GEFRAN

GFW adv
ADVANCED MODULAR POWER CONTROLLER

CONFIGURATION AND PROGRAMMING MANUAL

Software version: **2.0x**

CE

code: **80963B - 11-2012 - ENG**

This document supplements the following manuals:
- Instructions and warnings for GFW

ATTENTION!

This manual is an integral part of the product, and must always be available to operators.

This manual must always accompany the product, including if it is transferred to another user.

Installation and/or maintenance workers MUST read this manual and scrupulously follow all of the instructions in it and in its attachments. **GEFRAN** will not be liable for damage to persons and/or property, or to the product itself, if the following terms and conditions are disregarded.

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INTRODUCTION

The modular power controller described in this manual and shown on the cover is a separate unit for the independent control of a maximum of 3 zones. It offers high applicative flexibility thanks to the extended configurability and programmability of its parameters.

Instrument configuration and programming must be performed with a GFW-OP or a PC connected in USB/RS232/RS485, with specific GF_eXpress application software.

Since it is impossible to foresee all of the installations and environments in which the instrument may be applied, adequate technical preparation and complete knowledge of the instrument's potentials are necessary.

GEFRAN declines all liability if rules for correct installation, configuration, and/or programming are disregarded, as well as all liability for systems upline and/or downline of the instrument.

FIELD OF USE

The modular power controller is the ideal solution for applications in heat treatment furnaces, in thermoformers, in packaging and packing machines and, in general, in standard temperature control applications. Nevertheless, because it is highly programmable, the controller can also be used for other applications provided they are compatible with the instrument's technical data.

Although the instrument's flexibility allows it to be used in a variety of applications, the ***field of use*** must always conform to the limits specified in the technical data supplied.

GEFRAN declines all liability for damage of any type deriving from installations, configurations, or programmings that are inappropriate, imprudent, or not conforming to the technical data supplied.

Prohibited use

It is absolutely prohibited:
- to utilize the instrument or parts of it (including software) for any use not conforming to that specified in the technical documentation supplied;
- to modify working parameters inaccessible to the operator, decrypt or transfer all or part of the software;
- to utilize the instrument in explosive atmospheres;
- to repair or convert the instrument using non-original replacement parts;
- to utilize the instrument or parts of it without having read and correctly understood the technical documentation supplied;
- to scrap or dispose of the instrument in normal dumps; components that are potentially harmful to the environment must be disposed of in conformity to the regulations of the country of installation.

CHARACTERISTICS OF PERSONNEL

All *personnel operating*, installing, or doing maintenance on the instrument must be expert, trained, aware and mature, able to reliably and correctly interpret this manual.

This manual CANNOT make up for cultural or intellectual insufficiencies. Therefore, all personnel interacting with the instrument must:
- have adequate education, training, and skills;
- be completely aware of what he/she is doing;
- NOT act in an intentionally self-destructive manner.

All personnel must always use proper methods, instruments, and protective devices to work under safe conditions.

It is forbidden to employ untrained personnel, persons with disabilities, legally disqualified persons, persons who are not sober, or persons who take drugs.

STRUCTURE OF THIS MANUAL

This manual was originally written in ITALIAN. Therefore, in case of inconsistencies or doubts, request the original manual or explanations from GEFRAN.

The instructions in this manual do not replace the safety instructions and the technical data for installation, configuration and programming applied directly to the product or the rules of common sense and safety regulations in effect in the country of installation.

For easier understanding of the controller's basic functions and its full potentials, the configuration and programming parameters are grouped according to function and are described in separate **chapters**.

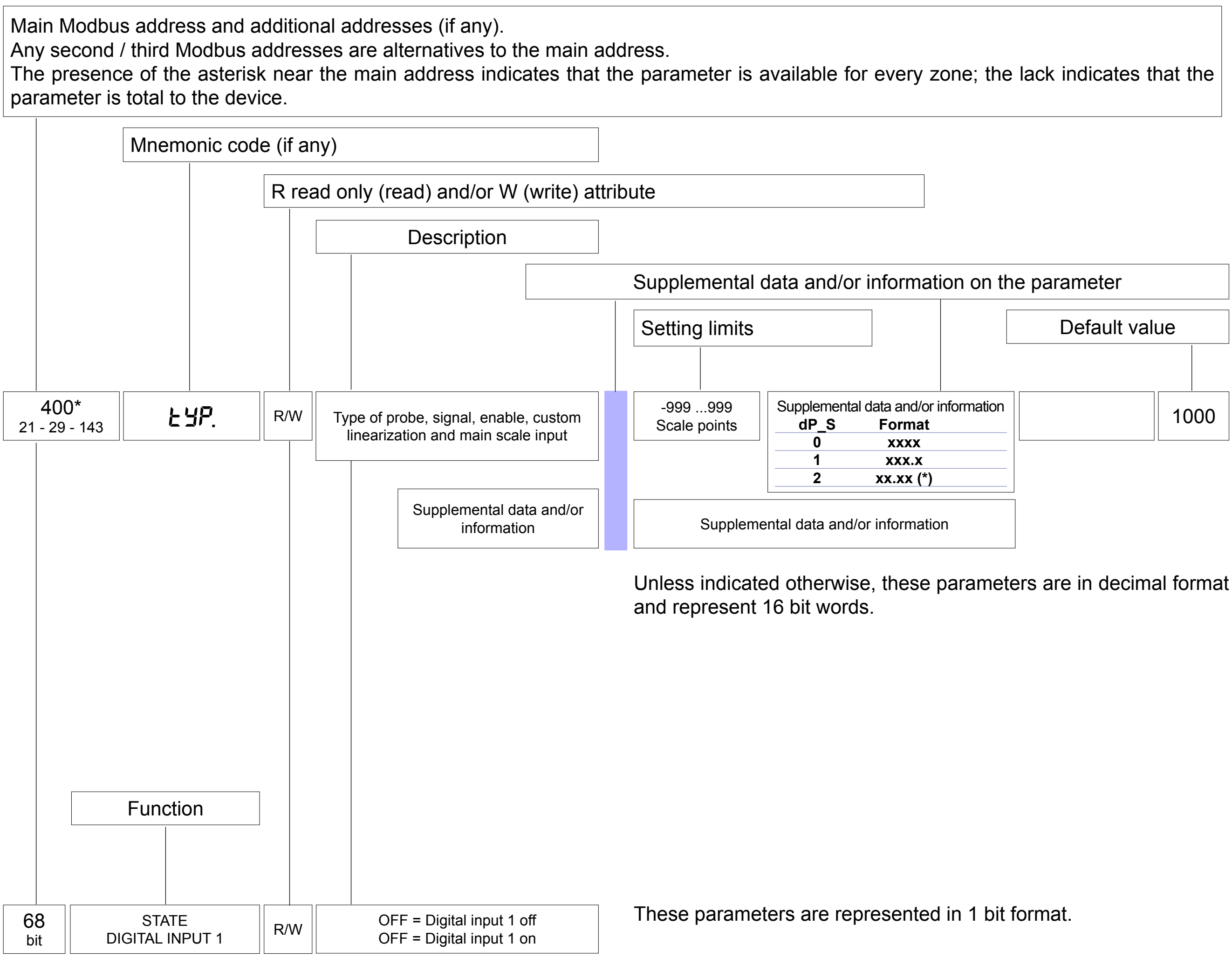
Each **chapter** has from 1 to 3 sections:

- the first section presents a general description of the parameters described in detail in the following zones;
- the second section presents the parameters needed for the controller's **basic applications**, which users and/or installers can access clearly and easily, immediately finding the parameters necessary for quick use of the controller;
- the third section (ADVANCED SETTINGS) presents parameters for advanced use of the controller: this section is addressed to users and/or installers who want to use the controller in special applications or in applications requiring the high performance offered by the instrument.

Some sections may contain a functional diagram showing interaction among the parameters described;

- terms used on other pages of the manual (related or supplemental topics) are shown in underlined italics and listed in the index (linked to IT support).

In each section, the programming parameters are shown as follows:



INSTRUMENT ARCHITECTURE

The modular power controller's flexibility permits replacement of previous-version such as GEFLEX (GFX), GFX4 and GFX4-IR instruments without changing the control software in use.
Based on the chosen work mode (see MODBUS SERIAL COMMUNICATION), you can use the instrument in 2 different modes:

- GFX compatible mode: as if there were at most 3 separate instruments (recommended for retrofitting projects and/or replacement of damaged instruments);

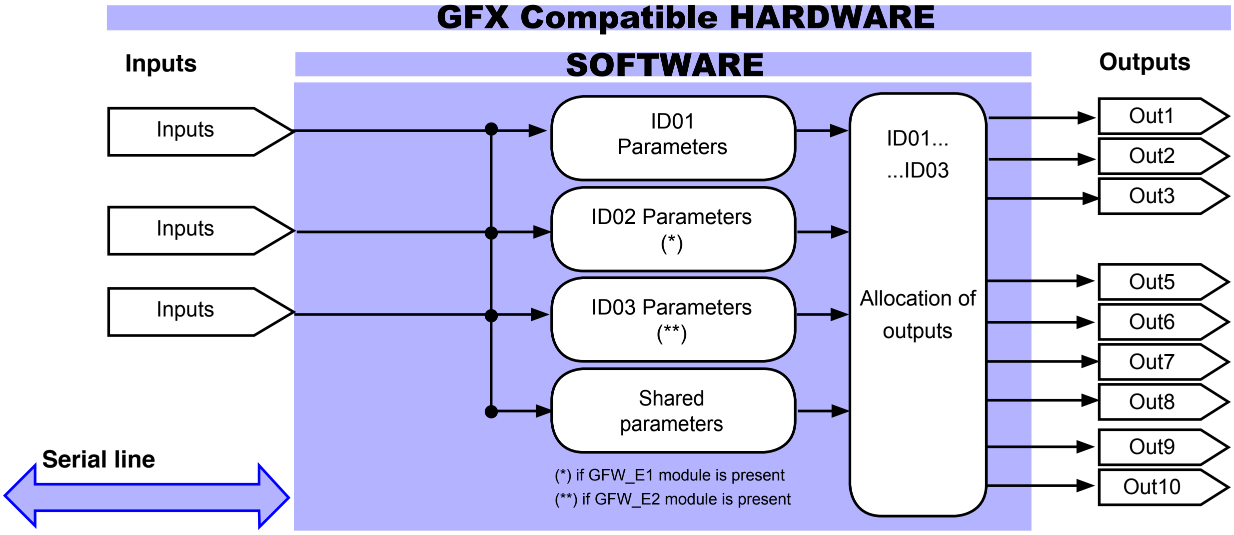
- GFX4/GFW mode: as a single instrument with the same functions as at most 3 separate instruments, but with possibility of interaction among the various parameters, inputs and outputs (recommended for new projects).

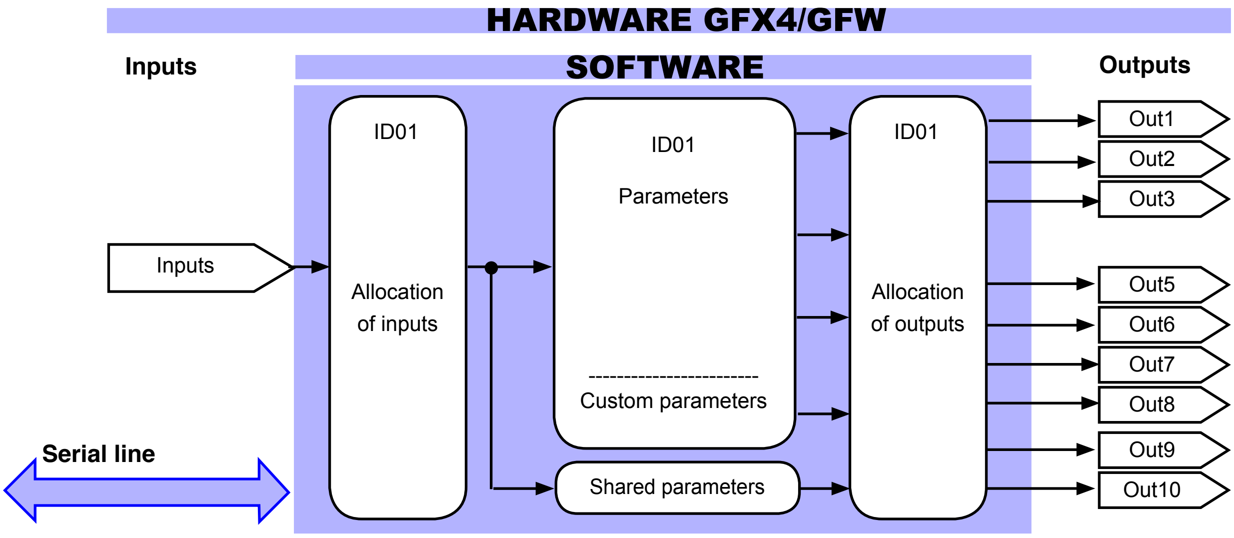
New shared parameters, are accessible for both modes and permit more advanced functions such as:

604	FLt.2	R/W	**Digital filter for auxiliary input**		0.0 ... 20.0 sec		0.1

In addition to having a CUSTOM group of parameters for dynamic addressing, GFX4/GFW mode lets you use a single communication network node instead of 3 nodes as in GFX compatible mode.

When programming, keep in mind that some of the addresses (parameters) described in this manual exist at most 3 times, specified by address node (ID).





SERIAL COMMUNICATION (MODBUS)

There are two Modbus addressing modes for variables and configuration parameters:
- GFX compatible
- GFX4/GFW

The modes are selected with dip-switch-7.

GFX-compatible mode (dip-switch-7 =ON)

This lets you uses supervision programs created for Geflex modules.
Memory is organized in at most 3 groups:
- Zone 1 for the variables of the module GFW-M
- Zone 2 for the variables of the module GFW-E1
- Zone 3 for the variables of the module GFW-E2

In each zone, the variables and parameters have the same address as a Geflex instrument; the value (Cod) set on the rotary switches corresponds to that of Zone 1; the values in the other zones, if expansions are present, are sequential.

Examples:
if the rotary switches have value 14, node 14 addresses Zone 1 (GFW-M), node 15 Zone 2 (GFW-E1), node 16 Zone 3 (GFW-E2).
The power Ou.P for Zone 1 has address Cod 2, the Ou.P for Zone 2 has address Cod+1, 2, etc...
Parameter out.5, which defines the function of output OUT 5 on the GFW, has address Cod 611.

GFX4/GFW mode (dip-switch-7=OFF)

This lets you optimize the efficiency of serial communication by integrating at most 3 zones in the GFW. Memory is organized in 4 groups: 3 already in GFX-compatible mode, plus one group defined as custom:
- Custom (additional memory map for dynamic addresses)
- Zone 1 for the variables of the module GFW-M
- Zone 2 for the variables of the module GFW-E1
- Zone 3 for the variables of the module GFW-E2

The custom group contains variables and parameters for a maximum of 120 words. The meaning of these words can be changed.

There is a single value (Cod) set on the rotary switches; i.e., one for each GFX4/GFW instrument. To access the data in each zone, simply add an offset to the address (+1024 for Zone 1, +2048 for Zone 2, +4096 for Zone 3).

Words in the custom group have addresses 0,...,119. The variables and parameters are defined by default. At addresses 200,...,319 we have words containing the value of the address of the corresponding variables or parameters. These addresses can be changed by the user, offering the ability to read/write data with multi-word messages structured according to various supervision requirements.

Protection of Maps 1-2
You have to write the value 99 on addresses 600 and 601 to enable change of the custom group (addresses 200... 319).
This value is reset at each switch-on.

Examples:
you can access the Ou.P variable in Zone 1 with address Cod, 1+1024 or address Cod, 11 custom variable 12 (address Cod, 211 has value 2+1024);
you can access the Ou.P variable in Zone 2 with address Cod, 2+ 2048 or address Cod, 40 custom variable 41 (address Cod, 240 has value 2+2048);
if you want to read the 3 powers in sequence at the first 3 addresses, set Cod, 200 = 1026, Cod.201 = 2050, Cod,202 = 4098.

CONNECTION

Each GFW has an optically isolated serial port RS485 (PORT 1) with standard Modbus protocol via connectors J8 and J9 (type RJ10).

You can insert a serial interface (PORT 2). There are various models based on the field bus required: Modbus, Profibus DP, CANopen, DeviceNet and Ethernet.
This communication port (PORT 2) has the same Cod address as PORT 1.
The parameters for PORT 2 are bAu.2 (select baud-rate) and Par.2 (select parity).
The Cod parameter (read only) shows the value of the node address, settable from 00 to 99 with the 2 rotary switches; the hexadecimal settings are reserved.
A parameter can be read or written from both communication ports (PORT 1 and PORT 2).

Changing the bAU (select baud-rate) and/or PAr (select parity) parameters may cause communication failure.

To set the bAu and PAr parameters, you have to run the Autobaud procedure described in the "Instruction and warnings" manual.

Installation of the "MODBUS" serial network

A network typically has a Master that "manages" communication by means of "commands" and Slaves that interpret these commands.

GFW are considered Slaves to the network master, which is usually a supervision terminal or a PLC.
They are positively identified by means of a node address (ID) set on the rotary switches (tens + ones).

GFW have a ModBus serial (Serial 1) and optional Fieldbus (Serial 2) serial (see order code) with one of the following protocols: ModBus, Profibus, CANopen, DeviceNet, Ethernet, EtherCAT and EthernetIP.

The following procedures are indispensable for the Modbus protocol.
For the remaining protocols, see the specific Geflex Profibus, Geflex CANopen, Geflex DeviceNet, Geflex Ethernet, GFX4-EtherCAT and GFX4-ETH1 manuals.
GFW modules have the following default settings:
- node address = 0 (0 + 0)
- speed Serial 1 = 19200 bit/s
- parity Serial 1 = none
- speed Serial 2 = 19200 bit/s
- parity Serial 2 = none

You can install a maximum of 99 GFW modules in a serial network, with node address selectable from "01" to "99" in standard mode, or create a mixed GFW / GFX4 network in GFX compatible mode in which each GFW identifies 3 zones with sequential node address starting from the code set on the rotary switches.
In short, the valid rotary switch settings (tens + ones) are:
- (0 +0) = Autobaud Serial 1
- (B +0) = Autobaud Serial 2

46	Cod	R	*Device identification code*	1 ... 99		
45	bAu	R/W	Select Baudrate - Serial 1	*Baudrate table*		4
626	bAu.2	R/W	Select Baudrate - Serial 2	0 1200 bit/s 1 2400 bit/s 2 4800 bit/s 3 9600 bit/s 4 19200 bit/s 5 38400 bit/s 6 57600 bit/s 7 115200 bit/s		4
47	PAr	R/W	Select parity - Serial 1	*Parity table*		0
627	PAr.2	R/W	Select parity - Serial 2	0 No parity 1 Odd 2 Even		0

INPUTS

ANALOG INPUT

The modular power controller has a analog input with the functionality power retransmission.

Probe type

573	tP.A	R/W	analog input	Table of analog input	1

0	Disable
1	0 ... 10V
2	0 ... 5V/Potentiometer
3	0 ... 20mA
4	4 ... 20mA

Scale limits

574	LS.A	R/W	Minimum scale limit analog input	-100,0...200,0		0,0
575	HS.A	R/W	Maximum scale limit analog input	LS.A...200,0		100,0

Offset adjustment

577	oFS.A	R/W	*Offset correction for analog input*	-99,9...99,9		0,0

Read state

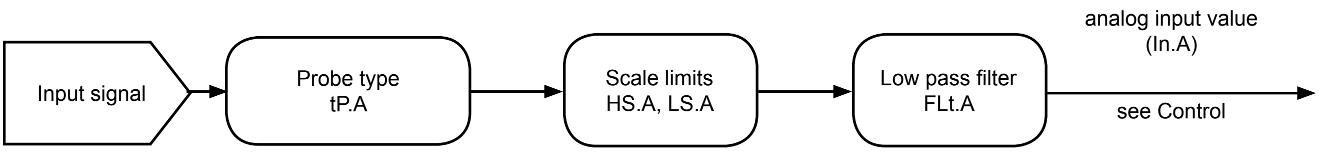
572	In.A	R	Value of the ingegneristico reading analog input

ADVANCED SETTINGS

Input filter

576	FLt.A	R/W	Low pass digital filter analog input	0,0...20,0 sec		0,1

FUNCTIONAL DIAGRAM



MAIN INPUT PID

The modular power controller has one main input (IN1) to control, to which you can connect temperature sensors (thermocouples and RTD), linear sensors or custom sensors to acquire process variable (PV) values.
These type of input is optional.

To configure, you always have to define the type of probe or sensor (tYP), the maximum and minimum scale limit (Hi.S – Lo.S) for the process variable value, and the position of the *decimal point* (dP.S).
If the sensor is a thermocouple or resistance thermometer, the minimum and maximum limits can be defined on the specific scale of the sensor. These limits define the width of the proportional control band and the range of values settable for the setpoint and alarm setpoints.

There is a parameter to correct the offset of the input signal (oF.S): the set value is algebraically added to the read of the process variable.

You can read the state of the main input (Err) in which an input error is reported: when the *process variable* goes beyond the upper or lower scale limit, it assumes the value of the limit and the corresponding state reports the error condition:
Lo = process variable < minimum scale limit
Hi = process variable > maximum scale limit
Err = Pt100 in short circuit and input value below minimum limit,
4...20mA transmitter interrupted or not powered
Sbr = Tc probe interrupted or input value above maximum limit

If noise on the main input causes instability of the acquired value, you can reduce its effect by setting a low pass digital filter (Flt). The default setting of 0.1sec is usually sufficient.

You can also use a *digital filter* (Fld) to increase the apparent stability of the process variable PV; the filter introduces a hysteresis on its value: if the input variation remains within the set value, the DPV value is considered unchanged.

Probes and sensors

400	tYP.	R/W	Probe type, signal, enable, custom linearization and main input scale	*Table of probes and sensors*	0

TC SENSOR

Type	Type of probe	Scale	Without dec. point	With dec. point
0	TC J	°C	0/1000	0.0/999.9
1	TC J	°F	32/1832	32.0/999.9
2	TC K	°C	0/1300	0.0/999.9
3	TC K	°F	32/2372	32.0/999.9
4	TC R	°C	0/1750	0.0/999.9
5	TC R	°F	32/3182	32.0/999.9
6	TC S	°C	0/1750	0.0/999.9
7	TC S	°F	32/3182	32.0/999.9
8	TC T	°C	-200/400	-199.9/400.0
9	TC T	°F	-328/752	-199.9/752.0
28	TC	custom	custom	custom
29	TC	custom	custom	custom

SENSOR: RTD 3-wires

Type	Type of probe	Scale	Without dec. point	With dec. point
30	PT100	°C	-200/850	-199.9/850.0
31	PT100	°F	-328/1562	-199.9/999.9
32	JPT100	°C	-200/600	-199.9/600.0
33	JPT100	°F	-328/1112	-199.9/999.9

SENSOR: 60mV voltage

Type	Type of probe	Scale	Without dec. point	With dec. point
34	0...60 mV	Linear	-1999/9999	-199.9/999.9
35	0...60 mV	Linear	Custom linearization	Custom linearization
36	12...60 mV	Linear	-1999/9999	-199.9/999.9
37	12...60 mV	Linear	Custom linearization	Custom linearization

SENSOR: 20mA current

Type	Type of probe	Scale	Without dec. point	With dec. point
38	0...20 mA	Linear	-1999/9999	-199.9/999.9
39	0...20 mA	Linear	Custom linearization	Custom linearization
40	4...20 mA	Linear	-1999/9999	-199.9/999.9
41	4...20 mA	Linear	Custom linearization	Custom linearization

SENSOR: 1V voltage

Type	Type of probe	Scale	Without dec. point	With dec. point
42	0...1 V	linear	-1999/9999	-199.9/999.9
43	0...1 V	linear	Custom linearization	Custom linearization
44	200 mv..1 V	linear	-1999/9999	-199.9/999.9
45	200 mv..1 V	linear	Custom linearization	Custom linearization

SENSOR: Custom

Type	Type of probe	Scale	Without dec. point	With dec. point
46	Cust. 20mA	-	-1999/9999	-199.9/999.9
47	Cust. 20mA	-	Custom linearization	Custom linearization
48	Cust. 60mV	-	-1999/9999	-199.9/999.9
49	Cust. 60mV	-	Custom linearization	Custom linearization
50	PT100-JPT	-	custom	custom

99 Input off

Maximum error of non linearity for thermocouples (Tc), resistance thermometer (PT100)

Tc type:
J, K error < 0.2% f.s.
S, R range 0...1750°C: error < 0.2% f.s. (t > 300°C)
For other ranges: error < 0.5% f.s.
T error < 0.2% f.s. (t > -150°C)

And inserting a custom linearization
E, N, L error <0.2% f.s.
B range 44...1800°C; error < 0.5% f.s. (t > 300°C)
range 44.0...999.9; error f.s.(t>300°C)
U range -200...400; error < 0.2% f.s. (for t > -100°C)
For other ranges; error <0.5% f.s.
G error < 0.2% f.s. (t > 300°C)
D error < 0.2% f.s. (t > 200°C)
C range 0...2300; error < 0.2% f.s.
For other ranges; error < 0.5% f.s.

