the instrument is used in applications with risk of damage to persons, machinery or materials, it is essential to connect it up to auxiliary alarm equipment. It is advisable to make sure that alarm signals are also triggered during normal operation.

The instrument must NOT be installed in flammable or explosive environments; it may be connected to equipment operating in such atmospheres only by means of appropriate and adequate types of interface, conforming to the applicable safety standards.

Notes Concerning Electrical Safety and Electromagnetic Compatibility:

CE MARKING:

The instrument conforms to the European Directives 2004/108/CE and 2006/95/CE with reference to the generic standards: EN 61000-6-2 (immunity in industrial environment) EN 61000-6-3 (emission in residential environment) **EN 61010-1** (safety).

Series 40B96 interceptor are mainly designed to operate in industrial environments, installed on the switchboards or control panels of productive process machines or plants.

As regards electromagnetic compatibility, the strictest generic standards have been adopted, as indicated in the table below.

EMC conformity has been tested with the following connections.

| Function | Cable type | Length |
|------------------------|------------|--------|
| Power supply cable | 1mm² | 1m |
| Relay output cables | 1mm² | 3.5m |
| Serial connection wire | 0,35mm² | 3.5m |
| Input | 1mm² | 3m |

| EMC Emission | | | | |
|---|---------------------|---|--|--|
| Generic standards, emission standard for residential commercial and light industrial environments | EN 61000-6-3 | | | |
| Emission enclosure | EN 61000-6-3 | Gruppo1 Classe B | | |
| Emission AC mains | EN 61000-6-3 | Gruppo1 Classe B | | |
| Radiated emission | EN 61326 CISPR 16-2 | Classe B | | |
| EMC In | nmunity | | | |
| Generic standards, immunity standard for industrial envi- ronments | EN 61000-6-2 | | | |
| Immunity ESD | EN 61000-4-2 | 4 kV contact discharge level 2 8 kV air discharge level 3 | | |
| Immunity RF interference | EN 61000-4-3 /A1 | 10 V/m amplitude modulated 80 MHz-1 GHz 10 V/m amplitude modulated 1.4 GHz-2 GHz | | |
| Immunity conducted disturbance | EN 61000-4-6 | 10 V/m amplitude modulated 0.15 MHz- 80 MHz (level 3) | | |
| Immunity burst | EN 61000-4-4 | 2 kV power line (level 3) 2 kV I/O signal line (level 4) | | |
| Immunity pulse | EN 61000-4-5 | Power line-line 1 kV (level 2) Power line-earth 2 kV (level 3) Signal line-earth 1 kV (level 2) | | |
| Immunity Magnetic fields | EN 61000-4-8 | 100 A/m (level 5) | | |
| Voltage dips, short interruptions and voltage immunity tests | EN 61000-4-11 | 100%U, 70%U, 40%U, | | |
| LVD | Safety | | | |
| Safety requirements for electrical equipment for measurement, control and laboratory use | EN 61010-1 | | | |



Advice for Correct Installation for EMC

Instrument power supply

- The power supply to the electronic equipment on the switchboards must always come directly from an isolation device with a fuse for the instrument part.
- The electronic instruments and electromechanical power devices such as relays, contactors, solenoid valves, etc., must always be powered by separate lines.
- When the electronic instrument power supply is strongly disturbed by the commutation of transistor or power units or motors, an isolation transformer should be used for the controllers only, earthing the screen.
- It is essential that the plant has a good earth connection:
 - the voltage between neutral and earth must not be <1V
 - the Ohmic resistance must be $<6\Omega$;
- If the mains voltage fluctuates strongly, use a voltage stabilizer.
- In the proximity of high frequency generators or arc welders, use adequate mains filters.
- The power supply lines must be separate from the instrument input and output ones.

Inputs and outputs connection

- The externally connected circuits must be doubly isolated.
- To connect the analogue inputs the following is necessary:
 - physically separate the input cables from those of the power supply, the outputs and the power connections.
 - use woven and screened cables, with the screen earthed in one point only
- To connect the regulating and alarm outputs (contactors, solenoid valves, motors, fans, etc.), fit RC groups (resistance and condensers in series) in parallel to the inductive loads that operate in Alternating Current.

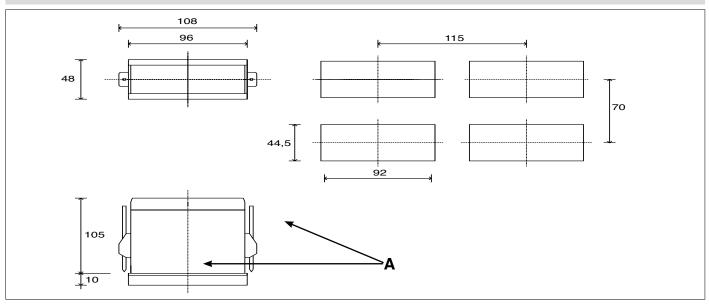
(Note: all the condensers must conform to VDE (class X2) standards and withstand a voltage of at least 220V AC. The resistances must be at least 2W).

 Fit a 1N4007 diode in parallel with the coil of the inductive loads that operate in Direct Current.



GEFRAN S.p.A. declines all responsibility for any damage to persons or property caused by tampering, neglect, improper use or any use which does not conform to the characteristics of the instrument and to the indications given in these Instructions for Use.

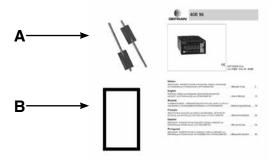
Dimensions and cut-out



Installation with panel mounting

As well as the actual instrument and these instructions for use, the package also contains:

- 2 panel fixing brackets (A)
- 1 protective seal against dust and water spray (B)



Fit the instrument to the panel as shown in the figure.



Warnings and instructions for mounting to the panel



Instructions for installation category II, pollution level 2, double isolation.

- only for low power supply: supply from Class 2 or low voltage limited energy source.
- the power supply lines must be separate from the controller input and output ones
- group the instruments together keeping them separate from the powered part of the relay
- do not install high-power remote switches, contactors, relays, thyristor power units (especially the "phase angle" type), motors, etc. in the same switchboard
- avoid dust, humidity, corrosive gasses and heat sources
- do not block the ventilation holes: the working temperature must be between 0...50°C
- surrounding air: 50°C
- use 60/75°C copper (Cu) conductor only, wire size range 2x No 22 - 14AWG, Solid/Stranded
- · use terminal tightening torque 0.5N m

Nominal ambient conditions

| Altitude | Up to 2000m |
|-------------------|---------------|
| Working/storage | 050°C/-2070°C |
| temperature | |
| Non condensing | 2085% |
| relative humidity | |

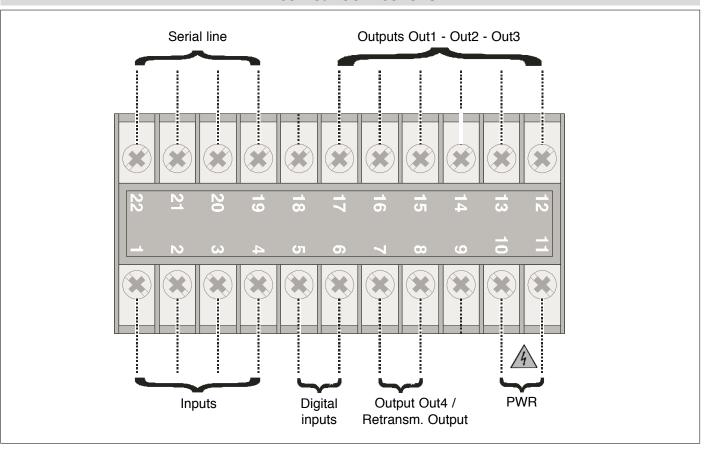


Before supplying the Controller with power, make sure that the mains voltage is the same as that shown in the last number of the order code.