JPT100 and PT100 error < 0.2% f.s.

The error is calculated as deviation from theoretical value with % reference to the full-scale value expressed in degrees Celsius (°C).

403	dP.S	R/W	Decimal point position for input scale	*Decimal point table*	0

Specifies the number of decimal figures used to represent the input signal value: for example, 875.4 (°C) with dP.S = 1.

	Format
0	xxxx
1	xxx.x
2	xx.xx (*)
3	x.xxx (*)

(*) Not available for TC, RTD probes

Scale limits

401	Lo.S	R/W	Minimum scale limit of main input	min...max scale of input selected in tyP	0

Engineering value associated to minimum level of the signal generated by the sensor connected to the input: for example 0 (°C) with type K thermocouple.

402	HI.S	R/W	Maximum scale limit of main input	min...max scale of input selected in tyP	1000

Engineering value associated to maximum level of the signal generated by the sensor connected to the input: for example 1300 (°C) with type K thermocouple.

Setting the offset

519 23	oFS.	R/W	*Offset correction for main input*	-999...999 scale points	0

Lets you set a value in scale points that is algebraically added to the value measured by the input sensor.

Read state

0 470	P.V.	R	Read of engineering value of process variable (PV)

85	Err	R	Self-diagnostic error code of main input	*Error code table*
	For custom linearization (tYP = 28 or 29): - LO is signaled with input values below Lo.S or at minimum calibration value. - HI is signaled with input values above Lo.S or at maximum calibration value.			

0	No Error
1	Lo (process variable value is < Lo.S)
2	Hi (process variable value is > di Hi.S)
3	ERR [third wire interrupted for PT100 or input values below minimum limits (ex.: for CT with connection error)]
4	SBR (probe interrupted or input values beyond maximum limits)

349	DPV	R	Read of engineering value of process variable (PV) filtered by FLd

ADVANCED SETTINGS

Input filters

24	FLt	R/W	Low pass digital filter on input signal	0.0 .... 20.0 sec		0,1

Sets a low pass *digital filter* on the main input, running the average value read in the specified time interval. If = 0 exclude the average filter on the sampled values.

179	FLd	R/W	Digital filter on oscillations of input signal	0 ... 9.9 scale points		0,5

Introduces a hysteresis zone on the input signal value within which the signal is considered unchanged, thereby increasing its apparent stability.

Linearization of input signal

The modular power controller lets you set a custom linearization of the signal acquired by the main input for signals coming from sensors and for signals coming from custom thermocouples.
Linearization is performed with 33 values (S00 ... S32: 32 segments).
S33, S34, S35 are an additional 3 values to be inserted in case of linearization with custom CT.

- Signals from sensors

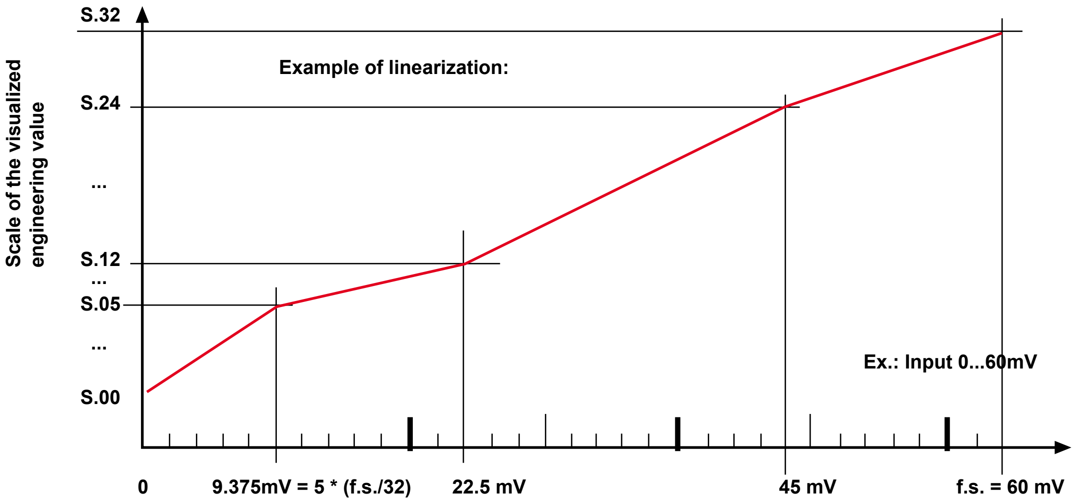
For signals coming from sensors, linearization is done by dividing the input scale into 32 zones of equal dV amplitude, where:

$$dV = (\text{full-scale value} - \text{start of scale value}) / 32$$

Point 0 (origin) corresponds to the engineering value attributed to the minimum value of the input signal.
Subsequent points correspond to the engineering values attributed to input values equal to:

$$\text{Input value (k)} = \text{Minimum input value} + k * dV$$

where k is the order number of the linearization point



The engineering values calculated in this way by the user can be set by means of the following parameters.

86	S.00	R/W	Engineering value attributed to Point 0 (minimum value of input scale)	(- 1999 ... 9999)
87	S.01	R/W	Engineering value attributed to Point 1	(- 1999 ... 9999)
	. . . . .		intermediate values	
118	S.32	R/W	Engineering value attributed to Point 32 (maximum value of input scale)	(- 1999 ... 9999)

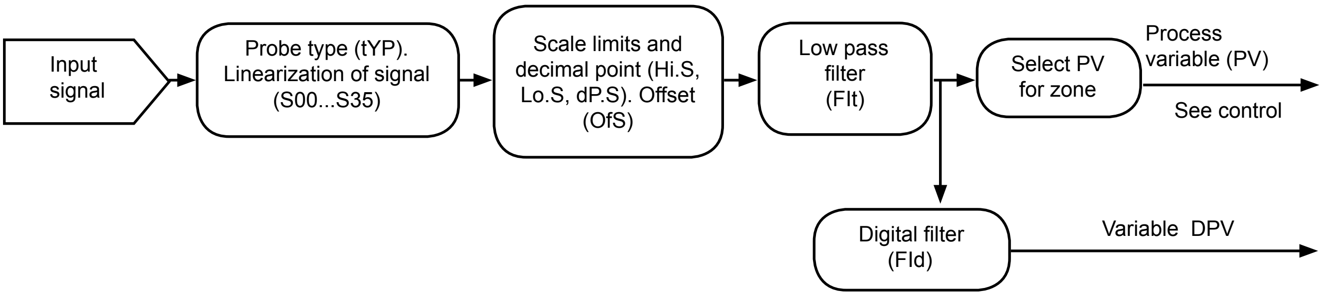
For correct signaling of error state (Lo, Hi), the value set in S.00 must coincide with limit Lo.S and the value set in S.32 with limit Hi.S.

- Signals coming from custom thermocouples

An alternate linearization is available only for sensors consisting of custom thermocouples, created by defining engineering values at three measurement scale points settable with the following parameters:

293	S.33	R/W	Engineering value attributed to minimum value of the input scale.	mV start of scale (- 19,99 ... 99,99)
294	S.34	R/W	Engineering value attributed to maximum value of the input scale.	mV full scale ((S.33+1) ... 99,99)
295	S.35	R/W	Engineering value attributed to input signal corresponding to 50°C.	mV at 50° C (- 1,999 ... 9,999)

FUNCTIONAL DIAGRAM



N.B. The decimal point does not change the contents of the PV, but only permits its correct interpretation.
Ex.: if dP.S = 1 and PV = 300, the engineering value in °C is 30.0.

CURRENT VALUE IN LOAD

The RMS current value is read in variable Ld.A of each zone.
If zone 1 has a 3-phase load, variable Ld.At contains the average value of the three RMS currents. The Ld.A of the first three zones contain the RMS current value on lines L1, L2 and L3, respectively..
Accuracy is better than 1% in start modes ZC, BF and HSC.
Accuracy is better than 3% in PA mode with conduction angle >90°, and better than 10% for lower conduction angles.
The circulating current in the load is acquired with a 0.25ms sampling time.

In addition, there are the following parameters for a zone with single-phase load:

I.tA1 instantaneous ammeter value
I.AF1 filtered ammeter value (see Ft.tA)
I1on current with active control
o.tA1 ammeter input offset correction
Ft.tA ammeter input digital filter

There are also the following parameters if zone 1 has a three-phase load:

I.tA1, I.tA2 and I.tA3 instantaneous ammeter value on line L1, L2 and L3
I.AF1, I.AF2 and I.AF3 filtered ammeter value (see Ft.tA) on line L1, L2 and L3
I1on, I2on and I3on current with active control
o.tA1, o.tA2 and o.tA3 ammeter input offset correction on line L1, L2 and L3
Ft.tA ammeter input digital filter

If diagnostics detects a fault condition on the load, the red ER LED will flash in synch with yellow LED O1 or O2 or O3 for the zone in question.
The condition POWER FAULT in OR with HB alarm can be assigned to an alarm or identified in the state of a bit in variables STATUS, STATUS1, STATUS2 and STATUS3.
In STATUS3 you can identify the condition that activated the POWER_FAULT alarm.

POWER_FAULT diagnostics is configurable with parameter hd.2, with which even just a part may be enabled

SSR SHORT SSR module in short circuit
NO VOLTAGE power failure or interrupted fuse
NO CURRENT due to SSR module open or fuse or load interrupted

For alarm HB (load partially interrupted), refer to the specific section of this manual.

The default value of the maximum limit or ammeter full-scale depends on the model:

MODEL	H.tA
40A	80,0
60A	120,0
100A	200,0
150A	300,0
200A	400,0
250A	500,0

Scale limits

746*	L.tA1	R	Minimum limit of CT ammeter input scale (phase1)		
747	L.tA2	R	Minimum limit of CT ammeter input scale (phase 2)		With 3-phase load
748	L.tA3	R	Minimum limit of CT ammeter input scale (phase 3)		With 3-phase load
405*	H.tA1	R	Maximum limit of CT ammeter input scale (phase 1)		
413	H.tA2	R	Maximum limit of CT ammeter input scale (phase 2)		With 3-phase load
414	H.tA3	R	Maximum limit of CT ammeter input scale (phase 3)		With 3-phase load

Setting the offset

220	o.tA1	R/W	<u>Offset correction CT input</u> (phase 1)	-99.9 ...99.9 scale points		0,0 zone 1	0,0 zone 2	0,0 zone 3
415	o.tA2	R/W	Offset correction CT input (phase 2)	-99.9 ...99.9 scale points	With 3-phase load			
416	o.tA3	R/W	Offset correction CT input (phase 3)	-99.9 ...99.9 scale points	With 3-phase load			

Read state

227* 473 - 139 - 756	I.tA1	R	Instantaneous CT ammeter input value (phase 1)	
490 494	I.tA2	R	Instantaneous CT ammeter input value (phase 2)	With 3-phase load
491 495	I.tA3	R	Instantaneous CT ammeter input value (phase 3)	With 3-phase load
468*	I.1on	R	CT filtered ammeter input value with output activated (phase 1)	
498	I.2on	R	CT filtered ammeter input value with output activated (phase 2)	With 3-phase load
499	I.3on	R	CT filtered ammeter input value with output activated (phase 3)	With 3-phase load
709*	I.tAP	R	Peak ammeter input during phase softstart ramp	
716*	co5.F	R	Power factor in hundredths	
753*	Ld.A	R	Current RMS on load	
754	Ld.A.t	R	Current RMS on 3-phase load	

ADVANCED SETTINGS

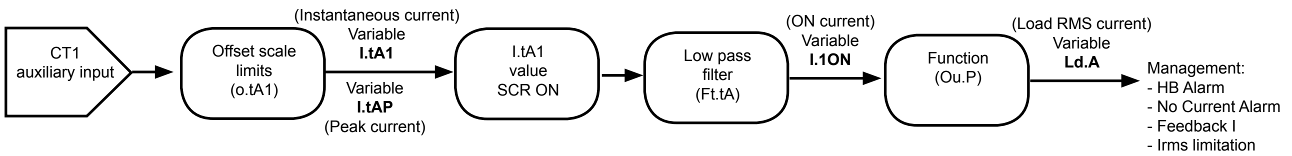
Input filter

219*	Ft.tA	R/W	*<u>CT input digital filter</u>*	0.0 ... 20.0 sec		0,1 zone 1	0,1 zone 2	0,1 zone 3

Sets a low pass filter on the CT auxiliary input, running the average of values read in the specified time interval. If = 0 , excludes the average filter on sampled values.

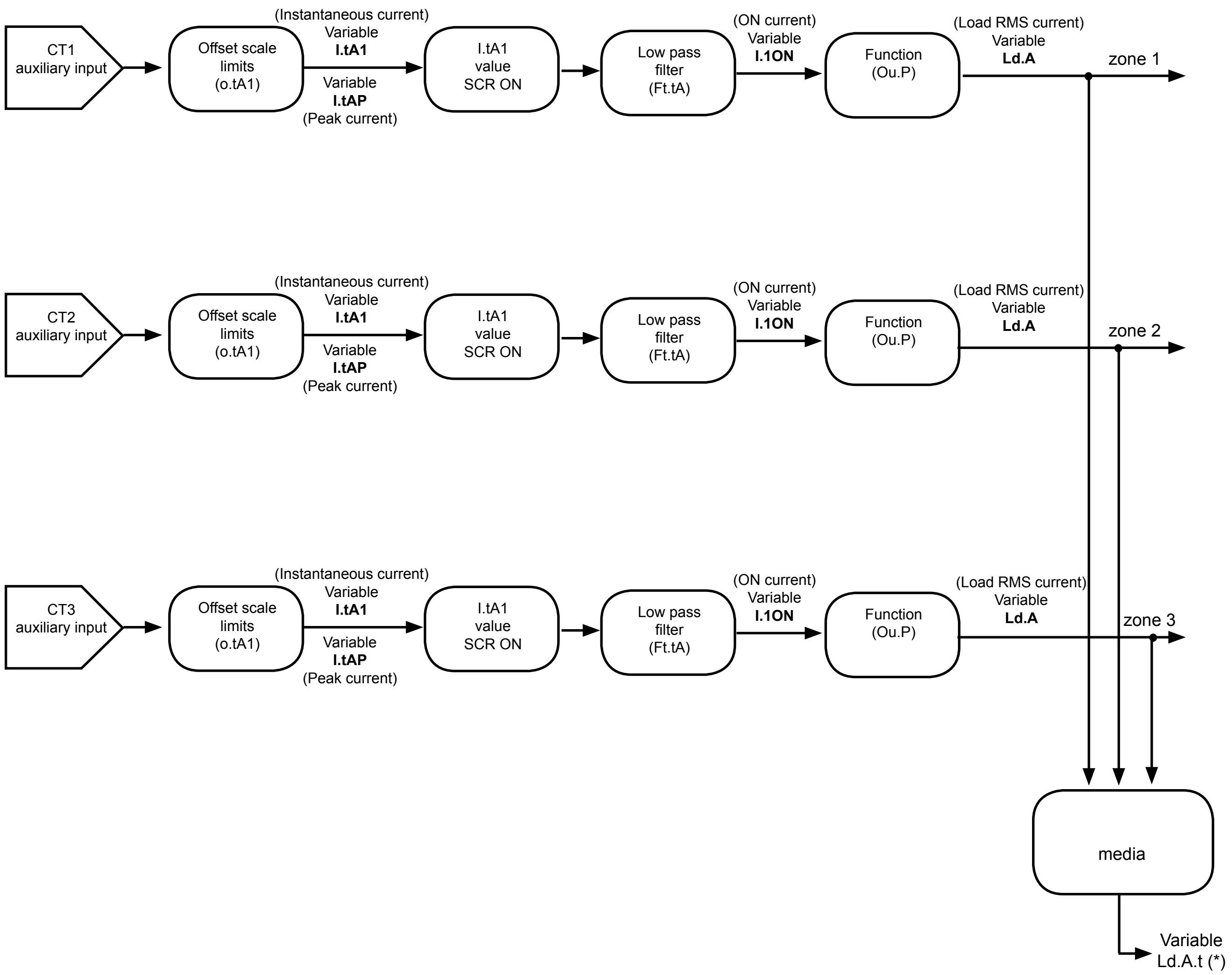
FUNCTIONAL DIAGRAM

Monophase load



FUNCTIONAL DIAGRAM

Threephase load



(*) with BI-PHASE command the Ld.A value of zone 3 is gained like average of the Ld.A values of zones 1 and 2

VOLTAGE VALUE ON LOAD

RMS voltage is read in variable Ld.V of each zone. If zone 1 has a 3-phase load, variable Ld.V.t in the first zone contains the average RMS value of voltages on three load L1, L2 and L3.
Voltage on the load is acquired with sampling on each cycle, 20ms at 50Hz (16.6ms at 60Hz). Accuracy is better than 1%.
If the option VLOAD is not present, the Load RMS voltage value is calculated from the line voltage and from the output power values.

Read state

751*	Ld.V	R	Voltage on load	
752	Ld.V.t	R	Voltage on 3-phase load (*)	

if the option VLOAD is present there are available the following parameters:

Scale limit

439*	L.tVL	R	Minimum limit of TV_LOAD voltmeter input scale	
443*	H.tVL	R	Maximum limit of TV_LOAD voltmeter input scale	

Setting the offset

444*	o.tVL	R/W	Offset correction for TV_LOAD input		-99.9 ...99.9 scale points		0,0 zona 1	0,0 zona 2	0,0 zone 3

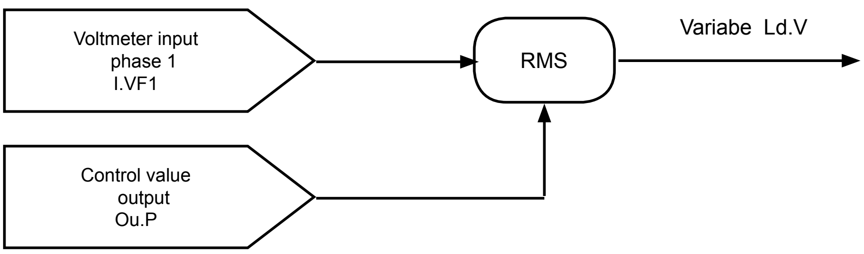
ADVANCED SETTINGS

Input filter

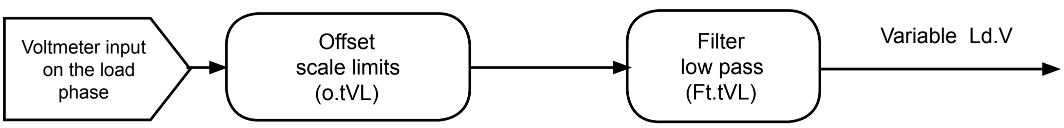
442*	Ft.tVL	R/W	Digital filter for voltmeter transformer TV_LOAD input		0,0 ..20,0 sec		0,1 zona 1	0,1 zona 2	0,1 zone 3

FUNCTIONAL DIAGRAM

Single-Phase Load without VLOAD option

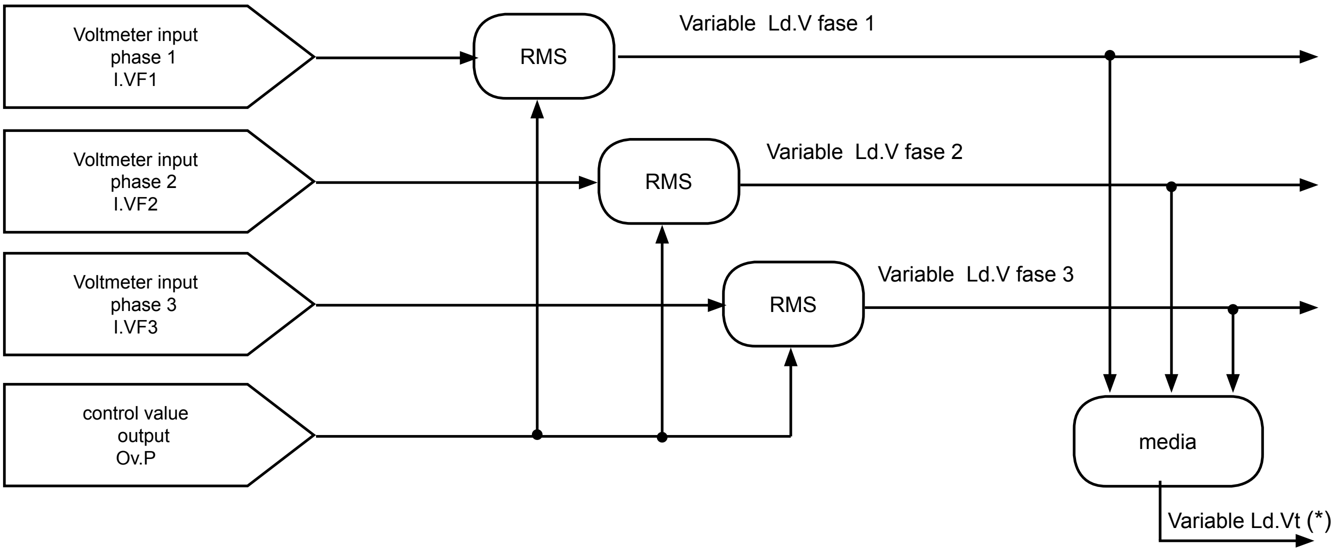


Single-Phase Load with VLOAD option

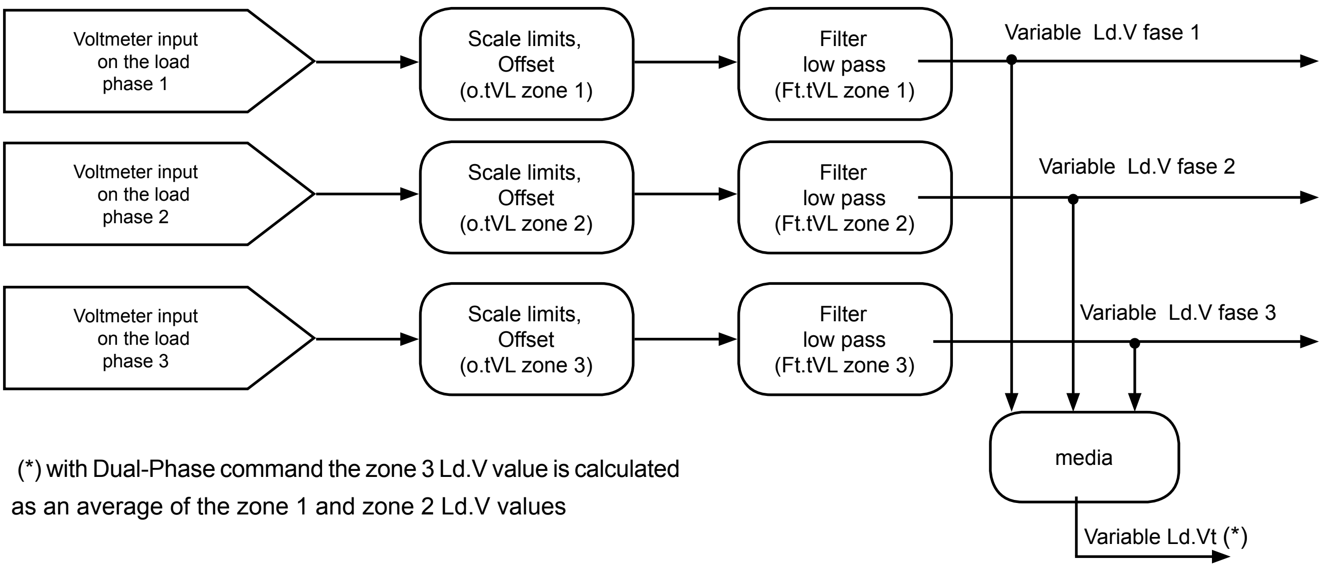


FUNCTIONAL DIAGRAM

Three-Phase Load without VLOAD option



Three-Phase Load with VLOAD option



(*) with Dual-Phase command the zone 3 Ld.V value is calculated as an average of the zone 1 and zone 2 Ld.V values

LINE VOLTAGE VALUE

There are the following parameters if zone 1 has a single-phase load:
- I.tV1 instantaneous voltmeter value of line
- I.VF1 filtered voltmeter value
- o.tV1 voltmeter input offset correction
- Ft.tV voltmeter input digital filter

There are the following parameters if zone 1 has a 3-phase load:
- I.tV1, I.tV2 and I.tV3, the instantaneous voltmeter value on line L1, L2 and L3, respectively.

RMS voltage values refer to voltage between 1/L1 and 3/L2 terminals.
I.VF1, I.VF2 and I.VF3 filtered voltmeter value on line L1, L2 and L3
o.tV1, o.tV2 and o.tV3 voltmeter input offset correction on line L1, L2 and L3.
Each phase has a voltage presence check that shuts off the module in case of incorrect values.
3-phase loads have an imbalance diagnostic, with consequent shut-down of the load and signal via LEDs.
A “voltage status” parameter contains information on the status of line voltage, including mains frequency identified 50/60Hz.
3-phase loads have diagnostics for correct phase connection, lack of a voltage, or imbalance of the three line voltages.

Scale limits

453*	L.tV1	R	Minimum limit of TV voltmeter input scale (phase1)	
454	L.tV2	R	Minimum limit of TV voltmeter input scale (phase 2)	With 3-phase load
455	L.tV3	R	Minimum limit of TV voltmeter input scale (phase 3)	With 3-phase load
410*	H.tV1	R	Maximum limit of TV voltmeter input scale (phase 1)	
417	H.tV2	R	Maximum limit of TV voltmeter input scale (phase 2)	With 3-phase load
418	H.tV3	R	Maximum limit of TV voltmeter input scale (phase 3)	With 3-phase load

Setting the offset

411*	o.tU1	R/W	<u>Offset correction for TV input</u> (phase 1)	-99.9 ...99.9 Scale points		0,0 zone 1	0,0 zone 2	0,0 zone 3
419	o.tU2	R/W	Offset correction for TV input (phase 2)	-99.9 ...99.9 Scale points	With 3-phase load	0,0		
420	o.tU3	R/W	Offset correction for TV input (phase 3)	-99.9 ...99.9 Scale points	With 3-phase load	0,0		

Read state

232* 485	I.tU1	R	Value of voltmeter input (phase 1)	
492	I.tU2	R	Value of voltmeter input (phase 2)	With 3-phase load
493	I.tU3	R	Value of voltmeter input (phase 3)	With 3-phase load
322*	I.UF1	R	Value filtered of voltmeter input (phase 1)	
496	I.UF2	R	Value filtered of voltmeter input (phase 2)	With 3-phase load
497	I.UF3	R	Value filtered of voltmeter input (phase 3)	With 3-phase load
702		R	Voltage Stutus	*<u>Table Voltage Status</u>*
315*	FrEq	R	Voltage frequency in tenths of Hz	

bit	
0	frequency_warning
1	10% umbalanced_line_warning
2	20% umbalanced_line_warning
3	30% umbalanced_line_warning
4	rotation 123_error
5	triphase_missing_line_error
6	60Hz

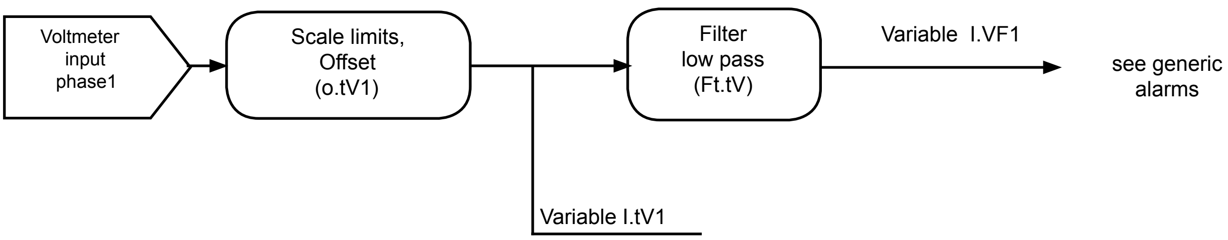
ADVANCED SETTINGS

Input filter

412*	Ft.tU	R/W	Digital filter for voltmeter transformer TV input	0.0 ... 20.0 sec.		2,0 zone 1	2,0 zone 2	2,0 zone 3
Sets a low pass filter on the auxiliary TV input, running the average of values read in the specified time interval. If = 0 , excludes the average filter on sampled values.								

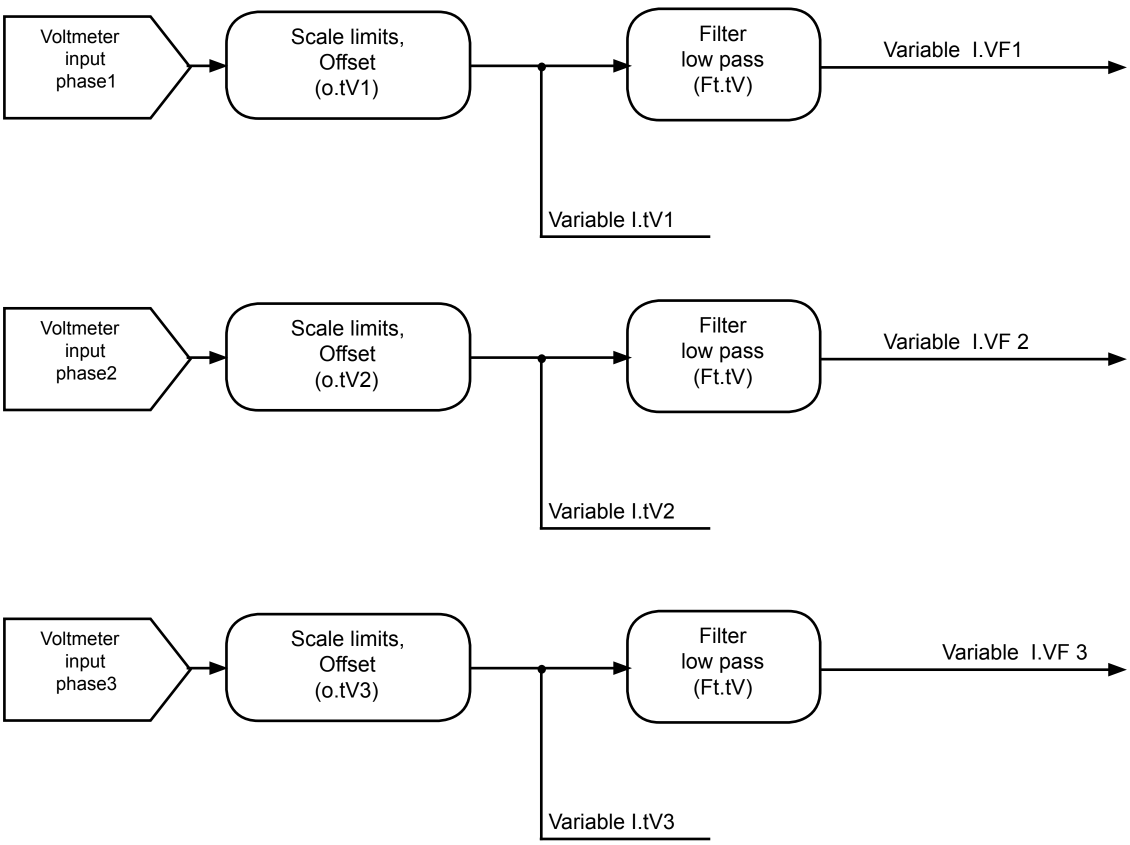
FUNCTIONAL DIAGRAM

Single-phase load



FUNCTIONAL DIAGRAM

3-phase load



POWER ON LOAD

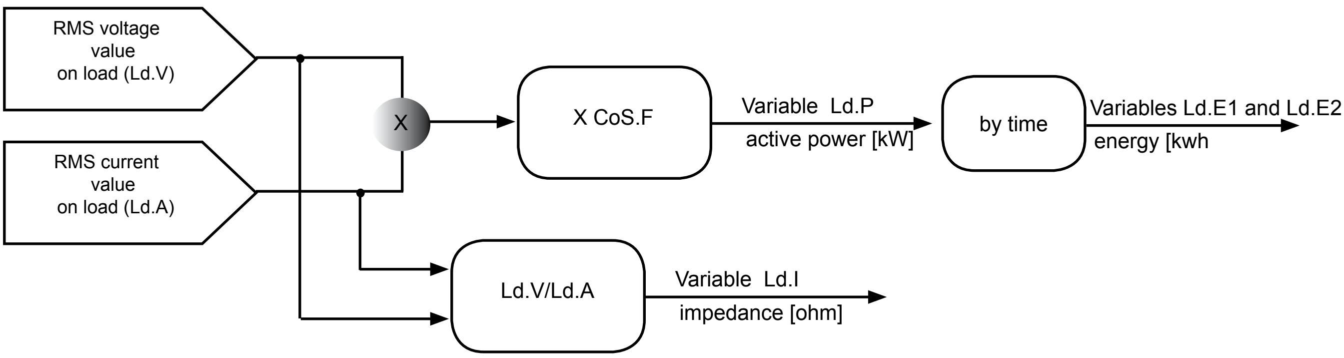
Power on the load in each zone is read in variable Ld.P and the corresponding energy value in variables Ld.E1 and Ld.E2. These energy values show the value accumulated since the first power on or since the last reset (commands at bits 114 and 115); non-volatile memory is updated at power off.
Load impedance in each zone is read in variable Ld.I.
If zone 1 has a 3-phase load, variable Ld.P.t shows power and Ld.I.t total impedance, the corresponding energy value in variables Ld.E1.t and Ld.E2.t.

Note that for loads such as IR lamps, impedance can vary greatly based on the power transferred to the load.

719*	Ld.P	R	Power on load	
720	Ld.P.t	R	Power on load 3-phase	
749*	Ld. I	R	Impedance on load	
750	Ld. I.t	R	Impedance onload 3-phase	
531*	Ld.E 1	R	**Energy on load**	**Data in DWORD (32 bit) format**
541	Ld.E 1.t	R	**Energy on 3-phase load**	**Data in DWORD (32 bit) format**
510*	Ld.E2	R	**Energy on load**	**Data in DWORD (32 bit) format**
541	Ld.E2.t	R	**Energy on 3-phase load**	**Data in DWORD (32 bit) format**
114* bit	Azzeramento Ld.E 1	R/W	**OFF = -** **ON = Reset Ld.E1**	
115* bit	Azzeramento Ld.E2	R/W	**OFF = -** **ON = Reset Ld.E2**	

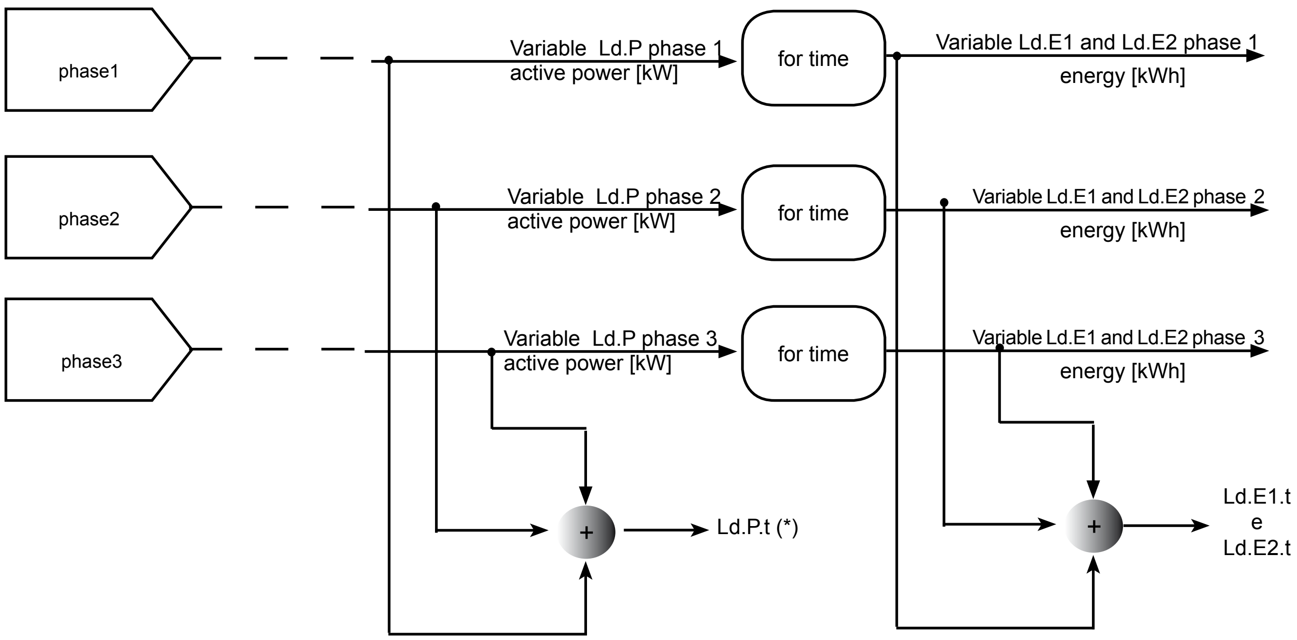
FUNCTIONAL DIAGRAM

Single-phase load

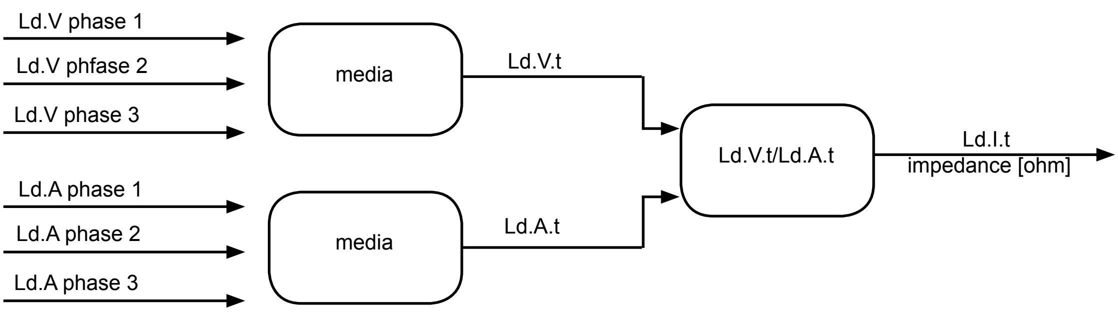


FUNCTIONAL DIAGRAM

3-phase load



(*) with BI-PHASE command the Ld.A value of zone 3 is gained like average of the Ld.A values of zones 1 and 2



AUXILIARY ANALOG INPUTS (LIN/TC)

The GFW has 4 inputs defined as auxiliary (IN2 for zone 1, IN3 for zone 2, IN4 for zone 3, IN5 for zone 4) to which TC or linear temperature sensors can be connected.
The presence of these inputs is optional

Input values are available in variables In.2/In.3/In.4/In.5 and can be read or used to activate assigned alarm signals.

When an auxiliary input is present, you have to define the following parameters:
- sensor type (**AI.2**, **AI.3, AI.4, AI.5**);
- its function (**tP.2**); (only for IN2 input)
- decimal point position (**dP.2, HS.3 – LS.3, HS.4 – LS.4, HS.5 – LS.5**);
- scale limits (**HS.2 – LS.2**);
- offset correction value (**oFS.2, oFS.3, oFS.4, oFS.5**).

If the sensor is a thermocouple, the minimum and maximum limits can be defined in the specific scale of the sensor used. The range of values settable for alarm setpoints depends on these limits.

There is also a digital filter (**Flt.2, Flt.3, Flt.4, Flt.5,**) that can be used to reduce noise on the input signal.

194	AI.2	R/W	Select type of auxiliary sensor input 2	0
553	AI.3	R/W	Select type of auxiliary sensor input 3	0
554	AI.4	R/W	Select type of auxiliary sensor input 4	0
555	AI.5	R/W	Select type of auxiliary sensor input 5	0

Auxiliary inputs sensors table

Type	Type of probe or sensor	Without dec. point	With dec. point
0	TC J °C	0/1000	0.0/999.9
1	TC J °F	32/1832	32.0/999.9
2	TC K °C	0/1300	0.0/999.9
3	TC K °F	32/2372	32.0/999.9
4	TC R °C	0/1750	0.0/999.9
5	TC R °F	32/3182	32.0/999.9
6	TC S °C	0/1750	0.0/999.9
7	TC S ° F	32/3182	32.0/999.9
8	TC T °C	-200/400	-199.9/400.0
9	TC T °F	-328/752	-199.9/752.0
34	0...60 mV	-1999/9999	-199.9/999.9
35	0...60 mV	Custom linearization	Custom linearization
36	12...60 mV	-1999/9999	-199.9/999.9
37	12...60 mV	Custom linearization	Custom linearization
99	Input off		

181	tP.2	R/W	Definition of auxiliary analog input function	0

Table of auxiliary input functions

tP.2	Auxiliary input function	LIMITS FOR SETTING the LS.2 and HS.2 min	max	
0	None	-1999	9999	
1	Remote setpoint	Absolute Lo.S, deviation -999	Absolute Hi.S, deviation +999	(*)
2	Manual analog remote	-100.0%	+100.0%	(*)
3	Reset analog power	-100.0%	+100.0%	(**)
8	analogic remote manual from main input			(*)
16	remote manual from analogic input			(*)
32	remote manual from PWM input			(*)

(*) see: Settings – Control Setpoint
(**) see: Controls –PID Parameters

677	dP.2	R/W	Decimal point position for the auxiliary input scale 2	0
568	dP.3	R/W	Decimal point position for the auxiliary input scale 3	0
569	dP.4	R/W	Decimal point position for the auxiliary input scale 4	0
570	dP.5	R/W	Decimal point position for the auxiliary input scale 5	0

Specifies the number of decimal figures used to represent the input signal value: for example, 875.4 (°C) with dP.S: = 1

Decimal point table

	Format
0	xxxx
1	xxx.x
2	xx.xx (*)
3	x.xxx (*)

(*) not available for TC probes

Scale limits

404	LS.2	R/W	Minimum limit of auxiliary input scale 2	Min...max input scale selected in AI.2 and tP.2	0
556	LS.3	R/W	Minimum limit of auxiliary input scale 3	Min...max input scale selected in AI.3	0
557	LS.4	R/W	Minimum limit of auxiliary input scale 4	Min...max input scale selected in AI.4	0
558	LS.5	R/W	Minimum limit of auxiliary input scale 5	Min...max input scale selected in AI.5	0

603	HS.2	R/W	Maximum limit of auxiliary input scale 2	Min...max input scale selected in AI.2 and tP.2	1000
559	HS.3	R/W	Maximum limit of auxiliary input scale 3	Min...max input scale selected in AI.3	1000
560	HS.4	R/W	Maximum limit of auxiliary input scale 4	Min...max input scale selected in AI.4	1000
561	HS.5	R/W	Maximum limit of auxiliary input scale 5	Min...max input scale selected in AI.5	1000

Setting the offset

605	oFS.2	R/W	*Offset for auxiliary input correction 2*	-999 ...999 Scale points		0
565	oFS.3	R/W	*Offset for auxiliary input correction 3*	-999 ...999 punti scala		0
566	oFS.4	R/W	*Offset for auxiliary input correction 4*	-999 ...999 punti scala		0
567	oFS.5	R/W	*Offset for auxiliary input correction 5*	-999 ...999 punti scala		0

Read state

602	In.2	R	Value of auxiliary input 2
547	In.3	R	Value of auxiliary input 3
548	In.4	R	Value of auxiliary input 4
549	In.5	R	Value of auxiliary input 5

606	Er.2	R	Error code for self-diagnosis of auxiliary input 2
550	Er.3	R	Error code for self-diagnosis of auxiliary input 3
551	Er.4	R	Error code for self-diagnosis of auxiliary input 4
552	Er.5	R	Error code for self-diagnosis of auxiliary input 5

Error code table

0	No error
1	Lo (value of process variable is < LS.x)
2	Hi (value of process variable is > HS.x)
3	ERR [third wire interrupted for PT100 or input values below minimum limits (ex.: for TC with connection error)]
4	SBR (probe interrupted or input values beyond maximum limits)

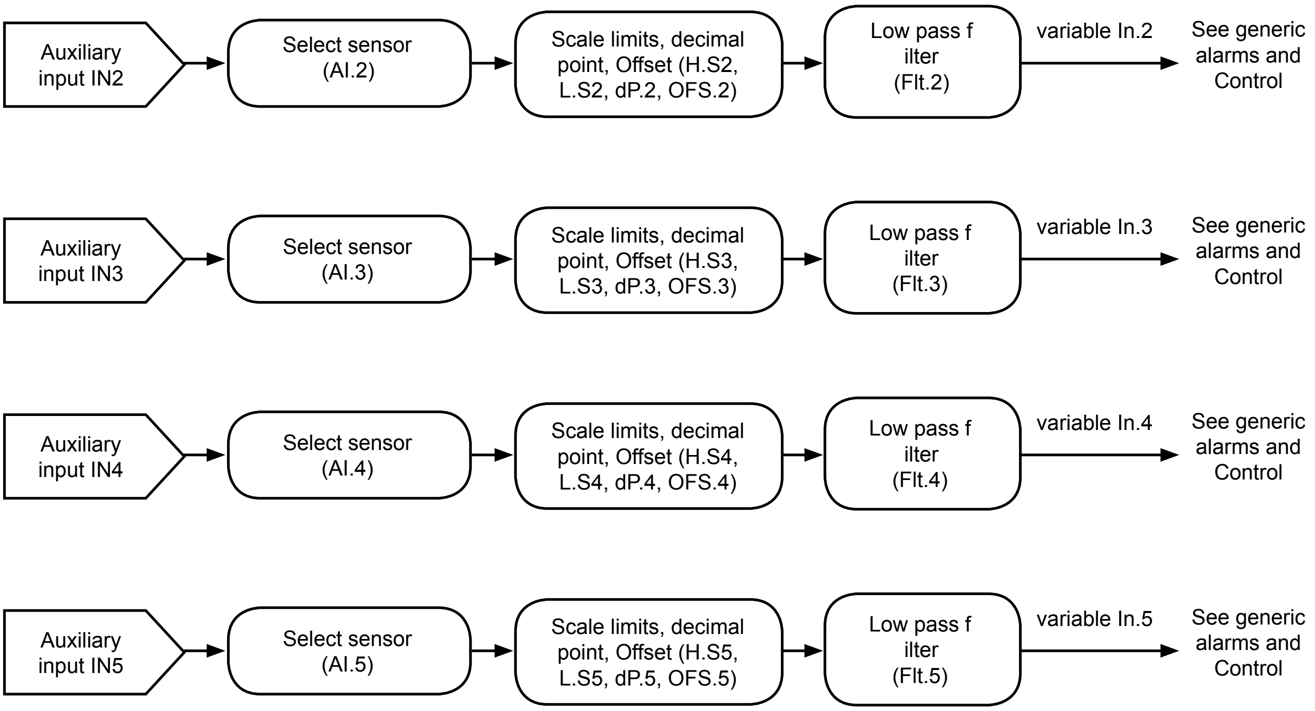
ADVANCED SETTINGS

Input filter

604	FLt.2	R/W	Digital filter for auxiliary input 2	0.0 ... 20.0 sec		0.1
562	FLt.3	R/W	Digital filter for auxiliary input 3	0.0 ... 20.0 sec		0.1
563	FLt.4	R/W	Digital filter for auxiliary input 4	0.0 ... 20.0 sec		0.1
564	FLt.5	R/W	Digital filter for auxiliary input 5	0.0 ... 20.0 sec		0.1

Sets a low pass filter on the auxiliary input, running the average of values read in the specified time interval. If = 0 , excludes the average filter on sampled values.