Ex:

$$40B96-5 - xx - xx - xx - x - x - 1 = 100..240$$
Vac/dc
 $40B96-5 - xx - xx - xx - x - x - 0 = 11..27$ Vac/dc

Electrical Connections

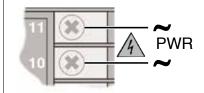




Always make the connections using cable types suitable for the voltage and current limits given in Section 5 - Technical Specifications.

If the instrument has faston terminals these must be protected and isolated. If it has screw terminals, the wires must be attached, at least in pairs

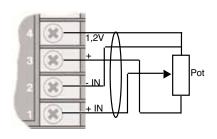
Power Supply



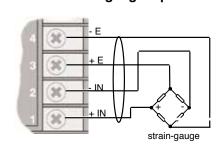
Standard: 100...240Vac/dc ±10% Optional: 11...27Vac7dc ±10% Power: max 8VA; 50/60 Hz

Inputs

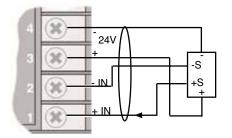
Potentiometer input



4-wires strain gauge input



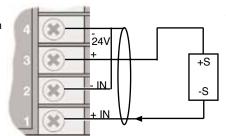
20mA input transmitter only for model 40B96-5-24-...



Terminal 2 (IN -) can be connected to terminal 4 in case of 3-wire transmitter 0-20mA.

Configure probe type: tP=0

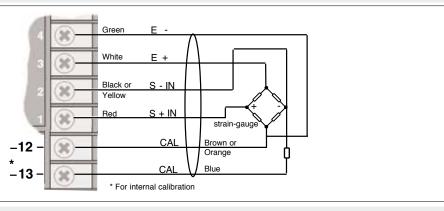
It needs of re-calibration 0-20mA (U.C=2)



4-20mA. 2 wires transmitter input Configure probe type: tP=0

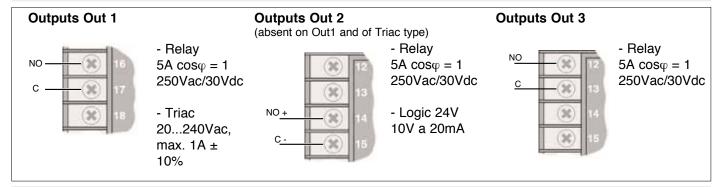
Inputs

Strain gauge input 6 wires to connect to Melt transducers



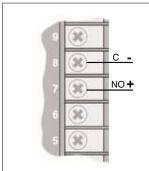
Outputs Out1, Out 2, Out3

User configurable generic outputs



Outputs Out 4 / Retransmission output

User configurable generic outputs

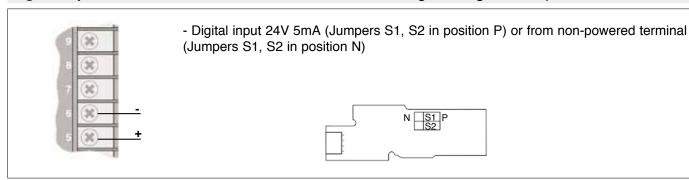


- Relay 5A $\cos \varphi = 1$ 250Vac/30Vdc
- Analogue 0...10V, 0/4...20mA
- 0/2...10V (S1-ON), 0/4...20mA (S1-OFF) S1 is a jumper on the board for continuous or analogic output



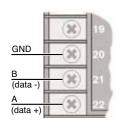
Digital inputs

User configurable generic inputs



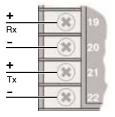
Serial line

Modbus 2 wires (Standard)



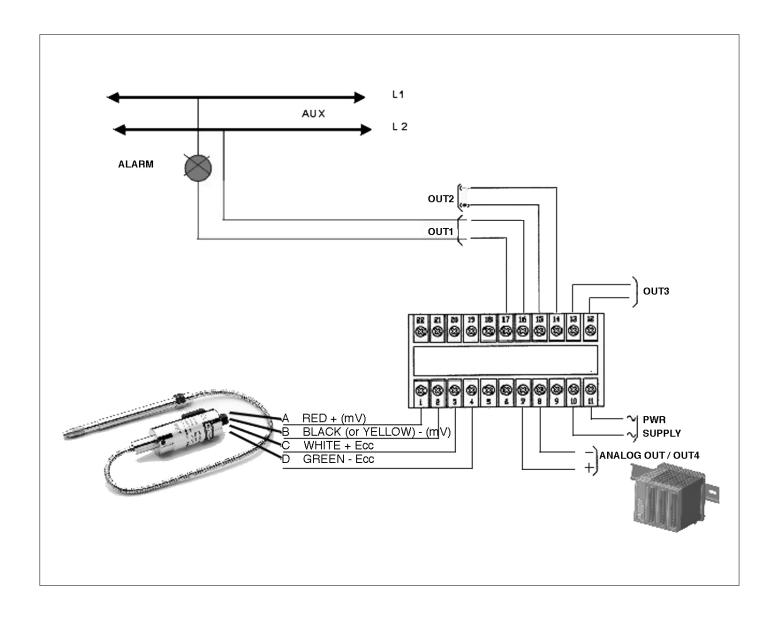
RS485 isolated serial line

Modbus 4 wires / Cencal



RS485 isolated serial line

For Modbus 4 wires/Cencal configuration see technical sheet of the serial board.



FUNCTIONS

This section illustrates the functions and operating modes of the displays, the indicator lights and the buttons that make up the operator interface of series 1200/1300 controllers. It is therefore an essential requirement for programming and configuring the controllers correctly.

Operator Interface

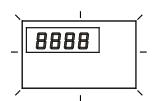


| ID | Symbol | Function |
|----|---------------------|--|
| 0 | 88888 | Shows the process variable, the menu identification, the parameters identification and the error codes |
| 9 | | Increases/Decreases the value of the parameter displayed until the max/min. value is reached. Held down: progressively increases the speed of increasing/decreasing |
| | | the value displayed. |
| | F | Used to move between the various menus and parameters of the instrument. |
| 3 | OUT1 OUT2 OUT3 OUT4 | Output status indicators |
| 4 | bar | Position where to apply the label with united ingegneristica |

General Operating Notes

Switching on and using the intrument

Self-diagnostics



Immediately after switching on the instrument carries out a self-diagnostic test.
 During the test, all the display segments and the 4 indicator lights will flash,
 when finished, enters normal work mode (Level 1) and displays variable value.

Normal Working - Level 1

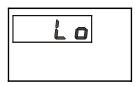
Displays the value of the Process Variable.



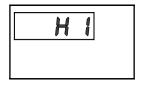
- By pressing briefly it is possible to see in sequence (and if necessary edit)
 the significant values that condition the way the instrument works in Level 1
 (Thresholds of interception)
- Keeping pressed down for 3 seconds we enter the Programming/Configuration menu - see Navigation in the instrument Menus for further details..