FUNCTIONAL DIAGRAM



DIGITAL INPUTS

There are always three inputs. Each input can perform various functions based on the setting of the following parameters:

140	dIG.	R/W	Digital input function		0
618	dIG.2	R/W	Digital input 2 function		0

Digital input functions table

		Activation
0	No functions (input off)	
1	MAN/AUTO controller	On leading edge
2	LOC / REM	On leading edge
3	HOLD	On state
4	AL1, ..., AL4 alarms memory reset	On state
5	SP1 / SP2 selection	On leading edge
6	Software on/off	On leading edge
7	None	
8	START / STOP Selftuning	On leading edge (**)
9	START / STOP Autotuning	On leading edge (**)
10	Power_Fault alarms memory reset	On state
11	LBA alarm reset	On state
12	AL1 .. AL4 and Power_Fault alarms reset memory	On state
13	Enable at software ON (*)	
14	Reference calibration of retroaction selected by Hd.6	
15	Calibration threshold alarm HB	

+ 16 for inverse logic input
+ 32 to force logic state 0 (OFF)
+ 48 to force logic state 1 (ON)

(*) For dIG. only
(**) IN dIG. alternative to serial

694	dIG.3	R/W	Digital input 3 function		0

Digital input 3 functions table

0	No functions (input off)
1	PWM input

+ 16 for inverse logic input

Read state

68 bit	STATE of DIGITAL INPUT 1	R	OFF = Digital input 1 off ON = Digital input 1 on
92 bit	STATE of DIGITAL INPUT 2	R	OFF = Digital input 2 off ON = Digital input 2 on
67 bit	STATE of DIGITAL INPUT 3	R	OFF = Digital input 3 off ON = Digital input 3 on

317		R	State of (INPUT_DIG) digital inputs	bit.0 = state INDIG1 bit.1 = state INDIG2 bit.2 = state INDIG3
518	In.PWM	R	PWM input value	0,0...100,0%

Functions related to digital inputs

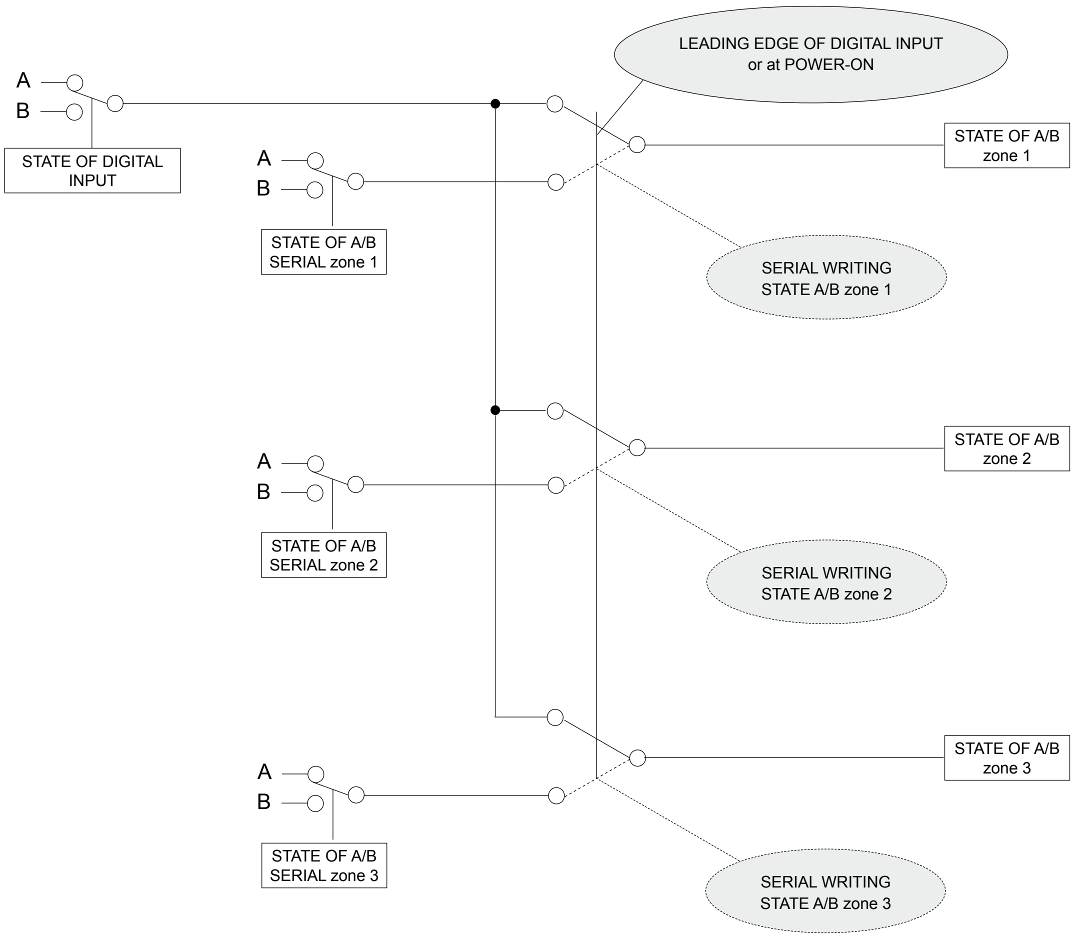
- MAN / AUTO controller	see AUTO/MAN CONTROL
- LOC / REM	see SETTING THE SETPOINT
- HOLD	see HOLD FUNCTION
- Reset memory latch	see GENERIC ALARMS AL1 .. AL4
- Select SP1 / SP2	see SETTINGS - Multiset
- Software OFF / ON	see SOFTWARE SHUTDOWN
- START / STOP Selftuning	see SELFTUNING
- START / STOP Autotuning	see AUTOTUNING
- Calibration of feedback reference	see FEEDBACK
- Calibration of HB alarm setpoint	see HB ALARM

USING A FUNCTION ASSOCIATED WITH DIGITAL INPUT AND VIA SERIAL

At power-on or on the leading edge of digital input 1 or 2, all zones assume the state set by the digital input. For each zone, this state can be changed by writing via serial.
The setting via serial is saved in eeprom (STATUS_W_EEP, address 698).

State A/B	Setting	Address for writing via serial	
	dIG. or dIG.2	Access at 16 bits	Access at 1 bit
AUTO/MAN controller	1	word 305 bit 4	bit 1
LOC/REM setpoint	2	word 305 bit 6	bit 10
SP1/SP2 setpoint	5	word 305 bit 1	bit 75
ON/OFF software	6	word 305 bit 3	bit 11
STOP/START selftuning	8	word 305 bit 2	bit 3
STOP/START autotuning(*) (**)	9	word 305 bit 5	bit 29

(*) continuous or one-shot
(**) only for zone 1 (GFW-M)

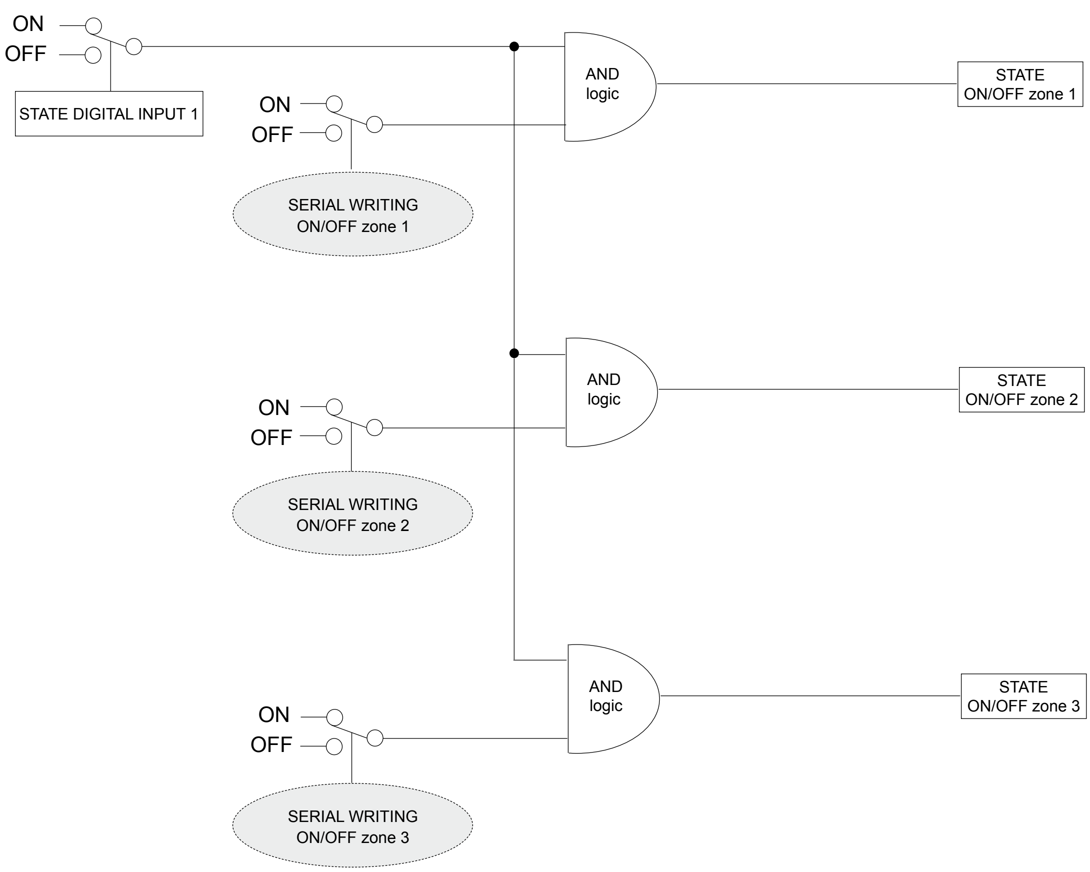


USING A FUNCTION OF DIGITAL INPUT 1 TO ENABLE AT SOFTWARE ON

Software ON can be configured either by enabling a digital input or by writing via serial. Enabling by digital input 1 (**dIG**) is common to all zones, whereas enabling via serial is specific for each individual zone.

The ON/OFF setting via serial is saved in eeprom (STATUS_W_EEP, address 698 bit 3) for resetting of the condition at the next hardware power-on; use parameter P.On.t. to force software always ON or software always OFF at next power-on.

	Setting	Address for writing via serial	
	dIG	Access at 16 bits	Access at 1 bit
ON/OFF software	13	word 305 bit 3	bit 11



GENERIC ALARMS AL1, AL2, AL3 and AL4

Four generic alarms are always available and can perform various functions.
Typically, alarm AL.1 is defined as minimum and AL.2 as maximum.
These alarms are set as follows:

- select the reference variable to be used to monitor the value (parameters A1.r, A2.r, A3.r and A4.r): the origin of the variable can be chosen from the process variable PV (generally linked to the main input), the ammeter input, the voltmeter input, the auxiliary analog input, or the active setpoint.

- set the value of the alarm setpoint (parameters AL.1, AL.2, AL.3 and AL.4).

This value is used for comparison with the reference variable value: it can be absolute or indicate a shift from the variable in case of deviation alarm.

- set the hysteresis value for the alarm (parameters Hy.1, Hy.2, Hy.3 and Hy.4):

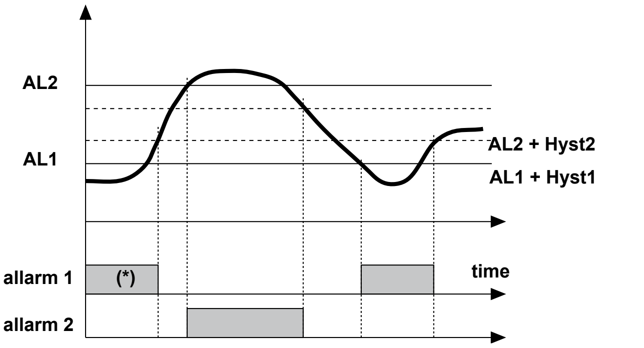
the hysteresis value defines a band for safe re-entry of the alarm condition: without this band, the alarm would be deactivated as soon as the reference variable re-entered the setpoint limits, with the possibility of generating another alarm signal in the presence of oscillations of the reference signal around the setpoint value.

- select alarm type:

- absolute/deviation: if the alarm refers to an absolute value or to another variable (for example, to the setpoint).
- direct/reverse: if the reference variable exceeds the alarm setpoint in the “same direction” as the control action or not. For example, the alarm is direct if the reference variable exceeds the upper setpoint value during heating or assumes values below the lower setpoint during cooling. In the same manner, the alarm is reverse if the reference variable assumes values below the lower setpoint during heating or exceeds the setpoint during cooling.
- normal/symmetrical: if band value is subtracted or added, respectively, to/from the upper and lower limit of the alarm setpoints or indicates a higher and lower band compared to the alarm setpoint.
- with/without disabling at switch-on: if you want to check the reference variable value at system switch-on or wait until the variable enters the control window.
- with/without memory: if the alarm signal persists even when the cause has been eliminated or stops when the variable returns to normal values.

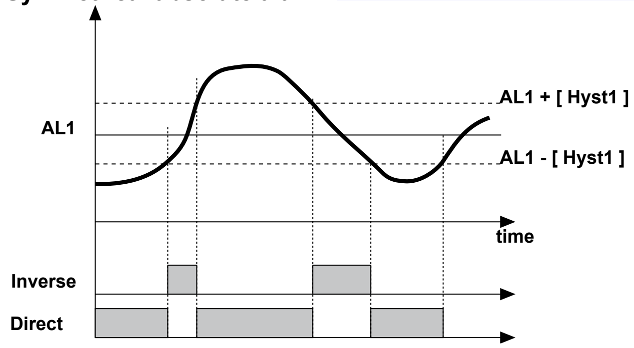
The above concepts are better explained in the following figures:

Normal absolute alarm



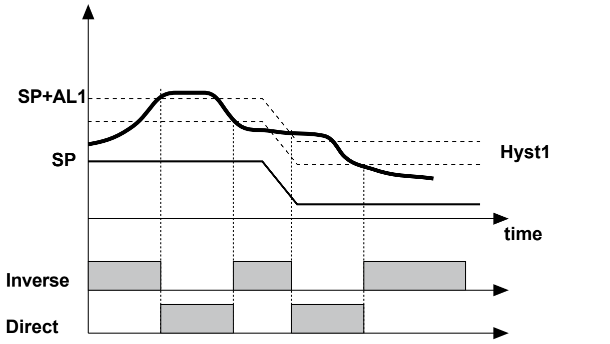
For AL1 reverse absolute alarm (low) with positive Hyst1, AL1 t = 1 (*) = OFF if disabled at switch on
For AL2 direct absolute alarm (high) with negative Hyst2, AL2 t = 0

Symmetrical absolute alarm



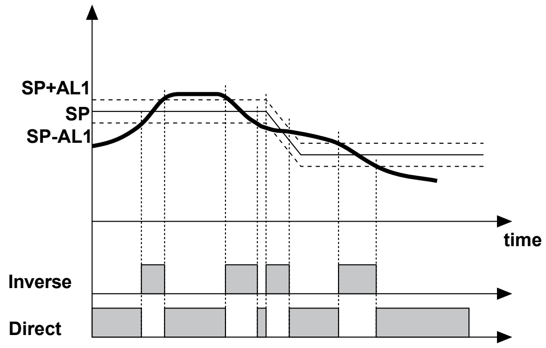
For AL1 = symmetrical inverse absolute alarm with Hyst1, AL1 t = 5
For AL1 = symmetrical direct absolute alarm with Hyst1, AL1 t = 4
Minimum hysteresis = 2 scale points

Deviation alarm



For AL1 = normal inverse deviation alarm with negative Hyst 1, AL1 t = 3
For AL1 = normal direct deviation alarm with negative Hyst 1, AL1 t = 2

Symmetrical deviation alarm



For AL1 = Symmetrical inverse deviation alarm with Hyst 1, AL1 t = 7
For AL1 = Symmetrical direct deviation alarm with Hyst 1, AL1 t = 6

Reference variables

215	A1.r	R/W	Select reference variable alarm 1	Table of alarm reference setpoints	0
216	A2.r	R/W	Select reference variable alarm 2		0
217	A3.r	R/W	Select reference variable alarm 3		0
218	A4.r	R/W	Select reference variable alarm 4		0

Table of alarm reference setpoints

	Variable to be compared	Reference setpoint
0	PV (process variable)	AL
1	in.tA1 (In.tA1 OR In.tA2 OR In.tA3 WITH 3-PHASE LOAD)	AL
2	In.tV1 (In.tV1 OR In.tV2 OR In.tV3 WITH 3-PHASE LOAD)	AL
3	SPA (active setpoint)	AL (absolute only)
4	PV (process variable)	AL [deviation only and referred to SP1 (with multiset function)
5	In.2 auxiliary input	AL
6	In.3 auxiliary input	AL
7	In.4 auxiliary input	AL
8	In.5 auxiliary input	AL
9	In.A analg input	AL
10	In.Pwm PWM input	AL

N.B. for codes 1, 2, 5, 6, 7, 8, 9 and 10 the reference to the alarm is in scale points and not to the decimal point (dP.x)

Alarm setpoints

12 475 - 177	AL.1	R/W	Alarm setpoint 1 (scale points)	-1999...9999 Scale points	-999...999 if alarm symetrical 0...999 if alarm relative and symetrical	500
13 476 - 178	AL.2	R/W	Alarm setpoint 2 (scale points)	-1999...9999 Scale points	-999...999 if alarm symetrical 0...999 if alarm relative and symetrical	100
14 52 - 479	AL.3	R/W	Alarm setpoint 3 (scale points)	-1999...9999 Scale points	-999...999 if alarm symetrical 0...999 if alarm relative and symetrical	700
58 480	AL.4	R/W	Alarm setpoint 4 (scale points)	-1999...9999 Scale points	-999...999 if alarm symetrical 0...999 if alarm relative and symetrical	800

Alarms hysteresis

27 187	HY.1	R/W	Hysteresis for alarm 1	± 999 Scale points	0...999 sec. If +32 in A1.t 0...999 min. If +64 in A1.t	- 1
30 188	HY.2	R/W	Hysteresis for alarm 2	± 999 Scale points	0...999 sec. If +32 in A1.t 0...999 min. If +64 in A1.t	- 1
53 189	HY.3	R/W	Hysteresis for alarm 3	± 999 Scale points	0...999 sec. If +32 in A1.t 0...999 min. If +64 in A1.t	- 1
59	HY.4	R/W	Hysteresis for alarm 4	± 999 Scale points	0...999 sec. If +32 in A1.t 0...999 min. If +64 in A1.t	- 1

Alarm type

406	A1.t	R/W	Alarm type 1	0
407	A2.t	R/W	Alarm type 2	0
408 54	A3.t	R/W	Alarm type 3	0
409	A4.t	R/W	Alarm type 4	0

Table of alarm behaviour

	Direct (high limit) Inverse (low limit)	Absolute Relative to activfe setpoint	Normal Symmetrical (window)
0	direct	absolute	normal
1	inverse	absolute	normal
2	direct	relative	normal
3	inverse	relative	normal
4	direct	absolute	symmetrical
5	inverse	absolute	symmetrical
6	direct	relative	symmetrical
7	inverse	relative	symmetrical

+ 8 to disable at switch-on until first setpoint
+ 16 to enable memory latch
+ 32 Hys becomes delay time for activation of alarm (0...999 sec.) (excluding absolute symmetrical)
+ 64 Hys becomes delay time for activation of alarm (0...999 min.) (excluding absolute symmetrical)
+ 136 to disable at switch-on or at change of setpoint until first setpoint
+ 256 only for alarms with memory and delay time: the delay time becomes a timed hysteresis (with time stopped in case of SBR condition: when SBR condition disappears the delay time starts counting from zero)

46 bit	AL1 direct/inverse	R/W	
47 bit	AL1 absolute/relative	R/W	
48 bit	AL1 normal/symmetrical	R/W	
49 bit	AL1 disabled at switch-on	R/W	
50 bit	AL1 with memory	R/W	
54 bit	AL2 direct/inverse	R/W	
55 bit	AL2 absolute/relative	R/W	
56 bit	AL2 normal/symmetrical	R/W	
57 bit	AL2 disabled at switch-on	R/W	
58 bit	AL2 with memory	R/W	
36 bit	AL3 direct/inverse	R/W	
37 bit	AL3 absolute/relative	R/W	
38 bit	AL3 normal/symmetrical	R/W	
39 bit	AL3 disabled at switch-on	R/W	
40 bit	AL3 with memory	R/W	
70 bit	AL4 direct/inverse	R/W	
71 bit	AL4 absolute/relative	R/W	
72 bit	AL4 normal/symmetrical	R/W	
73 bit	AL4 disabled at switch-on	R/W	
74 bit	AL4 with memory	R/W	

Enable alarms

195*	AL.n	R/W	Select number of enabled alarms	*Table of enabled alarms*	3 zone1	0 zone2	0 zone3

	Alarm 1	Alarm 2	Alarm 3	Alarm 4
0	disabled	disabled	disabled	disabled
1	enabled	disabled	disabled	disabled
2	disabled	enabled	disabled	disabled
3	enabled	enabled	disabled	disabled
4	disabled	disabled	enabled	disabled
5	enabled	disabled	enabled	disabled
6	disabled	enabled	enabled	disabled
7	enabled	enabled	enabled	disabled
8	disabled	disabled	disabled	enabled
9	enabled	disabled	disabled	enabled
10	disabled	enabled	disabled	enabled
11	enabled	enabled	disabled	enabled
12	disabled	disabled	enabled	enabled
13	enabled	disabled	enabled	enabled
14	disabled	enabled	enabled	enabled
15	enabled	enabled	enabled	enabled

+ 16 to enable HB alarm
+ 32 to enable LBA alarm

(*) For zone 2 (GFW-E1) and zona 3 (GFW-E2), AL.n defines enabling of only the HB alarm in mono-phase configuration.