Errors while working

In the event of errors during normal working:



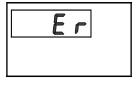
 L_0 process variable < min. scale limit (param. L5 in the I_0)



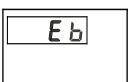
H I process variable > max. scale limit (param. H5 in the In)



br broken probe or input values higher than maximum limits



Er input values lower than minimum limits



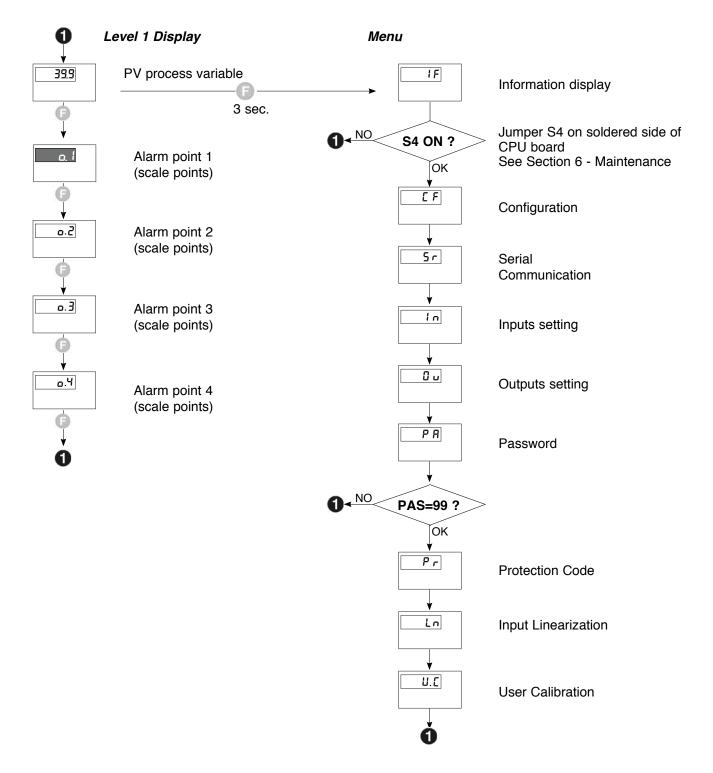
Probe power supply failure (function enabled via parameters (£. t. on In menu)



To solve the problem, refer to the paragraph: Troubleshooting Guide in Section 6 Maintenance

Navigating through the instrument Menu

Keep pressed down to scroll through the menus in sequence and release it when the required menu appears. Press to access the parameters of the selected menu.





If the keys () , () are not pressed within approx. 15 seconds, the display returns to level 1



The parameters and menus not significant for a given configuration are NOT displayed

4 · CONFIGURATION / PROGRAMMING



This section contains the instructions necessary to configure the instrument according to the needs of the application..

Optimal working operation of the 40B96 in the field of application it is intended for depends largely on correct configuration and programming of the relevant control parameters.

The flexibility and high performance level of these instruments is in fact based on the numerous parameters that can be programmed directly by the user with the buttons on the control panel, or transferred from a PC, in the form of configuration files, by means of the RS485 interface available as an option.

Configuration

Access to all the configuration / programming menus and to all the parameters available in configuration, allows every detail of the Controller to be configured, to satisfy all application requirements.



Correct setting of the parameters involved in the configuration presumes a high level of knowledge regarding of use problems and techniques, and so it is recommended that these parameters are not chaness the user is fully aware of the consequences, that ise form incorrect settings.



t is the user's responsibility to check that the parameters are set correctly before putting the instrument into service, in order to avoid damage to persons or property.



For any doubts or clarification needed, please visit the Web Site **www.gefran.com** and if necessary contact the Gefran Customer Care service..

The following pages describe one by one the various menus and show for each parameter the concise description of the function performed, any default values and the range of values that can be set.

Supplementary notes on consulting the Configuration/ Programming pages

To set some particularly complex parameters certain tables or detailed explanatory notes must be referred to.

These tables or explanatory notes are shown directly on the right of the page next to the parameter in question.

Application notes



The detailed explanations of certain functioning modes or special techniques the result Gefran's lengthy experience in the field of temperature control are instead contained at the end of the Configuration/ Programming. Section and can represent a valuable reference tool for the user.

Where necessary, in the configuration / programming flows the appropriate referrals to these Application Notes are provided.

Password: PR

down to access the next menus.

Protection code: Pr

The *Pr* parameter is used to enable or disable the display and/or the possibility of editing certain parameters. For further details refer to the description of the *Pr* parameter in the configuration flows.

Jumper S4 on CPU Board

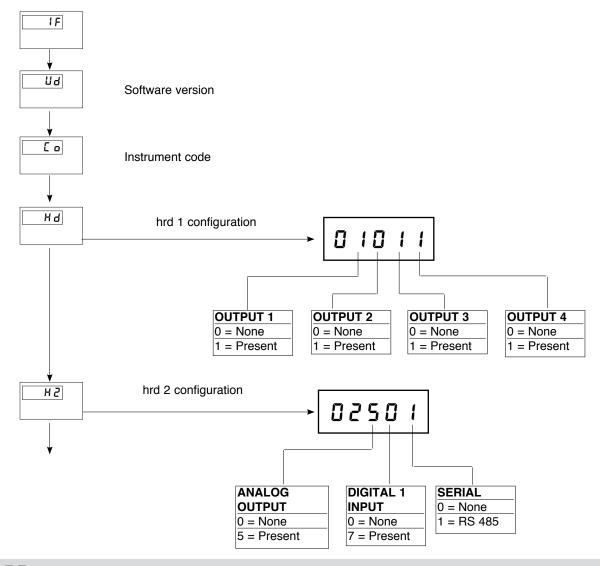
The absence of jumper S4 on the CPU board of the instrument prevents access to all the menus when the hardware configuration of the instrument does not require the pre-set parameters to be changed.

This jumper is engaged or disengaged during production and normally does not need to be modified by the final user. For further information, refer to Section 6 - Maintenance.

F Information display

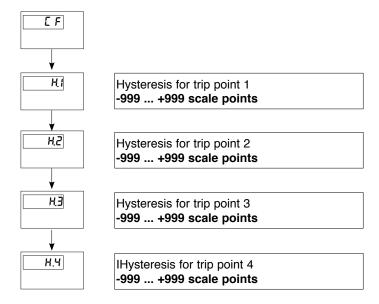
Programming configuration

This menu provides information on the status and hardware configuration of the instrument (number and type of inputs/outputs, software version, etc.).



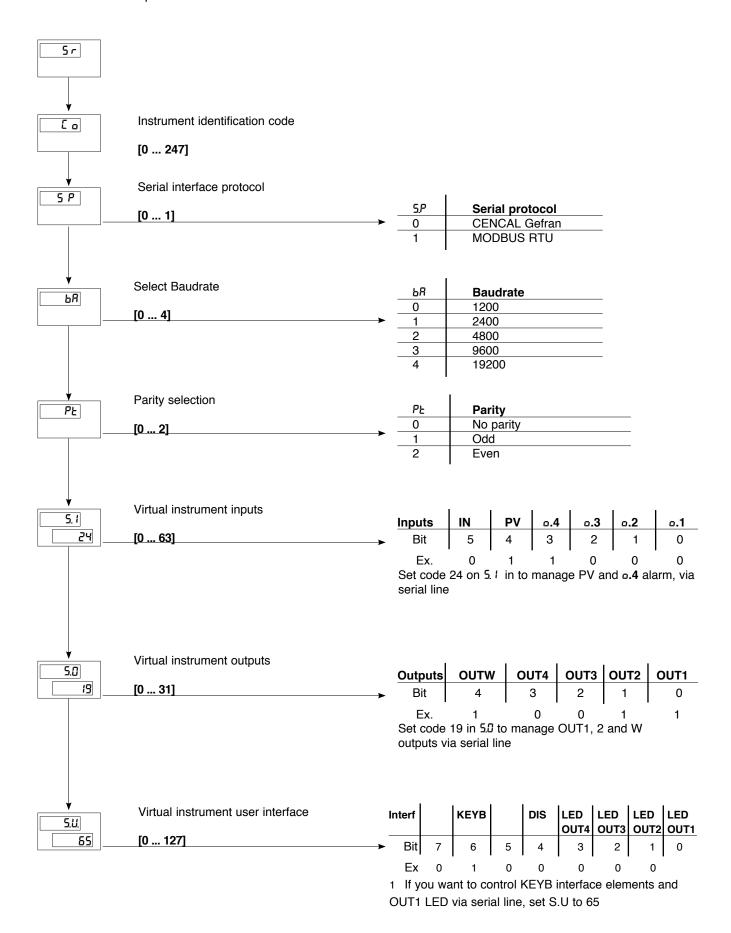
LF Configuration

This menu makes it possible to configure the interception parameters.



5 Serial communication

This menu makes it possible to configure the various parameters that control serial communication between the instrument and the supervisor.



In Input settings

This menu makes it possible to configure the parameters for the instrument input signals.





Probe type, signal and main input scale

| ŁΡ | Probe type | Signal polarization | Main in | puts scale limits | ; |
|----|--------------------|--------------------------|---------------|-------------------|---------------|
| 0 | Potent/4-20mA (*) | Positive (ex. 0/1V) | -1999/9999 | -19990/99990 | -1999/28000 |
| 1 | Potent./4-20mA (*) | Positive (ex. 0/1V) | Linear custom | Linear custom | Linear custom |
| 2 | Strain gauge | Positive (ex. 0/10mV) | -1999/9999 | -19990/99990 | -1999/28000 |
| 3 | Strain gauge | Symmetrical (ex10/+10mV) | -1999/9999 | -19990/99990 | -1999/28000 |

(*) 20mA Inputs: only for model 40B96-5-24-.

in case of input 0-20mA it is necessary to proceed to the calibration to two points 0 and 20mA (U.C = 2)



Select sampling time (resolution)

| | For Strain gauge with Sensor power supply control (Eb) | | Resolution |
|---|--|-------|---|
| 0 | 120ms | 120ms | > 14bit (campionamento Eb 240ms) |
| 1 | 120ms | 60ms | > 14bit; 16000 points (sampling Eb 120msec) |
| 2 | 60ms | 30ms | > 13bit; 8000 points (samplingEb 60msec) |
| 3 | 30ms | 15ms | > 12bit; 4000 points (sampling Eb 30msec) |

- +4 to disable filter (average of the last eight values sampled) Strain gauge only
- +8 disables Eb (sampling time is halved)

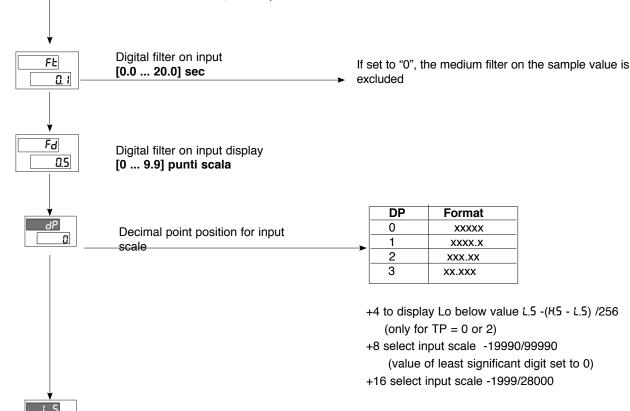
Minimum limit of main input scale

and retransmission analog output

Maximum limit of main input scale

and retransmission analog output

N.B.: maximum sampling frequency and minimum intercept time is obtained with code 15 (15 msec, 11bit resolution, filter off)