Reset memory latch

140	dIG.	R/W	Digital input function	*Digital input functions table*		0
618	dIG.2	R/W	Digital input function 2			0

0	No function (input off)
1	MAN /AUTO controller
2	LOC / REM
3	HOLD
4	AL1, ..., AL4 latch alarm reset
5	SP1 / SP2 selection
6	Software on/off
7	None
8	START / STOP Selftuning
9	START / STOP Autotuning
10	Power_Fault latch alarm reset
11	LBA alarm reset
12	AL1 .. AL4 and Power_Fault latch alarm reset
13	Enable at software ON (*)
14	Reference calibration of retroaction selected by Hd.6
15	Calibration threshold alarm HB

+ 16 for inverse logic input
+ 32 to force logic state 0 (OFF)
+ 48 to force logic state 1 (ON)

(*) For dIG. only

79 bit	Reset memory latch	R/W	

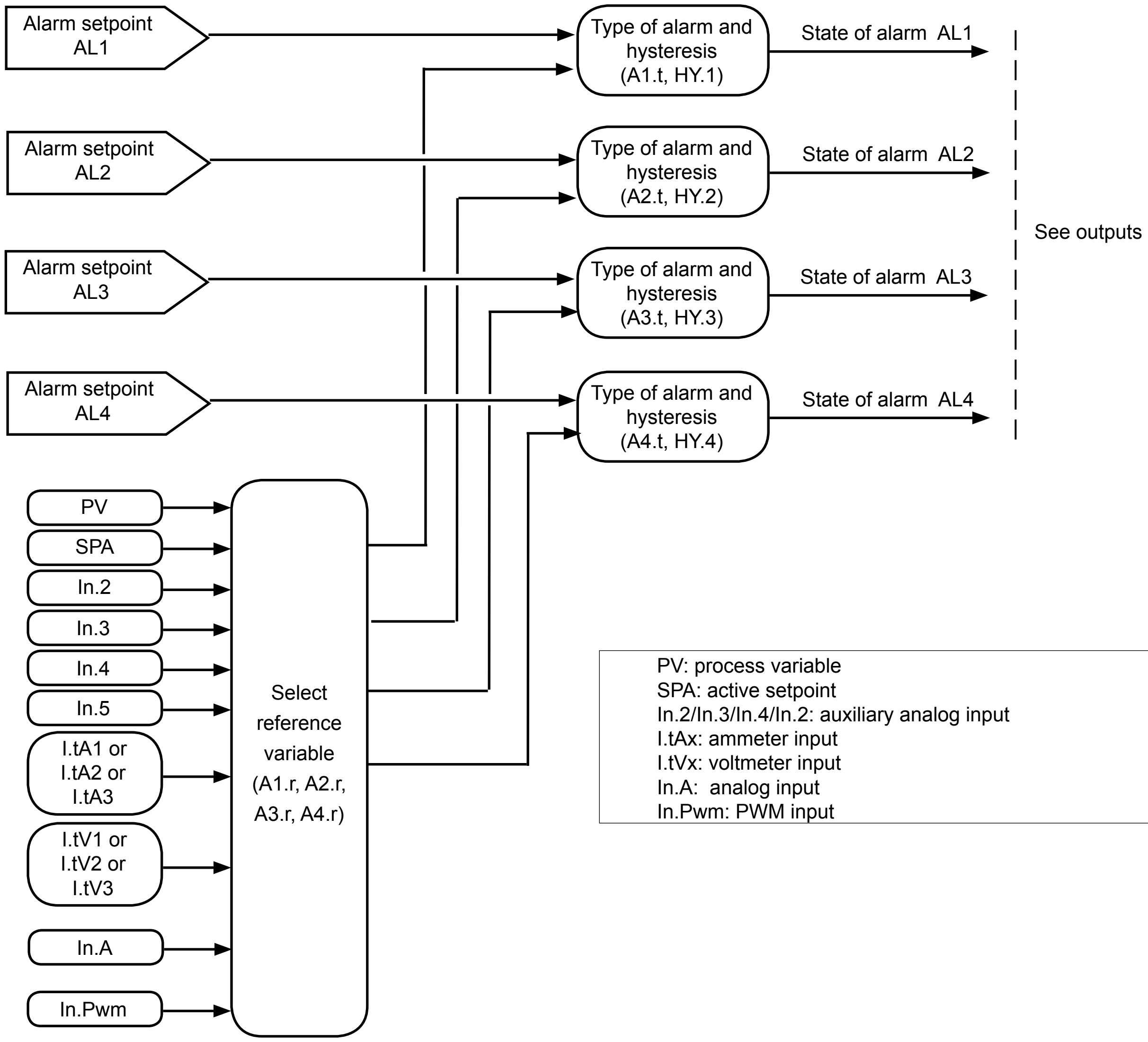
Read state

4 bit	STATE of ALARM 1	R	OFF = Alarm off ON = Alarm on
5 bit	STATE of ALARM 2	R	OFF = Alarm off ON = Alarm on
62 bit	STATE of ALARM 3	R	OFF = Alarm off ON = Alarm on
69 bit	STATE of ALARM 4	R	OFF = Alarm off ON = Alarm on
318*		R	State of alarms ALSTATE IRQ

States of alarm table

bit	
0	State AL.1
1	State AL.2
2	State AL.3
3	State AL.4
4	State AL.HB (if 3-phase or phase 1/2/3) or Power Fault
5	State AL.HB PHASE 1 (if 3-phase)
6	State AL.HB PHASE 2 (if 3-phase)
7	State AL.HB PHASE 3 (if 3-phase)

FUNCTIONAL DIAGRAM



PV: process variable
SPA: active setpoint
In.2/In.3/In.4/In.2: auxiliary analog input
I.tAx: ammeter input
I.tVx: voltmeter input
In.A: analog input
In.Pwm: PWM input

LBA ALARM (Loop Break Alarm)

This alarm identifies incorrect functioning of the control loop due to a possible load break or to a short circuited or reversed probe.

With the alarm enabled (parameter AL.n), the instrument checks that in condition of maximum power delivered for a settable time (Lb.t) greater than zero, the value of the process variable increases in heating or decreases in cooling: if this does not happen, the LBA alarm trips. In these conditions, power is limited to value (Lb.P).

The alarm condition resets if the temperature increases in heating or decreases in cooling.

Enable alarm

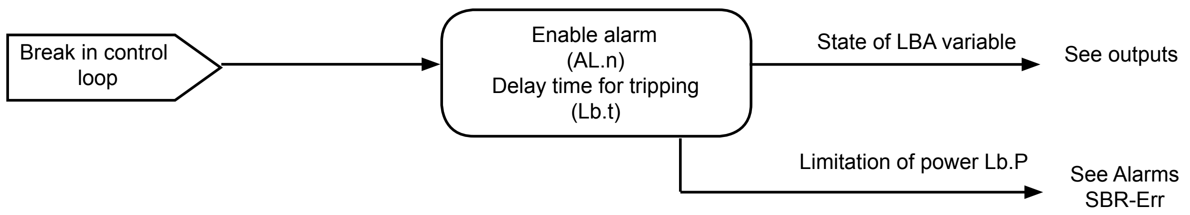
195*	AL.n	R/W	Select number of enabled alarms	*see: Table of enabled alarms*	3 zone1	0 zone2	0 zone3
44	Lb.t	R/W	Delay time for tripping of LBA alarm	0,0 ... 500,0 min	If Lb.t = 0, the LBA alarm is disabled	30,0	
119	Lb.P	R / W	Limitation of power delivered in presence of LBA alarm	-100,0 ..100,0 %		25,0	

81 bit	Reset LBA alarm	R/W	

Read state

8 bit	STATE of LBA ALARM	R	OFF = LBA alarm off ON = LBA alarm on

FUNCTIONAL DIAGRAM



HB ALARM (Heater Break Alarm)

This type of alarm identifies load break or interruption by measure the current delivered by means of a current transformer.
The following three fault situations may occur:

- delivered current is lower than nominal current: this is the most common situation, and indicates that a load element is breaking.

- delivered current is higher than nominal current: this situation occurs, for example, due to partial short circuits of load elements.

- delivered current remains significant even during periods in which it should be zero: this situation occurs in the presence of pilot circuits for the short-circuited load or due to relay contacts soldered together. In these cases, prompt action is very important to prevent greater damage to the load and/or to the pilot circuits.

In standard configuration, output SSR is associated to heating control in zone 1, obtained by modulating electrical power with the ON/OFF control based on the set cycle time.
The current read performed during the ON phase identifies an anomalous shift from the rated value due to a load break (first two fault situations described above), while the current read performed during the OFF phase identifies a break in the control relay, with consequent output always active (third fault situation).
The alarm is enabled by means of parameter AL.n; select the type of function you want by means of parameter Hb.F:
Hb.F=0: alarm activates if the current load value is below the setpoint value set in A.Hbx while the SSR control output is ON.
Hb.F=1: alarm activates if the current load value is above the setpoint value set in A.Hbx while the SSR control output is OFF.
Hb.F=2: alarm activates by combining functions 0 and 1, considering the setpoint of function 1 as 12% of the ammeter full scale defined in H.tAx.
Hb.F=3 or **Hb.F=7** (continuous alarm): alarm activates due to a load current value below the setpoint value set in A.Hbx; this alarm does not refer to the cycle time and is disabled if the heating (cooling) output value is below 3%.

Setting A.Hbx = 0 disables both types of HB alarm by forcing deactivation of the alarm state.
The alarm resets automatically if its cause is eliminated.

An additional configuration parameter for each zone, related to the HB alarm is:
Hb.t = delay time for activation of HB alarm, understood as the sum of times for which the alarm is considered active.
For example, with:
- Hb.F = 0 (alarm active with current below setpoint value),
- Hb.t = 60 sec and cycle time of control output = 10 sec,
- power delivered al 60%,

the alarm will activate after 100 sec (output ON for 6 sec each cycle);
if power is delivered at 100%, the alarm will activate after 60 sec.
If the alarm deactivates during this interval, the time sum is reset.

The delay time set in Hb.t must exceed the cycle time of the SSR output.
If zone 1 has a 3-phase load, you can set three different setpoints for the HB alarm:
A.Hb1= alarm setpoint for line L1
A.Hb2= alarm setpoint for line L2
A.Hb3= alarm setpoint for line L3

FUNCTION: HB ALARM SETPOINT SELF-LEARNING

This function permits self-learning of the alarm setpoint.
To use this function, you first have to set parameter Hb.P, which defines the percentage of current compared to rated load below which the alarm trips.
The function can be activated via control from serial line, digital input (see parameter dIG or dIG.2) or by key.
When the Teach-in function is activated in modes ZC, BF and HSC, the RMS current value in conduction ON multiplied by parameter Hb.P determines the HB alarm setpoint.
When the Teach-in function is activated in mode PA, the existing RMS current value is shown at 100% of power, which, multiplied by parameter Hb.P, determines the HB alarm setpoint.

For IR lamps (see parameter Hd.5 option +128), the function activates automatic reading of the power/current curve useful for determining the HB alarm setpoint.
Automatic reading of the power/current curve takes place with the following sequence:
- softstart at maximum power (default 100%), 5 sec. delay
- reduction of power to 50%, 30%, 20%, 15%, 10%, 5%, 3%, 2%, 1%, between every value 5 sec. delay
- return to normal operation.

Maximum conduction value in this phase can be limited by means of the PS.Hi parameter.
If requested, MUST be activated only with Hd.6=0 (the required Hd.6 value can be set only after calibration).

Enable alarm

195*	AL.n	R/W	Select number of enabled alarms	*See: Table of enable alarms*	3 zone1	0 zone2	0 zone3
57*	Hb.F	R/W	HB alarm functions	*Table of HB alarm functions*	0 zone1	0 zone2	0 zone3

Default:
SINGLE-PHASE LOAD: each A.HbX refers to its respective phase.
2-PHASE LOAD: single reference setpoint A.Hb1 and OR between phases 1, 2 and phases 3, 4.
3-PHASE LOAD: single reference setpoint A.Hb1 and OR among phases 1, 2 and 3.

+ 8 HB reverse alarm
+ 16 relates to single setpoints and singled phases WITH 3-PHASE LOAD

Val.	Description of functions
0	Relay, logic output: alarm active at a load current value below set point for control output ON time.
1	Relay, logic output: alarm active at a load current value above set point for control output OFF time.
2	Alarm active if one of functions 0 and 1 is active (OR logic between functions 0 and 1) (*)
3	Continuous heating alarm
7	Continuous cooling alarm

(*) minimum setpoint is set at 12% of ammeter full scale

56*	Hb.t	R/W	**Delay time for activation of HB alarm**	0 ... 999 sec	The value must exceed the cycle time of the output to which the HB alarm is associated.	5 zone1	5 zone2	5 zone3
112* bit	Calibration HB alarm setpoint for zone	R/W	OFF = Calibration not enabled ON = Calibration enabled	NB: In case of 3-phase load, you can set a different value for parameter A.Hb1, A.Hb2, A.Hb3 for each zone (ex.: to control an unbalanced 3-phase load).				

Alarm setpoints

55*	A.Hb 1	R/W	HB alarm setpoint (scale points ammeter input - Phase 1)		10,0 zone1	10,0 zone2	10,0 zone3
502	A.Hb2	R/W	HB alarm setpoint (scale points ammeter input - Phase 2)	With 3-phase load	10,0		
503	A.Hb3	R/W	HB alarm setpoint (scale points ammeter input - Phase 3)	With 3-phase load	10,0		
737*	Hb.P	R/W	Percentage HB alarm setpoint of current read in HB calibration	0,0 ... 100,0%	80,0 zone1	80,0 zone2	80,0 zone3
742*	Hb.tA	R/W	CT read in HB calibration		0,0 zone1	0,0 zone2	0,0 zone3
452*	Hb.tV	R/W	TV read in HB calibration		0,0 zone1	0,0 zone2	0,0 zone3
743*	Hb.Pw	R/W	Ou.P power in calibration		0,0 zone1	0,0 zone2	0,0 zone3
758*	Ir.tA.0	R/W	HB Calibration with IR lamp: current at 100% conduction		0,0 zone1	0,0 zone2	0,0 zone3
759*	Ir.tA.1	R/W	HB Calibration with IR lamp: current at 50% conduction		0,0 zone1	0,0 zone2	0,0 zone3
760*	Ir.tA.2	R/W	HB Calibration with IR lamp: current at 30% conduction		0,0 zone1	0,0 zone2	0,0 zone3
761*	Ir.tA.3	R/W	HB Calibration with IR lamp: current at 20% conduction		0,0 zone1	0,0 zone2	0,0 zone3
767*	Ir.tA.4	R/W	HB Calibration with IR lamp current at 15% conduction		0,0 zone1	0,0 zone2	0,0 zone3
768*	Ir.tA.5	R/W	HB Calibration with IR lamp current at 10% conduction		0,0 zone1	0,0 zone2	0,0 zone3
769*	Ir.tA.6	R/W	HB Calibration with IR lamp (only in mode PA): current at 5% conduction		0,0 zone1	0,0 zone2	0,0 zone3
382*	Ir.tA.7	R/W	HB Calibration with IR lamp (only in mode PA): current at 3% conduction		0,0 zone1	0,0 zone2	0,0 zone3
383*	Ir.tA.8	R/W	HB Calibration with IR lamp (only in mode PA): current at 2% conduction		0,0 zone1	0,0 zone2	0,0 zone3
384*	Ir.tA.9	R/W	HB Calibration with IR lamp (only in mode PA): current at 1% conduction		0,0 zone1	0,0 zone2	0,0 zone3

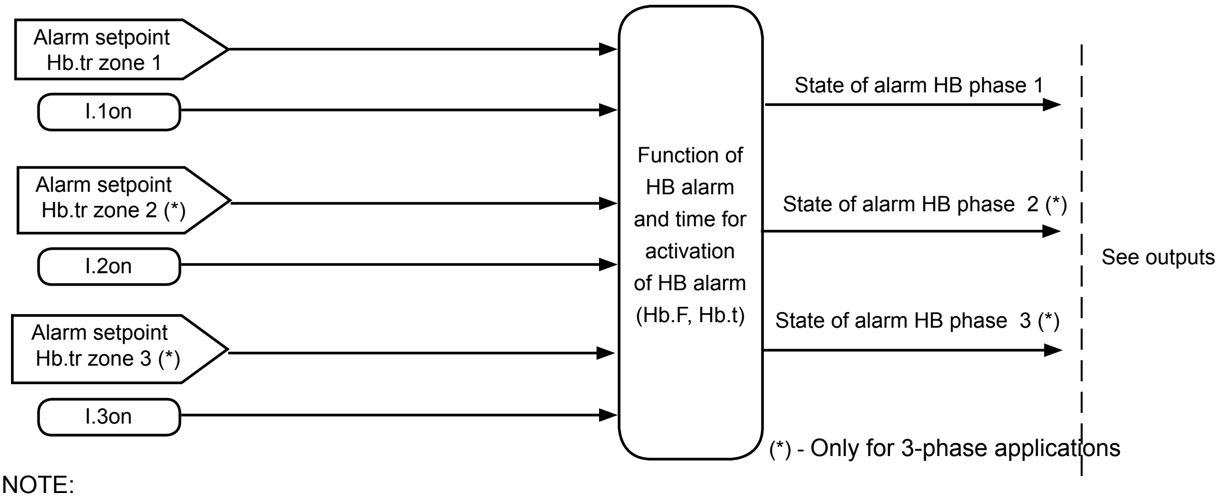
445*	Ir.tV.0	R/W	HB Calibration with IR lamp: voltage at 100% conduction		0,0 zone1	0,0 zone2	0,0 zone3
446*	Ir.tV.1	R/W	HB Calibration with IR lamp: voltage at 50% conduction		0,0 zone1	0,0 zone2	0,0 zone3
447*	Ir.tV.2	R/W	HB Calibration with IR lamp: voltage at 30% conduction		0,0 zone1	0,0 zone2	0,0 zone3
448*	Ir.tV.3	R/W	HB Calibration with IR lamp: voltage at 20% conduction		0,0 zone1	0,0 zone2	0,0 zone3
449*	Ir.tV.4	R/W	HB Calibration with IR lamp: voltage at 15% conduction		0,0 zone1	0,0 zone2	0,0 zone3
450*	Ir.tV.5	R/W	HB Calibration with IR lamp: voltage at 10% conduction		0,0 zone1	0,0 zone2	0,0 zone3
451*	Ir.tV.6	R/W	HB Calibration with IR lamp (only in mode PA): voltage at 5% conduction		0,0 zone1	0,0 zone2	0,0 zone3
390*	Ir.tV.7	R/W	HB Calibration with IR lamp (only in mode PA): voltage at 3% conduction		0,0 zone1	0,0 zone2	0,0 zone3
391*	Ir.tV.8	R/W	HB Calibration with IR lamp (only in mode PA): voltage at 2% conduction		0,0 zone1	0,0 zone2	0,0 zone3
392*	Ir.tV.9	R/W	HB Calibration with IR lamp (only in mode PA): voltage at 1% conduction		0,0 zone1	0,0 zone2	0,0 zone3

Read state

744*	Hb.tr	R	HB alarm setpoint as function of power on load	
26* bit	HB ALARM STATE OR POWER_FAULT	R	OFF = Alarm off ON = Alarm on	
76* bit	State of HB alarm phase 1TA	R	OFF = Alarm off ON = Alarm on	
77 bit	State of HB alarm phase 2TA	R	OFF = Alarm off ON = Alarm on	
78 bit	State of HB alarm phase 3TA	R	OFF = Alarm off ON = Alarm on	
504		R	HB alarm states ALSTATE_HB (for 3-phase loads)	*Table of HB alarm states* bit 0 HB TA2 time ON 1 HB TA2 time OFF 2 HB alarm TA2 3 HB TA3 time ON 4 HB TA3 time OFF 5 HB alarm TA3
512*		R	States of alarm ALSTATE (for single-phase loads)	*Table of alarm states ALSTATE* bit 4 HB alarm time ON 5 HB alarm time OFF 6 HB alarm
318*		R	State of alarms ALSTATE IRQ	*States of alarm table* bit 0 State AL.1 1 State AL.2 2 State AL.3 3 State AL.4 4 State AL.HB (if 3-phase or phase 1/2/3) or Power Fault 5 State AL.HB PHASE 1 (if 3-phase) 6 State AL.HB PHASE 2 (if 3-phase) 7 State AL.HB PHASE 3 (if 3-phase)

FUNCTIONAL DIAGRAM

HB Alarm

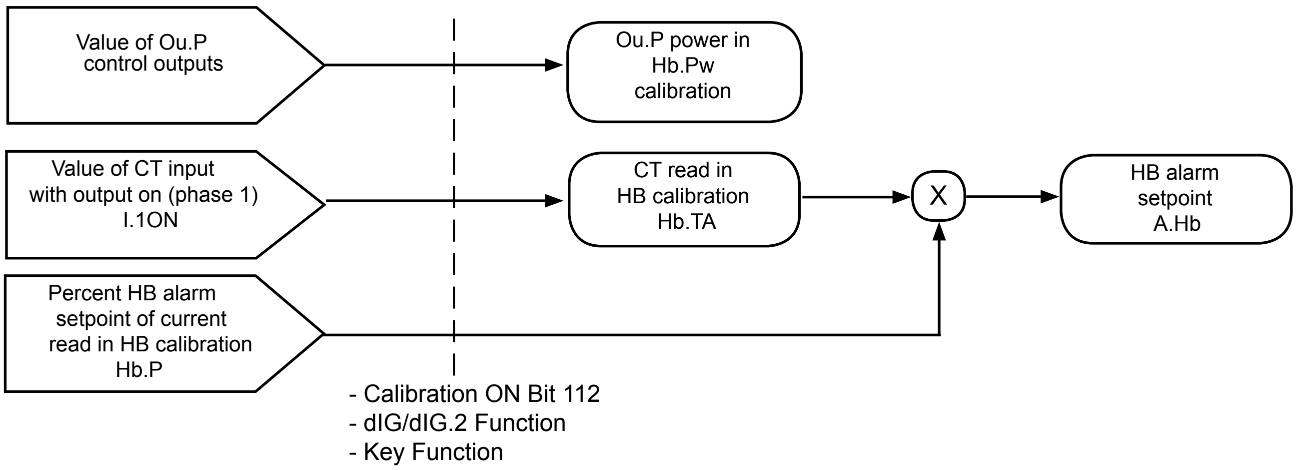


NOTE:
the value of setpoint Hb.tr for the HB alarm is calculated in two different ways, depending on the selected function mode:

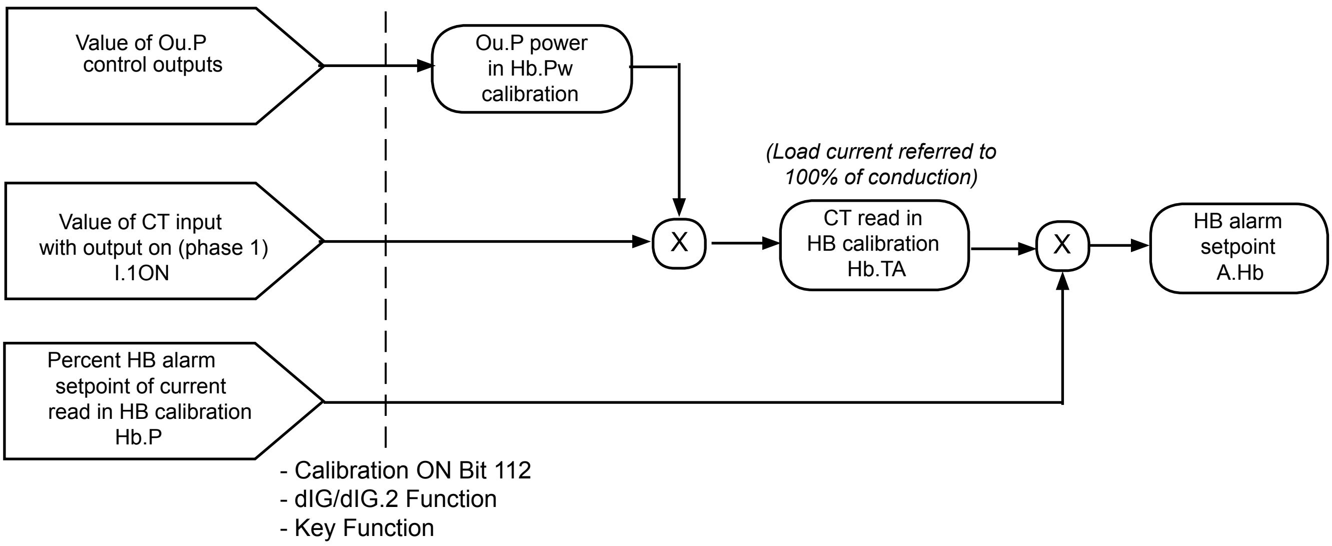
if ZC, BF, HSC mode: .... Hb.tr = A.Hb

if PA mode .... Hb.tr = A.Hb * $\sqrt{(Ou.P)}$

HB Calibration in modes ZC - BF - HSC



HB Calibration in mode PA



SBR - ERR ALARM (probe in short or connection error)

This alarm is always ON and cannot be deactivated. It controls correct functioning of the probe connected to the main input.