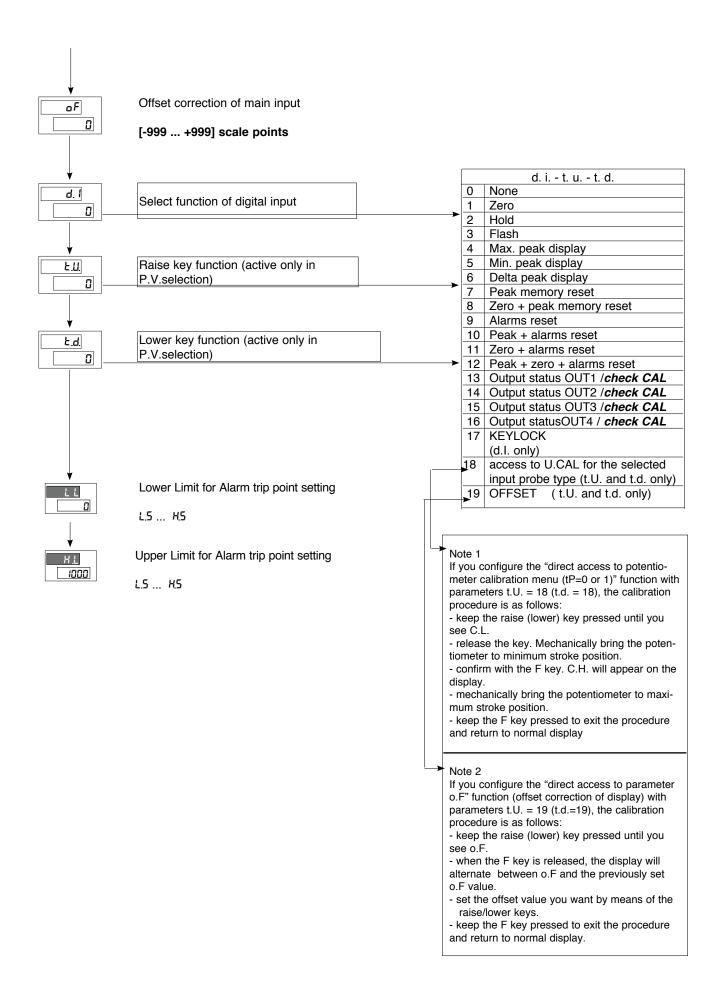


H.5 1000 Min... Max value associated with the input selected with

Min... Max value associated with the input selected with

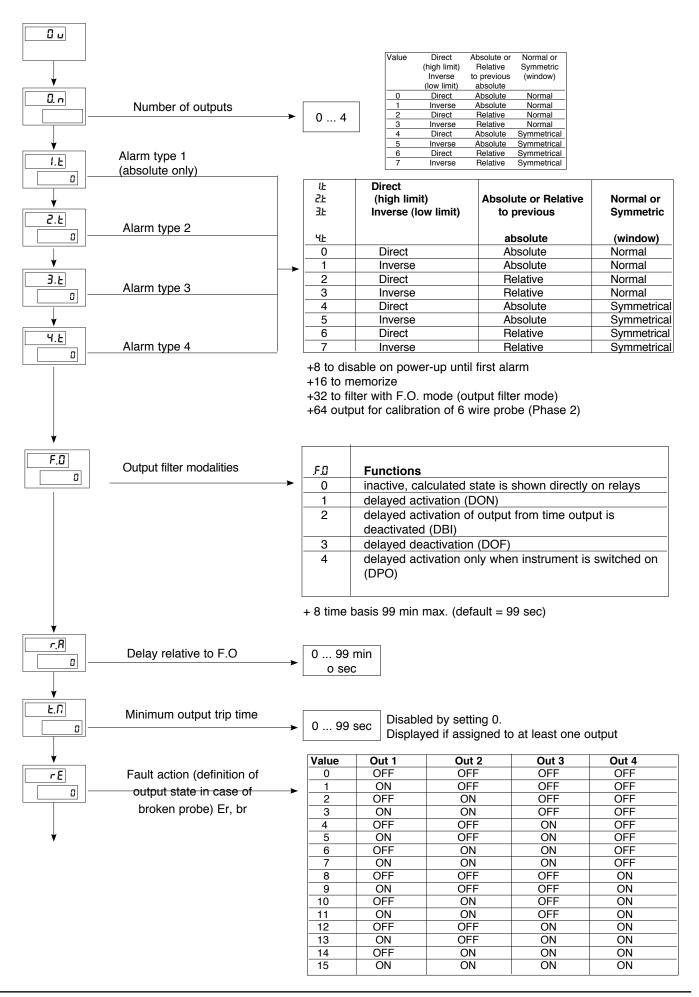
the P parameter

the LP parameter



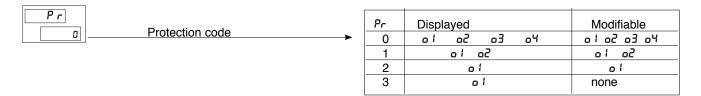
ப் Output settings

This menu makes it possible to configure the parameters of the instrument outputs.



Pr Protection code

This menu makes it possible to enable/disenable the display and/or modification of specific parameters

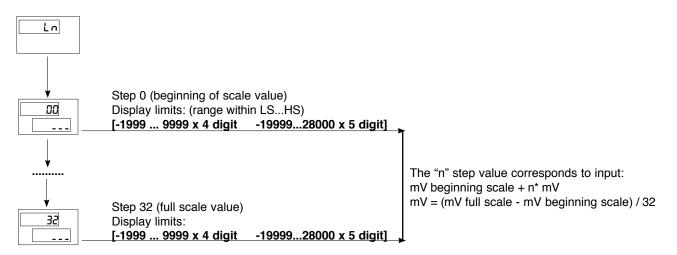


By adding the following figures to the value in the table it is possible to enable a series of supplementary functions:

- +4: to disable In, Du +8: to disable EF, 5r
- +16: to enable maintenance of reset latch at power-off +32: base configuration (the following parameters will not
 - be displayed: In: FE, Fd, oF, L.L, H.L
 - Du: Dn [forced to no. outputs present], rE
 - FŁ, Fd, oF remain at set value L.L, H.L are forced to L.5, H.5
- +64: Virtual instrument.
- +128: All pages access disabled, except PA (Password)

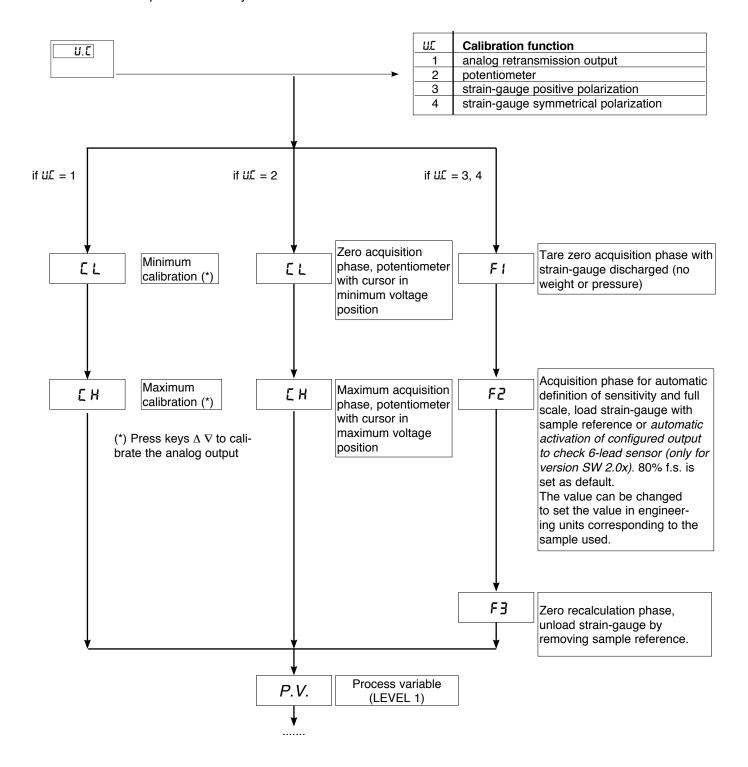
Ln Input linearization

This menu makes it possible to carry out custom linearization for the main input. Only if EP = Linear Custom



ป.E User calibration

This menu makes it possible to carry out user calibration.



Note: between the calibration phases some seconds could be requested to elaborate data.

Application Notes

Eb Function

The standard device is produced with parameter C.I.= 8,

with sampling time of 120 msec and Eb function disabled.

The Eb function lets you detect if the probe power supply is interrupted. This function is valid for probe currents > 20mA (8mA in version 2.0x)

Example:

- probe voltage 10V
- strain-gauge resistance 350Ω

- current =
$$\frac{V}{R} = \frac{10}{28mA}$$

or for three probes connected in parallel

- probe voltage 10V
- strain-gauge resistance 350Ω

HOLD function

The input value and alarms are frozen while the logic input is active.

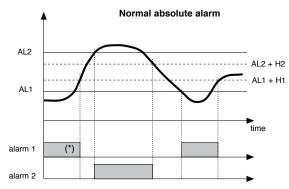
With the logic input active, a reset turns OFF both the relay outputs and the alarms latch.

FLASH function

Input value is sampled; state of alarms is not transferred to outputs; outputs are "frozen".

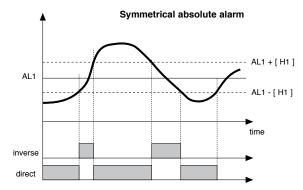
When the logic input is active the input value is "frozen" and the outputs are updated according to the calculated alarms state, including the ones latched.

Alarms (Interceptions)

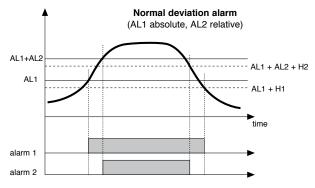


For AL1 inverse absolute alarm (min.) with positive H1, 1 t = 1 (*) = OFF if disabling on power-on exists

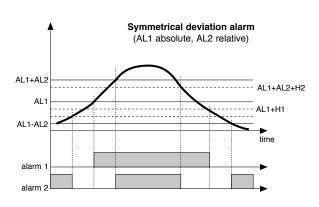
For AL2 direct absolute alarm (max) with negative H2, 2 t = 0



For AL1 inverse absolute, symmetrical alarm with hysteresis H1, 1 t = 5 For AL1 direct absolute, symmetrical alarm with hysteresis H1, 1 t = 4



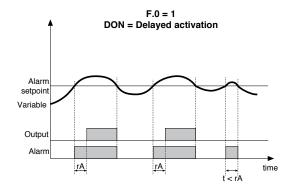
For AL1 direct absolute alarm (max) with negative H 1, 1 t = 0 For AL2 direct relative alarm (max) with negative H2, 2 t = 2

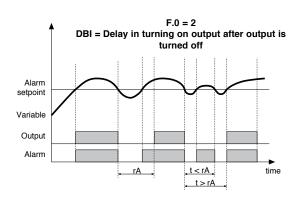


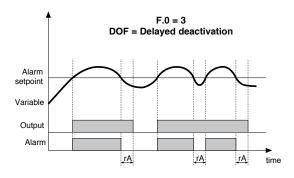
For AL1 direct absolute alarm (max) with negative H1, 1 t = 0 For AL2 symmetrical deviation alarm H2, 2 t = 6

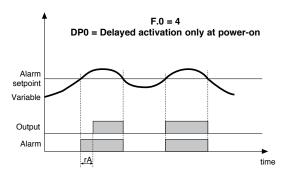
Filter - outputs with reference to parameters F.0 and r.A

The diagrams refer to a normal absolute alarm with hysteresis H = 0









UCAL: strain-gauge calibration

a) Positive signal polarization

Suppose we test a probe (load cell) with sensitivity of 2mV/V, powered at 10V.

The input signal range is 0 to 20mV. From unloaded to loaded cell you should see a value from 0 to 1000.

Set scale limits: L.S. = 0; H.S. = 1000. Calibration procedure: U.C. = 3.

Phase F1: unload the cell (equal to applying input voltage of 0mV). Wait 2 seconds for the signal to stabilize. Press key F.

Phase F2: load the cell with a sample weight: for example, 80% of total weight (equal to applying input voltage of 80% of 20mV (2mV*10V) = 16mV). On display, set a value equal to 80% of H.S. = 800.

Press key F.

Phase F3: unload the cell (equal to applying input voltage of 0mV). Wait 2 seconds for the signal to stabilize. Press key F (calibration finished).

b) Suppose we test a probe (force sensor) with sensitivity of 2mV/V, powered at 10V.

The input signal range is -20mV to 20mV. From maximum compression to maximum traction you should see a value from -1000 to 1000. Set scale limits: L.S. = -1000; H.S. = 1000.

Calibration procedure: U.C. = 4.

Phase F1: do not apply any traction or compression to the sensor (equal to applying input voltage of 0mV).

Wait 2 seconds for the signal to stabilize. Press key F.

Phase F2: apply compression equal to 80% of total compression

(equal to applying input voltage of 80% of 20mV (2mV*10V) = 16mV). On display, set a value equal to 80% of H.S. = 800. Press key F.

Phase F3: do not apply any traction or compression to the sensor (equal to applying input voltage of 0mV).

Wait 2 seconds for the signal to stabilize. Press key F (calibration finished).

Virtual Instrument

Management of the virtual instrument via serial is activated with the Pr parameter.

By setting the S.I, S.o and S.U parameters, you can enable writing of a few variables from the serial line to set input values, output state, LED state, and the value shown on displays.

You have to enable alarm limits when the write operations are continuous and you don't have to keep the last value in EPROM (applications requiring continuous variations of interceptions).

Enabling the PV input lets you exclude local acquisition of the input, replacing it with the value written in the VALUE_F register.

Enabling digital input lets you set the state of this input, for example, to perform the zero setting with writing of the appropriate bit in the V IN OUT register.

In analog mode, you can set the ON/OFF state of outputs OUT1, ..., OUT4 by writing the bit in the V_IN_OUT register; the value of analog output OUTW in the VALUE_W register; the state of LEDs OUT1,..., OUT4 by means of the bits in the V X LEDS register.

* To use the Display resources for setting a value on the display and Keyboard to simulate key pressure, you also have to set bit 7 of the STATUS6_W register (Modbus address 345 / Cencal 690). This bit is reset at every power-up.

The following table shows the register addresses:

| Parameter | bit | Resource enabled | Image register address | | Format | Register name |
|-----------|-----|--------------------------|------------------------|--------|-------------|----------------|
| | | | Modbus | Cencal | | |
| S.I | 0 | Alarm limit o.1 | 341 | 682 | word | Interception 1 |
| | 1 | Alarm limit o.2 | 342 | 684 | word | Interception 2 |
| | 2 | Alarm limit o.3 | 343 | 686 | word | Interception 3 |
| | 3 | Alarm limit o.4 | 302 | 604 | word | Interception 4 |
| | 4 | PV input | 347 | 694 | word | VALUE_F |
| | 5 | IN digital input | 344 | 688 | word, bit 4 | V_IN_OUT |
| S.o | 0 | Output OUT1 | 344 | 688 | word, bit 0 | V IN OUT |
| | 1 | Output OUT2 | 344 | 688 | word, bit 1 | V_IN_OUT |
| | 2 | Output OUT3 | 344 | 688 | word, bit 2 | V_IN_OUT |
| | 3 | Output OUT4 | 344 | 688 | word, bit 3 | V_IN_OUT |
| | 4 | Output OUTW | 307 | 614 | word | VALUE_W |
| S.U | 0 | Led OUT1 | 351 | 702 | word, bit 0 | V X LEDS |
| | 1 | Led OUT2 | 351 | 702 | word, bit 1 | V_X_LEDS |
| | 2 | Led OUT3 | 351 | 702 | word, bit 2 | V_X_LEDS |
| | 3 | Led OUT4 | 351 | 702 | word, bit 3 | V_X_LEDS |
| | 4 | * Display high thousands | 321 | 642 | word | ADD1 |
| | 4 | * Display high hundreds | 322 | 644 | word | ADD2 |
| | 4 | * Display high tens | 323 | 646 | word | ADD3 |
| | 4 | * Display high units | 324 | 648 | word | ADD4 |
| | 4 | * Display high tens of | | | | |
| | | thousands | 325 | 650 | word | ADD5 |
| | 6 | * Keyboard F key | 320 | 640 | word, bit 0 | NEW_TAST |
| | 6 | * Keyboard DOWN key | 320 | 640 | word, bit 1 | NEW_TAST |
| | 6 | * Keyboard UP key | 320 | 640 | word, bit 3 | NEW_TAST |

5 · TECHNICAL SPECIFICATIONS



This section contains a list of the Technical Specifications for the 40B96 instrument.