In case of broken probe:

- the state of alarms AL1, AL2, AL3 and AL4 is set based on the value of parameter rEL;
- control power control is set to the value of parameter FAP.

Identification of the type of break detected on the main input is contained in Err.

Enable alarm

229	rEL	R/W	**Fault action (definition of state in case of broken probe) Sbr, Err Only for main input**	*Table of probe alarm settings*	0

	Alarm 1	Alarm 2	Alarm 3	Alarm 4
0	OFF	OFF	OFF	OFF
1	ON	OFF	OFF	OFF
2	OFF	ON	OFF	OFF
3	ON	ON	OFF	OFF
4	OFF	OFF	ON	OFF
5	ON	OFF	ON	OFF
6	OFF	ON	ON	OFF
7	ON	ON	ON	OFF
8	OFF	OFF	OFF	ON
9	ON	OFF	OFF	ON
10	OFF	ON	OFF	ON
11	ON	ON	OFF	ON
12	OFF	OFF	ON	ON
13	ON	OFF	ON	ON
14	OFF	ON	ON	ON
15	ON	ON	ON	ON

228	FAP	R/W	Fault action power (supplied in conditions of broken probe)	-100,0 ..100,0 %	*see: OTHER FUNCTION*	0,0

Read state

85	Err	R	*Error code in self-diagnostics of main input*	*See: Table of error codes*
9 bit	STATE OF INPUT IN SBR	R	OFF = - ON = Input in SBR	

660*	hd.2	R/W	*Enable POWER_FAULT alarms*	*Table of Power Fault alarms*	0 zone1	0 zone2	0 zone3

	SSR_SHORT	NO_VOLTAGE	NO_CURRENT
0			
1	X		
2		X	
3	X	X	
4			
5	X		
6		X	
7	X	X	
8			X
9	X		X
10		X	X
11	X	X	X
12			X
13	X		X
14		X	X
15	X	X	X

+ 32 alarms with memory
+ 64 disables current polarity check (inductive loads only)
+ 136 enables partial load mode
(128+8) for three-phase delta configuration without neutral, with or without transformer Y/Y or Δ /Δ)
+ 264 enables partial load mode
(256+8) for three-phase delta configuration without neutral, with or without transformer Δ/Y or Y/Δ)

661	dG.t	R/W	Refresh rate SSR_SHORT The alarm activates after 3 seconds.	1...999 sec		10		
662*	dG.F	R/W	Time filter for NO_VOLTAGE, SSR_OPEN and NO_CURRENT alarms	0...99 sec	Set a value not less than cycle time	10 zone1	10 zone2	10 zone3
105* bit	Reset SSR_SHORT / NO_VOLTAGE / NO_CURRENT alarms	R/W						

Read state

96* bit	State of alarm SSR_SHORT phase 1	R	OFF = LBA alarm off ON = LBA alarm on	
97 bit	State of alarm SSR_SHORT phase 2	R	OFF = LBA alarm off ON = LBA alarm on	with 3-phase load
98 bit	State of alarm SSR_SHORT phase 3	R	OFF = LBA alarm off ON = LBA alarm on	with 3-phase load
99* bit	State of alarm NO_VOLTAGE phase 1	R	OFF = LBA alarm off ON = LBA alarm on	
100 bit	State of alarm NO_VOLTAGE phase 2	R	OFF = LBA alarm off ON = LBA alarm on	with 3-phase load
101 bit	State of alarm NO_VOLTAGE phase 3	R	OFF = LBA alarm off ON = LBA alarm on	with 3-phase load
102* bit	State of alarm NO_CURRENT phase 1	R	OFF = LBA alarm off ON = LBA alarm on	
103 bit	State of alarm NO_CURRENT phase 2	R	OFF = LBA alarm off ON = LBA alarm on	with 3-phase load
104 bit	State of alarm NO_CURRENT phase 3	R	OFF = LBA alarm off ON = LBA alarm on	with 3-phase load

Overheat alarm

Each power module has one temperature sensor for the internal heat sink and two additional temperature sensors connected to the LINE and LOAD terminals.
Temperature levels are shown in variables INNTC_SSR, INNTC_LINE and INNTC_LOAD.
The over_heat alarm trips when at least one of the temperatures exceeds a set threshold.
This condition may be caused by obstructed ventilation slits or by a stopped cooling fan.
With the over_heat alarm active, the control disables control outputs OUT1, OUT2 and OUT3.
There is an additional maximum temperature protection that hardware disables the SSR controls.

655*		R	INNTC_SSR	10,0 ....120,0 °C	Overheat alarm
534*		R	INNTC_LINE	10,0 ....120,0 °C	Overheat alarm
535*		R	INNTC_LOAD	10,0 ....120,0 °C	Overheat alarm

FUSE_OPEN AND SHORT_CIRCUIT_CURRENT ALARMS

The FUSE_OPEN alarm trips when the (optional) internal high-speed fuse opens or when the (optional) electronic fuse switches off.

The SHORT_CIRCUIT_CURRENT alarm trips when peak current on the load exceeds the maximum limit (corresponding to twice the rating) during the softstart ramp or at first power-on (with softstart ramp disabled).

If configured (Fr.n other than zero), the device restarts automatically in softstart for a maximum of Fr.n attempts, beyond which it remains deactivated while awaiting manual reset with front panel key BUT or with the control via serial (bit 109).

456	Fr.n	R/W	*Number of restarts in case of FUSE_OPEN / SHORT_CIRCUIT_CURRENT*		0
109* bit	RESET FUSE_OPEN /SHORT_CIRCUIT_CURRENT ALARMS	R/W	OFF = - ON = Reset FUSE_OPEN / SHORT_CIRCUIT_CURRENT alarms		

The restart function is available on models:
- with Electronic Fuse option from V.2.00
- without Electronic Fuse option from V.2.02

Read state

634*		R	State 4 (STATUS4)	Table State 4

ELECTRONIC FUSE OPTION

The electronic fuse avoids the use of a high-speed fuse to protect the controller.
In case of a short circuit on the load, the electronic fuse switches off immediately and the relative FUSE_OPEN alarm activates.

- The electronic fuse DOES NOT replace any of the safeties on the system (such as magnetothermic switches, delay fuses, etc.).

- The electronic fuse protects the controller (and therefore also the load) by replacing the high-speed fuse needed to protect the control SCRs against faults (without creating any additional cost to replace the fuse and reducing machine downtime).

- The electronic fuse has 2 function states:

- Normal (On-Off control of load power)

- Fuse-Open: GFW is open (a short occurred during normal operation).

OUTPUTS

The modular power controller has high flexibility in the assignment of functions to the physical outputs. As a result, the instrument can be used in sophisticated applications.

A function is assigned to each physical output in two steps: first assign the function to one of internal reference signals rL.1 .. rL.6, and then attribute the reference signal to parameters out.1 .. out.10 (corresponding to physical outputs OUT1 .. OUT10).

In standard configuration, physical outputs Out1, Out2, Out3 perform the heating control function (Heat) for zone 1, zone 2, and zone 3, respectively; value 0 (function HEAT) is assigned to reference signals rL.1 in each zone, and the following values to the output parameters: out.1=1 (output rL.1 zone 1), out.2=2 (output rL.1 zone 2), out.3=3 (output rL.1 zone 3).

Physical outputs Out5, Out6, Out7, Out8 are optional, and the type (relay, logic, continuous or triac) is defined by the order code. In standard configuration, these outputs perform the cooling control function (Cool) for zone 1, zone 2, and zone 3, respectively. In this configuration, value 1 (function COOL) is assigned to reference signals rL.2 in each zone, and the following values to the output parameters: out.5=5 (output rL.2 zone 1), out.6=6 (output rL.2 zone 2), out.7=7 (output rL.2 zone 3).

Relay outputs Out9 and Out10 are always present, programmable by means of parameters out.9 and out.10, to which available alarm signal functions are assigned by means of the four reference signals rL.3, rL.4, rL.5, rL.6 in each zone.

Standard configuration has the following assignments:

- reference signals: rL.3=2 (function AL1), rL.4=3 (function AL2), rL.5=4 (function AL3) and rL.6=5 (function AL.HB or POWER_FAULT with HB alarm).
- output parameters: out.9 =17 and out.10 =18.

In this way, the state of output physical Out9 is given by the logic OR of AL1, AL3 in each zone, and the state of output Out10 is given by the logic AND of AL2, AL.HB in each zone.

Each output can always be disabled by setting parameter out.x = 0.

The state of outputs Out1,...,Out10 can be acquired by serial communication by means of bit variables.

The following additional configuration parameters are related to the outputs:

Ct.1 = cycle time for output rL.1 for heating control (Heat)	*(see: SETTINGS)*
Ct.2 = cycle time for output rL.2 for cooling control (Cool)	*(see: SETTINGS)*
rEL = alarm states AL1, AL2, AL3, AL4 in case of broken probe, Err, Sbr	*(see: GENERIC ALARMS)*

ALLOCATION OF REFERENCE SIGNALS

160*	rL.1	R/W	Allocation of reference signal	0 zona1	0 zona2	0 zona3
163*	rL.2	R/W	Allocation of reference signal	1 zona1	1 zona2	1 zona3

Table of reference signals

	Function	
0	HEAT (heating control output) / in case of continuous output 0...20mA / 0...10V	
1	COOL (cooling control output) / in case of continuous output 0...20mA / 0...10V	
2	AL1 - alarm 1	(*)
3	AL2 - alarm 2	(*)
4	AL3 - alarm 3	(*)
5	AL.HB or POWER_FAULT with HB alarm (TA1 OR TA2 OR TA3)	
6	LBA - LBA alarm	(*)
7	IN1 – repetition of logic input DIG1	
8	AL4 - alarm 4	(*)
9	AL1 or AL2	(*)
10	AL1 or AL2 or AL3	(*)
11	AL1 or AL2 or AL3 or AL4	(*)
12	AL1 and AL2	(*)
13	AL1 and AL2 and AL3	(*)
14	AL1 and AL2 and AL3 and AL4	(*)
15	AL1 or AL.HB or POWER_FAULT with HB alarm (TA1 OR TA2 OR TA3)	(*)
16	AL1 or AL2 or (AL.HB or POWER_FAULT) with HB alarm (TA1 OR TA2 OR TA3)	(*)
17	AL1 and (AL.HB or POWER_FAULT) with HB alarm (TA1 OR TA2 OR TA3)	(*)
18	AL1 and AL2 and (AL.HB or POWER_FAULT) with HB alarm (TA1 OR TA2 OR TA3)	(*)
19	AL.HB - HB alarm (TA2)	
20	AL.HB - HB alarm (TA3)	
21	Setpoint power alarm	(*)
22	AL.HB - HB alarm (TA1)	
23	POWER_FAULT	
24	IN2 - repetition of logic input DIG2	
64	HEAT (heating control output) with fast cycle time 0.1 ... 20.0sec. / in case of continuous output 4...20mA / 2...10V	
65	COOL (cooling control output) with fast cycle time 0.1 ... 20.0sec. / in case of continuous output 4...20mA / 2...10V	

+ 32 for logic level denied in output
+ 128 to force output to zero
NOTE: continuous COOL OUTPUTS can be assigned codes 0, 1, 64 and 65 only, with cycle time fixed at 100 ms

(*) only for zone 1 (GFW-M)

NOTE: Parameters rL.1, ..., rL.6 for each zone can be considered as internal states.
Ex.: To assign alarm AL1 to physical output OUT5, assign rL.1-Zone1=2 (AL1-alarm 1) and than assign parameter out.5=1 (rL.1-Zone1)

166*	rL.3	R/W	Allocation of reference signal	see Function table	2 zone1 / 2 zone2 / 2 zone3
170*	rL.4	R/W	Allocation of reference signal	see Function table	35 zone1 / 35 zone2 / 35 zone3
171*	rL.5	R/W	Allocation of reference signal	see Function table	4 zone1 / 4 zone2 / 4 zone3
172*	rL.6	R/W	Allocation of reference signal	see Function table	160 zone1 / 160 zone2 / 160 zone3

	Function	
2	AL1 - alarm 1	(*)
3	AL2 - alarm 2	(*)
4	AL3 - alarm 3	(*)
5	AL.HB or POWER_FAULT with HB alarm (TA1 OR TA2 OR TA3)	
6	LBA - LBA alarm	(*)
7	IN1 - repetition of logic input INDIG1	
8	AL4 - alarm 4	(*)
9	AL1 or AL2	(*)
10	AL1 or AL2 or AL3	(*)
11	AL1or AL2 or AL3 or AL4	(*)
12	AL1 and AL2	(*)
13	AL1 and AL2 and AL3	(*)
14	AL1 and AL2 and AL3 and AL4	(*)
15	AL1 or AL.HB or POWER_FAULT with HB alarm (TA1 OR TA2 OR TA3)	(*)
16	AL1 or AL2 or (AL.HB or POWER_FAULT) with HB alarm (TA1 OR TA2 OR TA3)	(*)
17	AL1 and (AL.HB or POWER_FAULT) with HB alarm (TA1 OR TA2 OR TA3)	(*)
18	AL1 and AL2 and (AL.HB or POWERFAULT) with HB alarm (TA1 OR TA2 OR TA3)	(*)
19	AL.HB - HB alarm (TA2)	
20	AL.HB - HB alarm (TA3)	
21	Setpoint power alarm	(*)
22	AL.HB - HB alarm (TA1)	
23	POWER_FAULT	
24	IN2 - repetition of logic input INDIG2	

+ 32 for denied logic level at output
+ 128 to force output to zero

(*) state definite in zone 1 (GFW-M)

152* 9	Ct.1	R/W	OUT 1 (Heat) cycle time	1 ...200 sec (0,1 ...20,0 sec)	Set 0 for BF/HSC function *See POWER CONTROL*	DIP 5 = OFF (Resistive load): 0 zone1 / 0 zone2 / 0 zone3 DIP 5 = ON (Inductive load): 4 zone1 / 4 zone2 / 4 zone3
159*	Ct.2	R/W	OUT 2 (Cool) cycle time	1 ...200 sec (0,1 ...20,0 sec)		20 zone1 / 20 zone2 / 20 zone3

Read state

308* 319		R	State of rL.x (MASKOUT_RL)	*Table of signal reference states*

bit	
0	State rL.1
1	State rL.2
2	State rL.3
3	State rL.4
4	State rL.5
5	State rL.6

12* bit	STATE rL.1	R	OFF = Signal off ON = Signal on
13* bit	STATE rL.2	R	OFF = Signal off ON = Signal on
14* bit	STATE rL.3	R	OFF = Signal off ON = Signal on
15* bit	STATE rL.4	R	OFF = Signal off ON = Signal on
16* bit	STATE rL.5	R	OFF = Signal off ON = Signal on
17* bit	STATE rL.6	R	OFF = Signal off ON = Signal on

ALLOCATION OF PHYSICAL OUTPUTS

607	out. 1	R/W	Allocation of physical output OUT 1	1
608	out.2	R/W	Allocation of physical output OUT 2 (*)	2
609	out.3	R/W	Allocation of physical output OUT 3(**)	3
611	out.5	R/W	Allocation of physical output OUT 5	5
612	out.6	R/W	Allocation of physical output OUT 6	6
613	out.7	R/W	Allocation of physical output OUT 7	7
614	out.8	R/W	Allocation of physical output OUT 8	9
615	out.9	R/W	Allocation of physical output OUT 9	
616	out. 10	R/W	Allocation of physical output OUT 10	

(*) available only with GFW-E1 present
(**) available only with GFW-E2 present

Table of output allocations

0	Output disabled
1	Output rL.1 zone 1
2	Output rL.1 zone 2
3	Output rL.1 zone 3
5	Output rL.2 zone 1
6	Output rL.2 zone 2
7	Output rL.2 zone 3
9	Output rL.3 OR rL.5 zone 1
10	Output rL.3 OR rL.5 zone 2
11	Output rL.3 OR rL.5 zone 3
13	Output rL.4 AND rL.6 zone 1
14	Output rL.4 AND rL.6 zone 2
15	Output rL.4 AND rL.6 zone 3
17	Output (rL.3 OR rL.5) zone 1...zone 3
18	Output (rL.4 AND rL.6) zone 1...zone 3
+32	to reverse output status (only for Logic/Relay) output

NOTE: In 3-phase configuration, the state of physical output OUT1 is copied to OUT2 and OUT3.
In case of auxiliary continuous outputs, the same output functions can not be used on other outputs.
Ex: If oUt. 1 = 1 (out rL. 1 zone 1) it is not possible to set oUt.5 with the same code, if oUt.5 is continuous

17

18

Read state

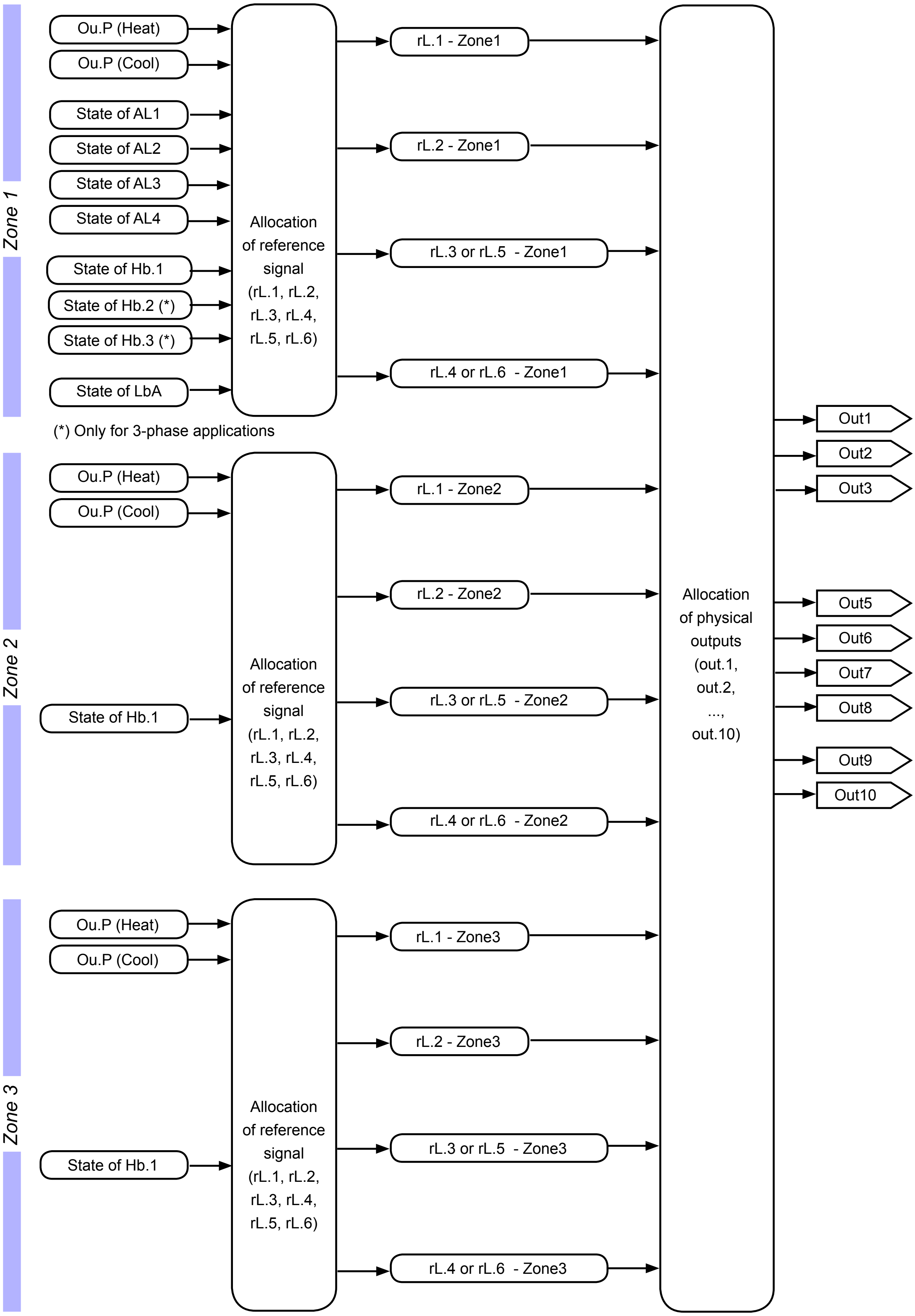
82 bit	State of output OUT1	R	OFF = Output off ON = Output on
83 bit	State of output OUT2	R	OFF = Output off ON = Output on
84 bit	State of output OUT3	R	OFF = Output off ON = Output on
86 bit	State of output OUT5	R	OFF = Output off ON = Output on
87 bit	State of output OUT6	R	OFF = Output off ON = Output on
88 bit	State of output OUT7	R	OFF = Output off ON = Output on
89 bit	State of output OUT8	R	OFF = Output off ON = Output on
90 bit	State of output OUT9	R	OFF = Output off ON = Output on
91 bit	State of output OUT10	R	OFF = Output off ON = Output on

664		R	State of outputs (MASKOUT_OUT)

Table of output state

bit	
0	OUT 1
1	OUT 2
2	OUT 3
4	OUT 5
5	OUT 6
6	OUT 7
7	OUT 8
8	OUT 9
9	OUT 10

FUNCTIONAL DIAGRAM



The controller has the following setpoint controls.

SETTING THE SETPOINT

The active (control) setpoint (SPA) can be set by means of the local setpoint (SP) or the remote setpoint (SP.rS). A remote setpoint can assume the value of an auxiliary input or one set via serial line (SP.r).

The remote setpoint can be defined in absolute value or relative to the local setpoint; in the latter case, the control setpoint will be given by the algebraic sum of the set local and the remote setpoint.

Local setpoint

138 16 - 472	SP	R/W	*Local setpoint*	Lo.L ... HI.L		0

Remote setpoint

181	tP.2	R/W	Auxiliary analog input function	*See: AUXILIARY ANALOG INPUT (LIN/TC)*	0

The remote setpoint can be set by means of the auxiliary analog input by enabling the function with parameter tP.2

18 136 - 249	SP.r	R/W	*Remote setpoint* (SET gradient for manual power correction)	*Setpoint table*	0

	Type of remote set	Absolute/Relative
0	Digital (from serial line)	Absolute
1	Digital (from serial line)	Relative to local set (SP or SP1 or SP2)
2	Auxiliary input	Absolute
3	Auxiliary input	Relative to set (SP or SP1 or SP2)

+4 set gradient in digit/sec.
+8 manual power correction based on line voltage
+16 disables saving of local setpoint SP
+32 disables saving of local manual power (at switch-off, returns to last value saved)

250	SERIAL_SP	R/W	*Remote setpoint from serial line*	Lo.L ... HI.L		0

Shared settings

25 20 - 28 - 142	Lo.L	R/W	Lower settable limit SP, SP remote	Lo.S ... Hi.S		0
26 21 - 29 - 143	HI.L	R/W	Upper settable limit SP, SP remote	Lo.S ... Hi.S		1000

10 bit	LOCAL/REMOTE	R/W	OFF = Enable local setpoint ON = Enable remote setpoint

305*		R/W	State (STATUS_W)	*Table of state settings*	0 zone1	0 zone2	0 zone3

bit	
0	-
1	Select SP1/SP2 (*)
2	Start/Stop Selftuning (*)
3	Select ON/OFF
4	Select AUTO/MAN
5	Start/Stop Autotuning (*)
6	Select LOC/REM (*)

(*) only for zone1 (GFW-M)

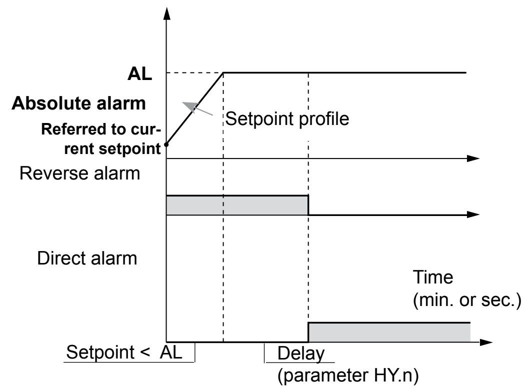
Read active setpoint

1 137 - 481	SPA	R	Active setpoint
4		R	Deviation (SPA - PV)

SETPOINT CONTROL

Set gradient

The “Set gradient” function sets a gradual variation of the setpoint, with programmed speed, between two defined values. If this function is active (G.SP other than 0), at switch-on and at auto/man switching the initial setpoint is assumed equal to the PV, and the local or selected set is reached with set gradient. Every variation of set, including variations of the local setpoint, is subject to the gradient.
The value of remote setpoint SP.rS is not saved in eeprom.
The set gradient is inhibited at switch-on when selftuning is enabled.