| Display | 5 red digits, digit height 14mm (5 digits) |
|-------------------------------------|---|
| Keys | 3 mechanical type (NC, DEC, F) |
| Accuracy | 0.2% f.s. ±1 digit a temperatura ambiente di 25°C t.s. 120msec |
| Thermal drift | 0,005% f.s. / °C |
| Resolution | function of settable sampling time: |
| | >14bit, t.s. 120msec with sensor power control if strain gauge |
| | >13bit, t.s. 30msec (60msec with strain gauge power control) |
| | >12bit, t.s. 15msec (30msec with strain gauge power control) |
| Main input | differential input for |
| · | - from strain-gauge 350Ω (for pressure, force, etc.) sensitivity |
| | 5mV/V with strain-gauge power max 15V, (7.5mV/V con power |
| | supply max. 10V-15mV/V with power supply max 5V), positive or |
| | symmetrical polarization, calibration with automatic calibration of |
| | sensitivity, possible signaling of interrupted sensor power supply |
| | - from potentiometer with power supply $1.2V_{,\geq} 100\Omega$ |
| | - 020/420mA transmitter with 24Vdc supply (Ri = 50Ω) |
| Linear scale range | -19999999 (with 4 digits),-199928000 (with 5 digits) settable |
| | decimal point; a 32 section linearization can be inserted |
| Alarms (interception) | max 4 configurable alarm types: absolute, deviation, symmetrical deviation. |
| | Hysteresis setting |
| Alarm masking | options: |
| | - exclusion at switch-on |
| | - latch, reset from key and/or contact |
| | - insertion of delay filter (DON,DBI,DOF,DPO) |
| | - activation of minimum time on trip |
| Relay contact | NO (NC), 5A, 250V/30Vdc cosφ=1 |
| Logic output | 24V ±10% (10V min / 20mA) |
| Triac output | 20240Vac ±10%, 1A max, snubberless, inductive and resistive |
| load | I²t = 128A |
| Fault settings | Alarm states can be configured in probe fault condition |
| Sensor power | 1,2Vdc for potentiometer > 100Ω |
| | 5Vdc, 10Vdc, max 120mA (for strain-gauge) |
| | 15Vdc, 50mA max. |
| | 24Vdc ± 10% non stabilized 50mA, (100mA max for the |
| | 020/420mA transmitter input model only) |
| Analogue retransmission | 10V/20mA Rload max 500Ω resolution 12 bit |
| Digital inputs | Ri = 4,7K Ω (24V, 5mA) or from terminal not supplied. |
| Serial interface (option) | RS485, isolated |
| Baudrate | 1200, 2400, 4800, 9600, 19200 |
| Protocol | Gefran CENCAL / MODBUS |
| Power supply (switching type) | (standard) 100240Vac/dc ±10% max 18VA |
| | (optional) 1127Vac/dc ±10% max 11VA |
| | 50/60Hz |
| Faceplate protection | IP65 |
| Working / Storage temperature range | 050°C / -2070°C |
| Relative humidity | 2085% Ur non-condensing |
| Environmental working conditions | for indoor use, altitudes up to 2000m |
| Installation | panel, removable faceplate |
| Installation specifications | installation category II, pollution level 2, double isolation |
| Weight | 160 g complete version |



This section gives the information and the necessary warnings for routine maintenance of the instrument and contains a Troubleshooting Guide which should before seeking help from the Gefran Customer Assistance, in the event of instrument malfunction.

If installed and configured correctly according to the instructions and the recommendations provided in Sections 2 and 4 of these Instructions for use, the instrument will work normally without any need for maintenance, apart from the usual operations of cleaning the faceplate, and if necessary the internal parts of the instrument.

To gain access to the inside of the instrument (for exam-



ple for cleaning or to check the jumpers) just undo the screw at the bottom of the faceplate and take out the instrument without having to disconnect the cables.

Make sure that the power is turned off upstream of the instrument however.

Remember that the 40B96 interceptor is not equipped with an ON/OFF switch.

Cleaning the Instrument

To clean the faceplate and the case use only a cloth dampened in water or ethyl alcohol.



Do not use hydrocarbon-based solvents (trichiorethylene, petrol, etc.).

Do not use compressed air to remove dust from the electronic circuit boards, if necessary use a clean brush with soft bristles.

Repairs

Repairs to the 40B96 instrument must only be carried out by qualified technicians, properly trained and authorized by Gefran. Any attempts at repair or modification of the instrument hardware

characteristics by unauthorized personnel will invalidate the warrantya.

Checking the jumpers

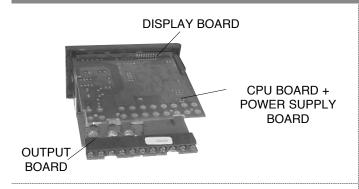
The solders side of the CPU board contains the jumper S4 which enables (if on) access to the controller menus.

The instrument contains components which are sensiti-



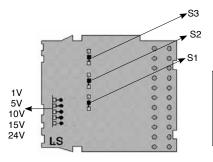
ve to electrostatic discharge, so the vant precautions must be taken when handling the electronic circuit boards contained in it, in order to avoid permanent damage to components themselves.

Device structure: identification of boards

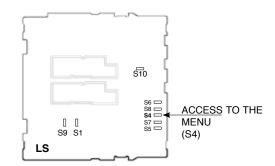


OUTPUT BOARD

Power supply selection Sensor or Transmitter



CPU BOARD + POWER SUPPLY BOARD



Jumper S4 is normally closed. To change its state, the connection has to be removed. This operation must be done by trained technical personnel.

| | Jumper | Direct | | Inver | se |
|------|--------|--------|-----|-------|----|
| | | Α | В | Α | В |
| OUT1 | S1 | ON | OFF | OFF | ON |
| OUT2 | S2 | ON | OFF | OFF | ON |
| OUT3 | S3 | ON | OFF | OFF | ON |

You can select output state to have direct or reverse mode.

Jumper S1, S2 and S3 are normally closed in position A. To change their state, the connection has to be removed. This operation must be done by trained technical personnel.

Example in case of relay output:

- Direct mode: energized relay and related closed contact correspond to active trip point.
- Reverse mode: de-energized relay and related open contact correspond to active trip point.

Troubleshooting Guide

| Symptom | Cause and Recommended remedy |
|-------------------------------------|---|
| The instrument display and | Instrument power supply problem. Check that power is being supplied to terminals 10-11. |
| Led do not come on | make sure the power supply corresponds with the one stated in the order code: |
| | 40B965xx - xx - xx - x - 1 = 100240Vac/dc |
| | 40B96 5 xx - xx - xx - xx - 0 = 1127 Vac/dc |
| The characters shown on the | Possible fault with one of the display segments. Check that all the segments are working pro- |
| display are incomplete or | perly by switching the instrument off and then on again. When it is switched on again a self- |
| illegible | diagnostic test is performed that checks intermittent start up of all the segments (displays the value 8888). If one or more segments do not light up contact your Gefran dealer. |
| When pressing down none | If the problem appears during the first installation, it probably means that the hardwa- |
| of the configuration menus can | re configuration doesn't allow changing of the default parameters beyond the alarm |
| be accessed | setpoint value. (Parameter change is enabled by jumper S4 on the CPU board). If on the other |
| | hand the problem occurs on a instrument that previously gave access to the configuration |
| | parameters, this probably means that there is a false contact on the jumper S4. |
| | In this case check the continuity of the jumper referring to the previous paragraph. |
| When pressing down | Access to some menus and/or parameters is protected by a password (PA) and a code (PR) that limits configuration mode. |
| configuration menus can be accessed | To set the password and the protection code correctly refer to Section 4 "Configuration/ Programming". |
| Instead of the process variable | In the first four cases it means that an input error has been found (for details refer to Section |
| the PV display shows one of | 3 - Functions). |
| the following: | In the last case, it means probe power supply failure. |
| Lo - HI - br - Er - Eb | This function has to be enabled via parameter c.l. on the In menu. |

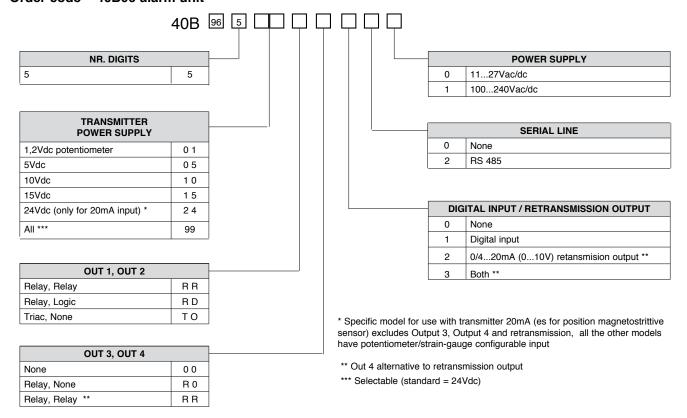
7 · TECHNICAL/COMMERCIAL INFORMATION

B.