234 22	G.SP	R/W	Set gradient	0.0 ...999.9 digit / min (digit / sec see SP.r)		0,0
259	G.S2	R/W	Set gradient relative to SP2	0.0 ...999.9 digit / min (digit / sec see SP.r)		0,0
265	Hot	R/W	Select special functions	*Table of special functions*		0

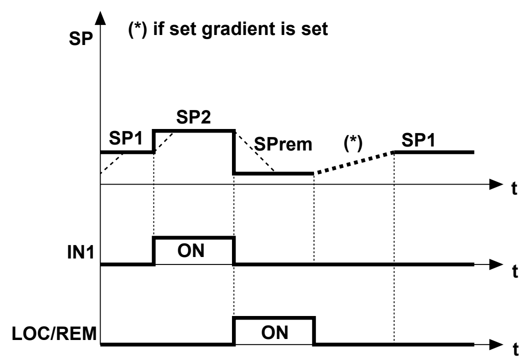
	Enable	Fault action power if PV is not stabilized	Enable preheating softstart
0		FA.P	
1	X	Average power	
2		FA.P	
3	X	FA.P	
4		FA.P	X
5	X	Average power	X
6		FA.P	X
7	X	FA.P	X

+8 enable GS.2

FA.P – see alarm for probe in short or connection error (SBR-ERR)

Multiset

The MULTISET function determines the local setpoint by selecting the value from Setpoint 1 (SP.1) or from Setpoint 2 (SP.2) based on the state of a digital input or by setting from a serial line.
The variation between Setpoint 1 and Setpoint 2 can take place with gradient: parameter G.SP determines the speed for reaching Setpoint 1 and parameter G.S2 defines the speed for reaching Setpoint 2.
The MULTISET function is enabled with parameter hd.1 and automatically enables the gradient function.
Selection between Setpoint 1 and Setpoint 2 can be seen by means of LED.



191	hd.1	R/W	*Enable multiset:* control instruments via serial	*Multiset table*		0

hd.1	Enable Multiset	Enable virtual instrument
0		
1	X	
2		X
3	X	X

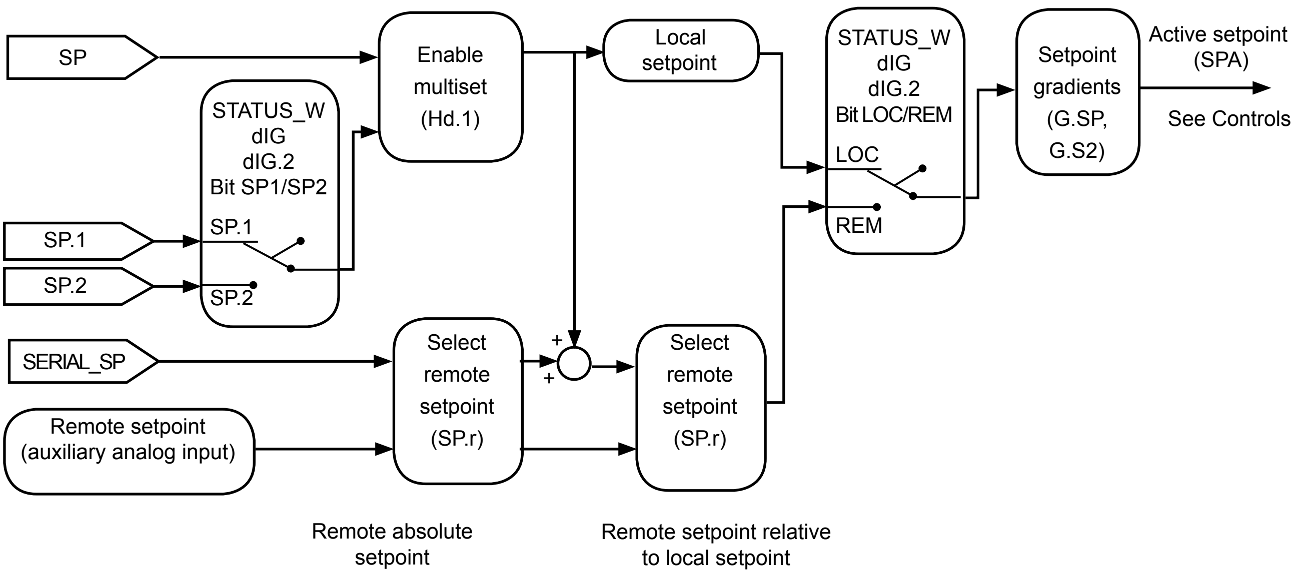
230 482	SP.1	R/W	Setpoint 1	Lo.L ... HI.L		100
231 483	SP.2	R/W	Setpoint 2	Lo.L ... HI.L		200

140	dIG.	R/W	Digital input function	*See: Table of digital input functions*		0	
618	dIG.2	R/W	Digital input function 2	*See: Table of digital input functions*		0	
75 bit	SELECT SP1 / SP2	R/W	OFF = Select SP1 ON = Select SP2				
305*		R/W	State (STATUS_W)	*Table of state settings*	0 zone1	0 zone2	0 zone3

bit	
0	-
1	Select SP1/SP2 (*)
2	Start/Stop Selftuning (*)
3	Select ON/OFF
4	Select AUTO/MAN
5	Start/Stop Autotuning (*)
6	Select LOC/REM (*)

(*) only for zone1 (GFW-M)

FUNCTIONAL DIAGRAM



PID HEAT/COOL CONTROL

The controller can manage a heating output and a cooling output in a completely independent manner. Heating and cooling parameters are described below. Parameters for *PID* (proportional band, integral and derivative time) control are typically calculated by means of Autotuning and Selftuning functions.

Control actions

Proportional action:
action in which contribution to output is proportional to deviation at input (deviation = difference between controlled variable and setpoint
Derivative action:
action in which contribution to output is proportional to rate of variation input deviation.
Integral action:
action in which contribution to output is proportional to integral of time of input deviation.

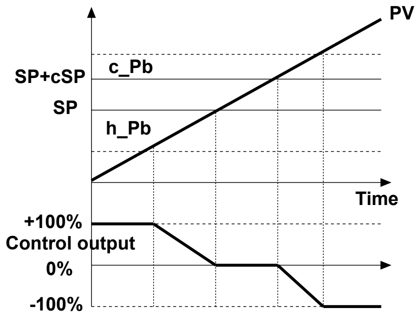
Proportional, derivative, and integral action

Increasing the proportional band reduces oscillation but increases deviation.
Reducing the proportional band reduces deviation but causes oscillation of the controlled variable (excessively low proportional band values make the system unstable).
An increase in Derivative Action corresponds to an increase in Derivative Time, reduces deviation, and prevents oscillation up to a critical Derivative Time value, beyond which deviation increases and there are prolonged oscillations.
An increase in Integral Action corresponds to a decrease in Integral Time, tends to annul deviation between the controlled variable and the setpoint at rated operating speed.
If the Integral Time value is too long (weak Integral Action), there may be persistent deviation between the controlled variable and the setpoint.
For more information on control actions, contact GEFRAN.

Heat/cool control with separate or superimposed band

Output with separate band

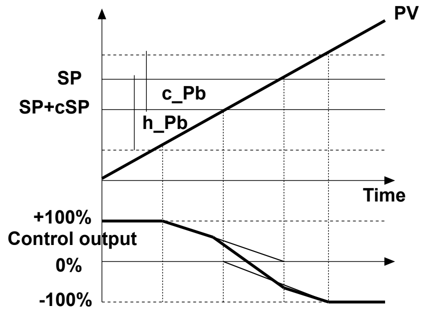
Control output with only proportional action in case of proportional heating band separate from cooling band.



PV = process variable
SP + cSP = cooling setpoint
c_Pb = cooling proportional band

Output with superimposed band

Control output with only proportional action in case of proportional heating band superimposed on cooling band.



PV = process variable
SP = heating setpoint
h_Pb = heating proportional band

Heat/cool control with relative gain

This control mode (enabled with parameter Ctr = 14) asks you to specify cooling type. The PID cooling parameters are then calculated based on heating parameters in the ratio specified (ex: C.ME = 1 (oil), H_Pb = 10, H_dt =1, H_It = 4 implies: C_Pb = 12.5, C_dt = 1 , C_It = 4)
Apply the following values when setting cycle times:

Air	T Cool cycle = 10 sec.
Oil	T Cool cycle = 4 sec.
Water	T Cool cycle = 2 sec.

NB.: Cool parameters cannot be changed in this mode.

PID Parameters

617*	SPU	R/W	Reference power	*Table of selections*	0 zone1 / 0 zone2 / 0 zone3

(**) function "slave" zone

- *The reference power of a slave zone in automatic mode is the power of a master zone in automatic or manual mode.*
- *The reference power of a slave zone in manual mode is the zone manual power.*
- *Software shutdown remains independent for each zone.*

SPU	
0	Power from analog input (In.A)
1	Power from main input (PV)
2	Power from aux input (In.2)
3	Power from aux input (In.3)
4	Power from aux input (In.4)
5	Power from aux input (In.5)
6	Power from PID (PID_POWER) (**)
7	Power from digital input (In.Pwm)
9	Power from GFW-M (FW_POWER) (**)
10	Power from GFW-E1 (FW_POWER) (**)
11	Power from GFW-E2 (FW_POWER) (**)

180	Ctr	R/W	Control type	*Table of heat/cool controls*	134

Val	Control type
0	P heat
1	P cool
2	P heat / cool
3	PI heat
4	PI cool
5	PI heat / cool
6	PID heat
7	PID cool
8	PID heat / cool
9	ON-OFF heat
10	ON-OFF cool
11	ON-OFF heat / cool
12	PID heat + ON-OFF cool
13	ON-OFF heat + PID cool
14	PID heat + cool with relative gain (see parameter C.MEd)

Select sample time for derivative action.
+0 sample 1 sec.
+16 sample 4 sec.
+32 sample 8 sec.
+64 sample 240 msec.
+128 No Reset of integral component at setpoint change
Note: the LBA alarm is not enabled in the ON/OFF control.

5 148 - 149	h.Pb	R/W	*Proportional band* for heating or hysteresis ON/OFF	0 ...999,9% f.s.		1,0
7 150	h.It	R/W	*Integral heating time*	0.00 ...99,99 min		4,00
8 151	h.dt	R/W	*Derivative heating time*	0.00 ...99,99 min		1,00
6	c.Pb	R/W	*Proportional band* for cooling or hysteresis ON/OFF	0 ...999,9% f.s.		1,0
76	c.It	R/W	*Integral cooling time*	0.00 ...99,99 min		4,00
77	c.dt	R/W	*Derivative cooling time*	0.00 ...99,99 min		1,00

Note: Parameters c.PB, c.It and c.dt are read-only if heat/cool control is enabled with relative gain (Ctr = 14).

513	C.ME	R/W	Select cooling fluid	0 ...2		0

		Relative gain (rG)
0	Air	1
1	Oil	0,8
2	Water	0,4

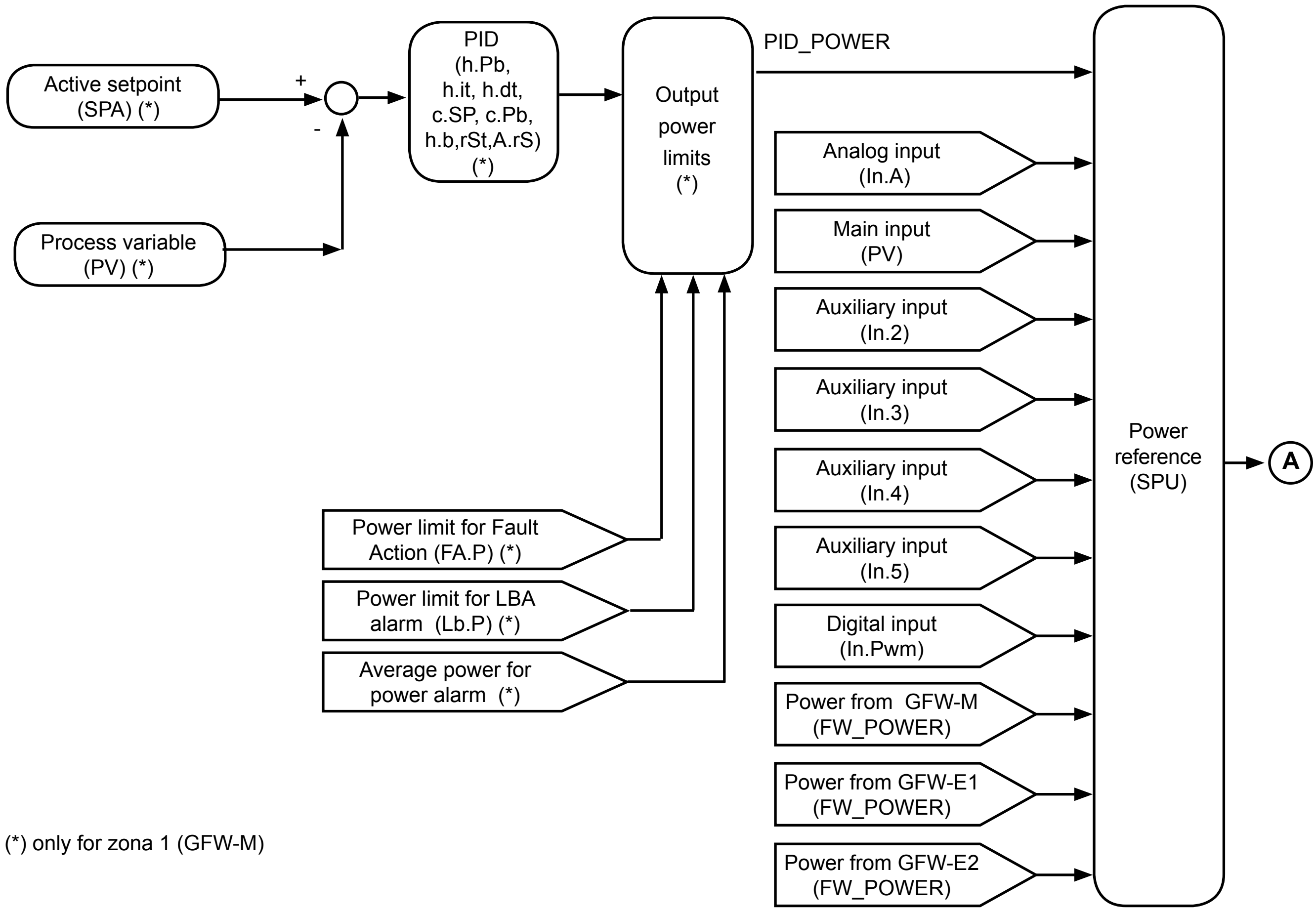
Read state

2* 132 - 471	Ou.P	R	*Value of control outputs* (+Heat / -Cool)	(W – only in manual mode at address 252)

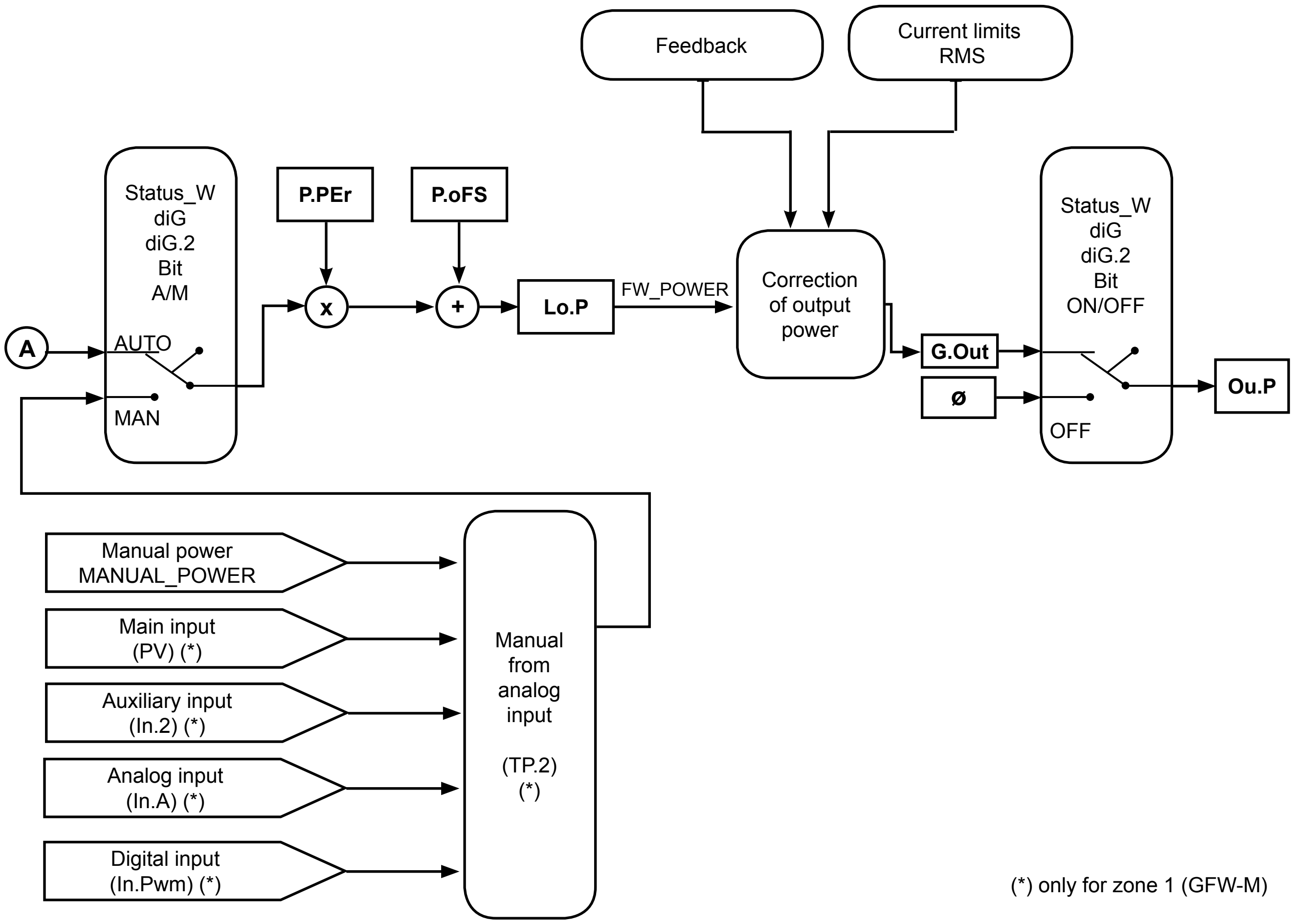
ADVANCED SETTINGS

39 484	c.SP	R/W	*Cooling setpoint* relative to heating setpoint	±25.0% f.s.		0,0	
78	rSt	R/W	Manual reset (value added to PID input)	-999 ...999 scale points		0	
516	P.rS	R/W	*Reset power* (value added directly to PID output)	-100,00.... ....100,0 %		0,0	
79	A.rS	R/W	Antireset (limits integral action of PID))	0 ...9999 scale points		0	
80	FFd	R/W	Feedforward (value added to PID output after processing)	-100,00.... ....100,0 %		0,0	
42 146	h.P.H	R/W	Maximum limit *heating power*	0.0 ...100,0 %		100,0	
254	h.P.L	R/W	Minimum limit heating power (not available for double heat/cool action)	0.0 ...100,0 %		0,0	
43	c.P.H	R/W	Maximum limit *cooling power*	0.0 ...100,0 %		100,0	
255	c.P.L	R/W	Minimum limit cooling power (not available for double heat/cool action)	0.0 ...100,0 %		0,0	
765*	P.PEr	R/W	Percentage of output power	0.0 ...100,0 %		100,0 zone1	100,0 zone2	100,0 zone3
766*	P.oFS	R/W	Offset of output power	-100,0 ...100,0 %		0,0 zone1	0,0 zone2	0,0 zone3
763*	G.oUt	R/W	Gradient for control output	0,0 ...200,0 % sec	set to 0 to disable	0,0 zone1	0,0 zone2	0,0 zone3
764*	Lo.P	R/W	Minimum trigger output	0,0 ...50,0 %		0,0 zone1	0,0 zone2	0,0 zone3

FUNCTIONAL DIAGRAM



(*) only for zona 1 (GFW-M)



(*) only for zone 1 (GFW-M)

AUTOMATIC / MANUAL CONTROL

By means of the digital input function you can set the controller in MAN (manual) and set the control output to a constant value changeable by means of communication.

When returning to AUTO (automatic), if the variable is within the proportional band, switching is bumpless.

252*		R/W	MANUAL_POWER	-100,0...100,0%		0,0 zone1	0,0 zone2	0,0 zone3
2* 132 - 471	OuP	R	*Value of control outputs* (+Heat / -Cool)	(W – only in manual mode at address 252)				
140	dIG.	R/W	Digital input function	*See: Table of digital input functions*		0		
618	dIG.2	R/W	Digital input function 2			0		
1* bit	AUTO/MAN	R/W	OFF = Automatic ON =Manual					
305*		R/W	State (STATUS_W)	*See: Table of state settings*		0 zone1	0 zone2	0 zone3

HOLD FUNCTION

The process variable value and the setpoints remain “frozen” for the time the digital input is active.

By activating the digital input with the Hold function when the variable is at values below the setpoint, a setpoint memory reset de-energizes all energized relays and resets all memory latches.

140	dIG.	R/W	Digital input function	*See: Table of digital input functions*		0
618	dIG.2	R/W	Digital input function 2			0
64 bit	HOLD	R/W	OFF = Disable hold ON = Enable hold			

MANUAL POWER CORRECTION

With this function (available on models with CV diagnostics option), you can run a correction of power delivered in manual based on the reference line voltage (riF). The % value of the (Cor) is freely settable and acts in inverse proportion.

The function is activated/deactivated by means of parameter SP.r.

Example: with the following settings: Cor = 10%; riF = 380; SP.r = value + 8; instrument in manual; line voltage 380 VAC, manual power set at 50%, following a 10% increase in line voltage, 380V + 10% (380V) = 418V, there is a decrease in set manual power equal to the same % of change: 50% - 10% (50%) = 45%.
To use this function, the controller must have a CT (current transformer) and a VT (voltage transformer).
N.B.: the % change in manual power is limited to the value set in parameter “Cor”.

The maximum manual power correction is limited to ± 65%.