This section contains information regarding the instrument order codes and the main accessories available.

As stated in the Preliminary Warnings of these Instructions for Use, correct interpretation of the instrument order code allows the hardware configuration to be identified immediately and so it is essential to quote the order code each time the Gefran Customer Care Service is contacted for assistance with any problems.

Order code - 40B96 alarm unit





For information on the availability of codes please contact your Gefran dealer.

ACCESSORIES

• RS232 / TTL interface for GEFRAN instrument configuration

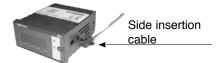


N.B. RS232 interface for PC configuration is supplied with the WINSTRUM programming software. Make connection with instrument powered but with inputs and outputs disconnected.

ORDER CODE

WSK-0-0-0

Cable interface + CD Winstrum



APPENDIX



The appendix contains the list of all the abbreviations of parameters which appear in the various configuration/programming menus with the respective default values and meanings.

The CONF column can be used to indicate the user's modified values with respect to the default configuration, on the basis of application requirements.

| Display | Default | CONF | Acronym | Description | | | | | | |
|---------|---------|------|-------------------|--|--|--|--|--|--|--|
| Level 1 | | | | | | | | | | |
| o. 1 | 40 | | Output 1 | Setting of alarm setpoint (Scale points) | | | | | | |
| 0.2 | 50 | | Output 2 | Setting of alarm setpoint (Scale points | | | | | | |
| 0.3 | 60 | | Output 3 | Setting of alarm setpoint (Scale points) | | | | | | |
| ۵.۲ | 70 | | Output 4 | Setting of alarm setpoint (Scale points) | | | | | | |
| Menu # | | | | | | | | | | |
| Ud | 3.20 | | UPdate | Software version identification | | | | | | |
| L٥ | 1 | | Code | Instrument code identification | | | | | | |
| На | | | Conf Hardware 1 | Hardware outputs configuration | | | | | | |
| H2 | | | Conf Hardware 2 | Hardware inputs configuration | | | | | | |
| Menu [F | | | | | | | | | | |
| H, I | -1 | | HYsteresis 1 | Hysteresis for setpoint 1 | | | | | | |
| H.2 | -1 | | HYsteresis 2 | Hysteresis for setpoint 2 | | | | | | |
| Н.3 | -1 | | HYsteresis 3 | Hysteresis for setpoint 3 | | | | | | |
| нч | -1 | | HYsteresis 4 | Hysteresis for setpoint 4 | | | | | | |
| Menu 5r | | | | | | | | | | |
| Co | 1 | | Instrument Code | Instrument identification code | | | | | | |
| S.P | 1 | | Serial Protocol | Serial interface protocol | | | | | | |
| ЬЯ | 4 | | bAudrate | Baudrate selection | | | | | | |
| PŁ | 0 | | PArity | Parity selection | | | | | | |
| 5. (| 0 | | S. Input | Virtual instrument inputs | | | | | | |
| 5.0 | 0 | | S. Output | Virtual instrument outputs | | | | | | |
| 5.U | 0 | | S. User Interface | Virtual instrument user interface | | | | | | |
| Menu In | | | | | | | | | | |
| ŁP | 0 | | type of Probe | Probe type, signal, enable linearization, etc. | | | | | | |
| [] | 0 | | Sample time | Select sampling time | | | | | | |
| FŁ | 0.1 | | FiLter time | Digital filter on input | | | | | | |
| Fd | 0.5 | | FiLter display | Digital filter on display | | | | | | |
| d₽. | 0 | | Decimal point | Decimal point position for input scale | | | | | | |
| L.5 | 0 | | Low Scale | Minimum limit input scale | | | | | | |
| H.5 | 1000 | | High Scale | Maximum limit input scale | | | | | | |
| oF | 0 | | oFfSet | Offset correction of main input | | | | | | |
| d. l | 0 | | Digital input | Digital input function | | | | | | |
| ŁU | 0 | | UP key | Raise key function | | | | | | |
| Ł.d | 0 | | DOWN key | Lower key function | | | | | | |
| L.L | 0 | | Low Limit | Lower limit for setting SP and absolute alarms | | | | | | |
| HL | 1000 | | High Limit | Upper limit for setting SP and absolute alarms | | | | | | |

| Display | Default | CONF | Acronym | Description | | | | | | |
|--|---------|------|---------------|--|--|--|--|--|--|--|
| Menu 🗓 🛭 | | | | | | | | | | |
| On | 0 | | Output number | Number of trip point outputs | | | | | | |
| IE. | 0 | | Output type 1 | Trip point type for Out 1 | | | | | | |
| 2£ | 0 | | Output type 2 | Trip point type for Out 2 | | | | | | |
| 3E | 0 | | Output type 3 | Trip point type for Out 3 | | | | | | |
| ЧĿ | 0 | | Output type 4 | Trip point type for Out 4 | | | | | | |
| FO | 0 | | Output filter | Filter mode on trip points | | | | | | |
| rЯ | 0 | | Output delay | Trip point delay | | | | | | |
| Ł۲ | 0 | | Minimum type | Minimum output trip point time | | | | | | |
| гE | 0 | | Fault action | Definition of output states with broken sensor | | | | | | |
| Manu ! a - Input linearization 00 - 22 | | | | | | | | | | |

Menu Ln - Input linearization 00 – 32

| _N° | Default | CONF | N° | Default | CONF | _N° | Default | CONF | N° | Default | CONF | N° | Default | CONF |
|-----|---------|------|-----|---------|------|-----|---------|------|-----|---------|------|-----|---------|------|
| .00 | 0 | | .07 | 219 | | .14 | 437 | | .21 | 656 | | .28 | 875 | |
| .01 | 31 | | .08 | 250 | | .15 | 469 | | .22 | 687 | | .29 | 906 | |
| .02 | 62 | | .09 | 281 | | .16 | 500 | | .23 | 719 | | .30 | 937 | |
| .03 | 94 | | .10 | 312 | | .17 | 531 | | .24 | 750 | | .31 | 969 | |
| .04 | 125 | | .11 | 344 | | .18 | 562 | | .25 | 781 | | .32 | 1000 | |
| .05 | 156 | | .12 | 375 | | .19 | 594 | | .26 | 812 | | | | |
| .06 | 187 | | .13 | 406 | | .20 | 625 | | .27 | 844 | | | | |