505*	rIF	R/W	*Line voltage* Compensation of the voltage transformer read to maintain output power at a constant level.	0.0 ...999,9		0,0 zone1	0,0 zone2	0,0 zone3
506*	Cor	R/W	Correction of manual power based on line voltage	0,0 ...100,0 %		0,0 zone1	0,0 zone2	0,0 zone3
18 136 - 249	SP.r	R/W	*Remote setpoint* (SET gradient for manual power correction)	*Setpoint table*		0		

Setpoint table:

	Type of remote set	Absolute/Deviation
0	Digital (from serial line)	Absolute
1	Digital (from serial line)	Deviation local set (_SP o SP1 o SP2)
2	Auxiliary input	Absolute
3	Auxiliary input	Deviation set (_SP o SP1 o SP2)

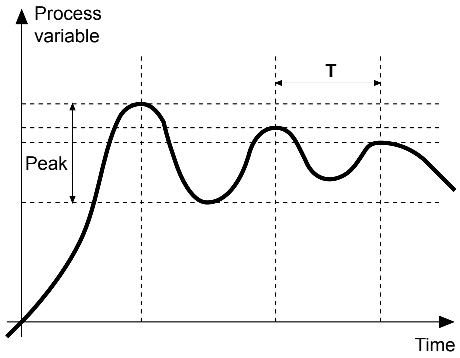
+4 set gradient in digit/sec.
+8 correction of manual power based on line voltage
+16 disable saving of local setpoint _SP
+32 disable saving of local manual power (at switch-off returns to last value saved)

MANUAL TUNING

A) Enter the setpoint at its working value.
B) Set the proportional band at 0.1% (with on-off type setting).
C) Switch to automatic and observe the behavior of the variable. It will be similar to that in the figure:
D) The PID parameters are calculated as follows: Proportional band

$$P.B. = \frac{Peak}{V\,max - V\,min} \times 100$$

(V max - V min) is the scale range.
Integral time It = 1,5 x T
Derivative time dt = It/4
E) Switch the controller to manual, set the calculated parameters (activate the PID control by setting a cycle time for relay outputs, if any), switch to automatic.
F) To assess parameter optimization, change the setpoint value if possible and check temporary behavior. If oscillation persists, increase the value of the proportional band; if response is too slow, decrease the value.



See: CONTROL - PID Parameters

AUTOTUNING

Enabling the autotuning function blocks the settings of the PID parameters.
Autotuning continues to measure the system oscillations, seeking as quickly as possible the PID parameter values that reduce the oscillation; it does not intervene if the oscillations drop to values below 1.0% of the proportional band.
It is interrupted if the setpoint is changed, and resumes automatically with a constant setpoint. The calculated parameters are not saved; if the instrument is switched off the controller resumes with the parameters programmed before autotuning was enabled.
Autotuning terminates the procedures with switching to manual.

Enabling the autotuning function blocks the settings of the PID parameters.
It can be two types: continuous or one shot.

Continuous autotunìng is enabled with parameter Stu (values 1, 3, 5); it continues to measure the system oscillations, seeking as quickly as possible the PID parameter values that reduce the oscillation; it does not intervene if the oscillations drop to values below 1.0% of the proportional band.
It is interrupted if the setpoint is changed, and resumes automatically with a constant setpoint.
The calculated parameters are not saved if the instrument is switched off, in case of switching to manual or disabling the code in configuration, and controller resumes with the parameters programmed before autotuning was enabled.
The calculated parameters are saved when the function is enabled via digital input or via A/M key (start /stop) at stop.

One-shot autotuning can be activated manually or automatically with parameter Stu (as can be seen on the table, the values to be set depend on enabling of Selftuning or Softstart).
It is useful for calculating PID parameters when the system is in the vicinity of the setpoint; it produces a variation on the control output of a maximum of ± 100% of the current control power limited by h.PH - h.PL (heat), c.PH - c.PL (cool) and assesses the effects in overshoot over time. The calculated parameters are saved.
Manual activation (code Stu = 8, 10, 12) by setting the parameter directly or via digital input or key.
Automatic activation (code Stu = 24, 26, 28 with error range of 0.5%) when the PV-SP error exceeds the defined range (programmable at 0.5%, 1%, 2%, 4% of full scale).

Activation is inhibited if PV <5% or PV >95% of input scale.

NB: at switch-on after selftuning, after switching to MANUAL, after software shutdown or after a setpoint change, automatic activation is inhibited for an interval equal to five times the integral time, with a minimum of 5 minutes.
An identical interval has to lapse after a one-shot run.

See: CONTROL - PID Parameters

31	S.tu	R/W	*Enable selftuning, autotuning, softstart*	*Selftuning, autotuning, softstart table*	0

	Autotuning continuous	Selftuning	Softstart
0	NO	NO	NO
1	YES	NO	NO
2	NO	YES	NO
3	YES	YES	NO
4	NO	NO	YES
5	YES	NO	YES
6	Autotuning One-shot		
8*	WAIT	NO	NO
9	GO	NO	NO
10*	WAIT	YES	NO
11	GO	YES	NO
12*	WAIT	NO	YES
13	GO	NO	YES

(*) +16 with automatic switching in GO if PV-SP > 0.5% f.s.
+32 with automatic switching in GO if PV-SP > 1% f.s.
+64 with automatic switching in GO if PV-SP > 2% f.s.
+128 with automatic switching in GO if PV-SP > 4% f.s.

140	dIG.	R/W	Digital input function	*See: Table of digital input functions*		0
618	dIG.2	R/W	Digital input 2 function			0
29 bit	AUTOTUNING	R/W	OFF = Stop Autotuning ON = Start Autotuning			

Read state

28 bit	AUTOTUNING STATE	R	OFF = Autotuning in Stop ON = Autotuning in Start	
68 bit	DIGITAL INPUT 1	R	OFF = Digital input 1 off ON = Digital input 1 on	*See: Table of digital input functions*
92 bit	DIGITAL INPUT 2	R	OFF = Digital input 2 off ON = Digital input 2 on	
296		R	Autotuning and selftuning enable state (FLG_PID)	

bit	
3	Selftuning on
4	Softstart on
6	Autotuning on

305*		R/W	State (STATUS_W)	*Table of state settings*	0 zone1	0 zone2	0 zone3

bit	
0	-
1	Select SP1/SP2 (*)
2	Start/Stop Selftuning (*)
3	Select ON/OFF
4	Select AUTO/MAN
5	Start/Stop Autotuning (*)
6	Select LOC/REM (*)

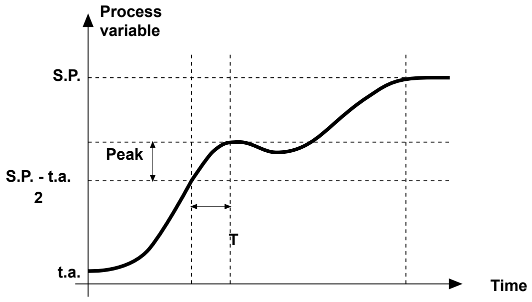
(*) only for zone1 (GFW-M)

SELFTUNING

This function is valid for single-action (either heat or cool) systems and for double-action (heat/cool) systems.

Selftuning is activated to calculate the best control parameters when starting the process. The variable (example: temperature) must be the one assumed at zero power (room temperature).
The controller supplies the maximum power set until reaching an intermediate point between starting value and the setpoint, then resets power. The PID parameters are calculated by evaluating superelongation and the time needed to reach the peak (N.B.: This action is not considered in ON/OFF control).
When the function is completed, it disengages automatically, and the control proceeds to reach the setpoint.

Selftuning



How to activate selftuning:

A. Activation at switch-on

1. Set the setpoint to the desired value.
2. Enable selftuning by setting parameter Stu to 2
3. Switch off the instrument.
4. Make sure that temperature is near room temperature.
5. Switch on the instrument.

B. Activation via serial command

1. Make sure that temperature is near room temperature.
2. Set the setpoint to the desired value.
3. Run the Start Selftuning command.

The procedure runs automatically until termination. At termination, the new PID parameters are saved: proportional band, integral and derivative times calculated for the current action (heat or cool). In case of double action (heat + cool), the parameters for the opposite action are calculated by maintaining the initial ratio between the parameters (example: Cpb = Hpb * K; where K = Cpb / Hpb when selftuning is started). At termination, the Stu code is automatically cancelled.
Note: The procedure does not start if temperature exceeds the setpoint for heat control, or is below the setpoint for cool control. In this case, the Stu code is not cancelled. It is advisable to enable the LEDs to signal selftuning state. By setting parameter Ld.St = 4 on the Hrd menu, the appropriate LED will light up or flash when selftuning is active.

see: CONTROLS - PID parameters

31	S.tu	R/W	Enable selftuning, autotuning, softstart	Selftuning, autotuning, softstart table	0

	Autotuning continuous	Selftuning	Softstart
0	NO	NO	NO
1	YES	NO	NO
2	NO	YES	NO
3	YES	YES	NO
4	NO	NO	YES
5	YES	NO	YES
6	Autotuning One-shot		
8*	WAIT	NO	NO
9	GO	NO	NO
10*	WAIT	YES	NO
11	GO	YES	NO
12*	WAIT	NO	YES
13	GO	NO	YES

(*) +16 with automatic switching in GO if PV-SP > 0.5% f.s.
+32 with automatic switching in GO if PV-SP > 1% f.s.
+64 with automatic switching in GO if PV-SP > 2% f.s.
+128 with automatic switching in GO if PV-SP > 4% f.s.

140	d iG.	R/W	Function digital input	*See: Table of digital input functions*		0
618	d iG.2	R/W	Digital input 2 function			0
3 bit	SELFTUNING	R/W	OFF = Selftuning in Stop ON = Selftuning in Start			
305*		R/W	Instrument state (STATUS_W)	*See: Table of instrument settings*		

Read state

0 bit	SELFTUNING STATE	R	OFF = Selftuning in Stop ON = Selftuning in Start	
68 bit	STATE OF DIGITAL INPUT 1	R	OFF = Digital input 1 off ON = Digital input 1 on	*See: Table of digital input functions*
92 bit	STATE OF DIGITAL INPUT 2	R	OFF = Digital input 2 off ON = Digital input 2 on	
296		R	Autotuning and selftuning enable state (FLG_PID)	bit 3 Selftuning on 6 Autotuning on

SOFTSTART

If enabled, this function partializes power based on a percentage of time elapsed since instrument switch-on compared to the set time of 0.0 ... 500.0 min ("SoFt" parameter CFG phase). Softstart is an alternative to selftuning and is activated after each instrument switch-on. Softstart is reset when switching to manual.

31	S.tu	R/W	*Enable selftuning, autotuning, softstart*	*Selftuning, autotuning, softstart table*	0

	Autotuning continuous	Selftuning	Softstart
0	NO	NO	NO
1	YES	NO	NO
2	NO	YES	NO
3	YES	YES	NO
4	NO	NO	YES
5	YES	NO	YES
6	Autotuning One-shot		
8*	WAIT	NO	NO
9	GO	NO	NO
10*	WAIT	YES	NO
11	GO	YES	NO
12*	WAIT	NO	YES
13	GO	NO	YES

(*) +16 with automatic switching in GO if PV-SP > 0.5% f.s.
+32 with automatic switching in GO if PV-SP > 1% f.s.
+64 with automatic switching in GO if PV-SP > 2% f.s.
+128 with automatic switching in GO if PV-SP > 4% f.s.

263	SP.S	R/W	*Softstart setpoint* (preheating hot runners)		100
30 bit	RESTART SOFTSTART	R/W	OFF = ON = Restart of Softstart		

Read state

63 bit	STATE SOFTSTART	R	OFF = NO Active Softstart ON = Active Softstar

START MODE

699*	P.ont	R/W	Start modes at Power-On	0* Function at previous state 1 Software shutdown 2 Software startup	0 zone1	0 zone2	0 zone3

(*) digital input states always have priority

SOFTWARE SHUTDOWN

Running the software shutdown procedure causes the following:
1) Reset of Autotuning, Selftuning and Softstart.
2) Digital input enabled only if assigned to SW shutdown function.
3) In case of switch-on after SW shutdown, any ramp for the set (set gradient) starts from the PV.
4) Outputs OFF: except for signals them of reference rL.4 and rL.6 that they come forced ON
5) Reset of HB alarm.
6) Reset of LBA alarm.
7) The Heat and Cool bit on the state word STATUS and POWER are reset.
8) At shutdown, the current power is saved. At switch-on, integral power is recalculated as the difference between saved power and proportional power; this calculation is defined as “desaturation at switch-on.”
9) In case of Geflex, the state of alarms (AL1...AL4, ALHBTA1...ALHBTA3) is reset.
9) Alarms AL 1… AL 4 can be enable or disable through the parameter oFF.t.

140	dIG.	R/W	Digital input function	*See: Table of digital input functions*		0
618	dIG.2	R/W	Digital input 2 function			
11 bit	SOFTWARE LAUNCH/ SHUTDOWN	R/W	OFF = On software ON =Off software			
700	oFF.t	R/W	Modes at software shutdown	0	Outputs rL.1- rL.2 - rL.3 - rL.5 = OFF Outputs rL.4 - rL.6 = ON Alarms AL.1 -AL.2 -AL.3 - AL.4 disabled	0
				1	Outputs rL.1- rL.2 - rL.3 - rL.5 = OFF Outputs rL.4 - rL.6 = ON Alarms AL.1 -AL.2 -AL.3 - AL.4 enabled	

+16 restart softstart (if enabled) at software relaunch

Read state

68 bit	STATE of DIGITAL INPUT 1	R	OFF = Digital input 1 off ON = Digital input 1 on	*See: Table of digital input functions*	
92 bit	STATE of DIGITAL INPUT 2	R	OFF = Digital input 2 off ON = Digital input 2 on		
305*		R/W	Instrument (STATUS_W)	*See: Table of state settings*	0

FAULT ACTION POWER

You can decide what power to supply in case of broken probe.
FAP is the reference power for parameter FAP.
Average power is the average power calculated in the last 300 sec.
The alarm reset and reference power update take place only at switch-on or after a setpoint change.
The alarm is not activated if the control (Ctr) is ON/OFF type, during Selftuning and in Manual.

265	Hot	R/W	Select special functions	*See: Hot runners table - Setpoint Settings*		0
228	FAP	R/W	Fault action power (supplied in conditions of broken probe)	-100,0 ..100,0 %		0,0

Read state

26* bit	STATE OF HB ALARM OR POWER_FAULT	R	OFF = Alarm off ON = Alarm on
80 bit	State of power alarm	R	OFF = Alarm off ON = Alarm on

POWER ALARM

The alarm signals any power changes (OuP) after the process variable (PV) has stabilized on the setpoint (SP). The time beyond which the process variable is considered stable is 300 sec.

The reference power update take place only at switch-on or after a setpoint change.

If the process variable leaves the stabilization band after the first stabilization, this does not influence the alarm.

In case of SBR:

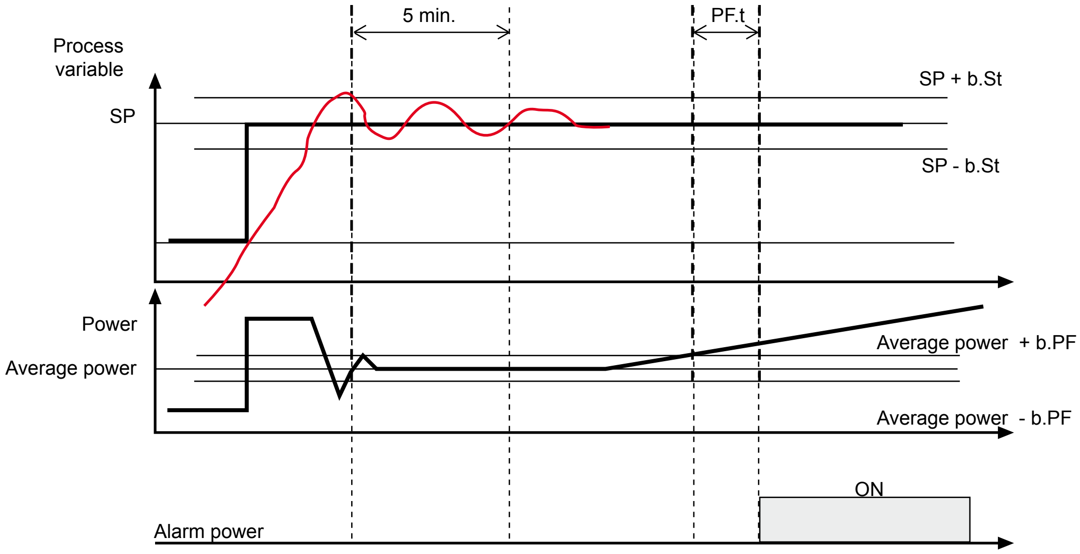
- if the PV has not yet stabilized, either the average power over the last 5 minutes or FAP power is supplied (depending on the setting of the HOT parameter).
- if the PV has stabilized the average power over the last 5 minutes is supplied.

Function:

If necessary, assign an output (rL.2...6) for the power alarm.
Set the band (b.ST) within which the process variable is considered stable after 300 sec. have elapsed.
Set the band (b.PF) outside which the alarm is activated after time PF.t has elapsed.

The reference power is the active power after 300 sec. have elapsed.
The alarm reset and reference power update take place only at switch-on or after a setpoint change.

The alarm is not activated if the control (Ctr) is ON/OFF type, during Selftuning and in Manual.



The parameters for alarm power are:

261	b.St	R/W	<u>*Stability band*</u> (alarm power function)	0,0 ... .100,0 % f.s.		0,0
262	b.PF	R/W	<u>*Alarm power band*</u> (alarm power function)	0,0 ...100,0 %		0,0
260	PF.t	R/W	Delay time for alarm power activation	0 ...999 sec		0

160*	rL.1	R/W	**Allocation of** <u>*reference signal*</u>	*See: Generic alarms – Table of reference signals*	0 zone1	0 zone2	0 zone3
163*	rL.2	R/W	**Allocation of reference signal**		1 zone1	1 zone2	1 zone3
166*	rL.3	R/W	Allocation of reference signal - OR Output		2 zone1	2 zone2	2 zone3
170*	rL.4	R/W	Allocation of reference signal - AND Output		35 zone1	35 zone2	35 zone3
171*	rL.5	R/W	Allocation of reference signal - OR Output		4 zone1	4 zone2	4 zone3
172*	rL.6	R/W	Allocation of reference signal - AND Output		160 zone1	160 zone2	160 zone3

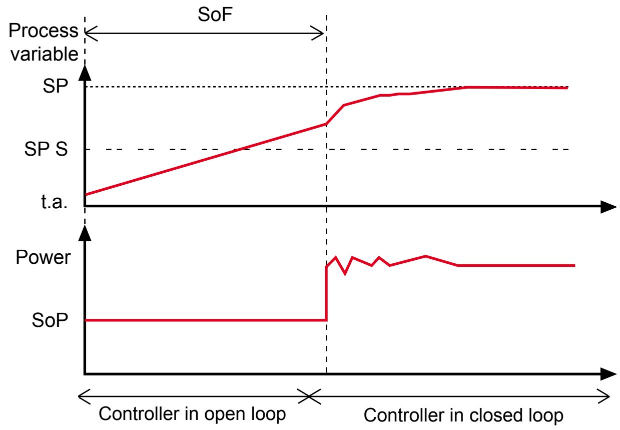
SOFTSTART FOR PREHEATING

This function lets you deliver a settable power (So.P) for time (SoF), after which normal control is resumed by means of PID control.

Activation is only at switch-on, with manual-automatic switching during Softstart (the time restarts from 0), and if the process variable is below setpoint SP.S.

From SW version 2.02:

With softstart time SoF = 0, preheat condition PV <SP.S with settable power SO.P is continuously checked.



31	S.tu	R/W	*Enable selftuning, autotuning, softstart*	*Selftuning, autotuning, softstart table*	0

	Autotuning continuous	Selftuning	Softstart
0	NO	NO	NO
1	YES	NO	NO
2	NO	YES	NO
3	YES	YES	NO
4	NO	NO	YES
5	YES	NO	YES
6	Autotuning One-shot		
8*	WAIT	NO	NO
9	GO	NO	NO
10*	WAIT	YES	NO
11	GO	YES	NO
12*	WAIT	NO	YES
13	GO	NO	YES

(*) +16 with automatic switching in GO if PV-SP > 0.5% f.s.
+32 with automatic switching in GO if PV-SP > 1% f.s.
+64 with automatic switching in GO if PV-SP > 2% f.s.
+128 with automatic switching in GO if PV-SP > 4% f.s.

263	SP.S	R/W	*Softstart setpoint*	Lo.L...HI.L		100
264	So.P	R/W	Softstart power	-100,00.... ....100,0 %		0,0
147	SoF	R/W	Softstart time	0.0 ...500,0 min		0,0

Read state

63 bit	STATE OF SOFTSTART	R	OFF = Softstart in Stop ON = Softstart in Start

HEATING OUTPUT (Fast cycle)

For outputs rL.1 (Out 1) and rL.2 (Out 2) you can set a fast cycle time (0.1 ... 20,0 sec) by setting the parameter to 64 (Heat) or 65 (Cool).

160*	rL.1	R/W	Allocation of reference signal	*See: Generic alarms -Table of reference signals*	0 zone1	0 zone2	0 zone3
163*	rL.2	R/W	Allocation of reference signal		1 zone1	1 zone2	1 zone3

SSR CONTROL MODES

ON Modality

The GFW has the following power control modes:

- PA modulation via variation of phase angle
- ZC, BF, HSC modulation via variation of number of conduction cycles with zero crossing trigger.

PA phase angle: this mode controls power on the load via modulation of the phase angle.
ZC zero crossing: this type of operation reduces EMC emissions. This mode controls power on the load via a series of conduction ON and non conduction OFF cycles.
The cycle time is constant and can be set from 1 to 200 sec (or from 0.1 to 20.0 sec).
BF burst firing: this mode controls power on the load via a series of conduction ON and non conduction OFF cycles. The ratio of the number of ON cycles to OFF cycles is proportional to the power value to be supplied to the load. The repeat period or cycle time is kept to a minimum for each power value.
Parameter bF.Cy defines the minimum number of conduction cycles, settable from 1 to 10.
In case of 3-phase load without neutral or closed delta, BF.Cy >= 5 has to be set to ensure correct operation (balancing of current in the 3 loads).
HSC Half Single Cycle: this mode corresponds to a BF that includes ON and OFF half-cycles. It is useful for reducing flicker with short-wave IR loads (and is applied only to single-phase or 3-phase with neutre or open delta loads).

Start mode is set with parameter Hd.5
Control of maximum rms current (whose value is set in parameter Fu.tA) can always be enabled with parameter Hd.5 in every power-on mode.
The cycle time can be set with two different resolutions in seconds or tenths of a second based on the type of heat or cool function assigned to outputs rL1 and rL2. The use of short cycle times (< 2-3 sec) is always recommended in case of control with SSRs.

Settings

703*	Hd.5	R/W	Enable trigger modes

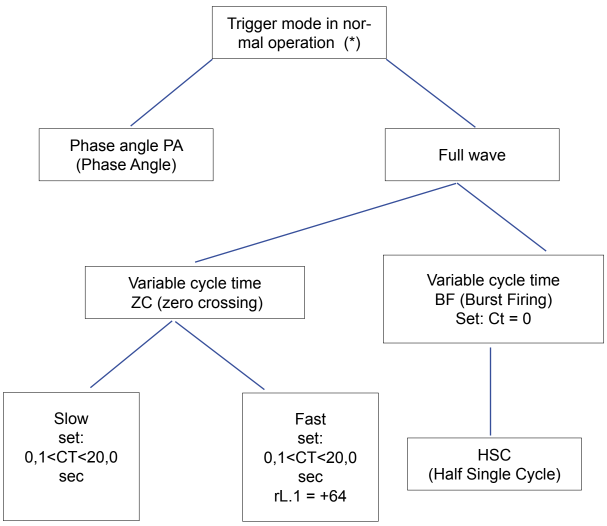


Table of trigger modes

	Ramp of Softstart	Trigger mode in normal operation (*)	BF mode	RMS in softstart	Current control in normal operation
0	NO	ZC/BF	-	NO	NO
1	YES	ZC/BF	-	NO	NO
2	NO	PA	-	NO	NO
3	YES	PA	-	NO	NO
4	NO	ZC/BF	HSC	NO	NO
5	YES	ZC/BF	HSC	NO	NO
6	NO	PA	-	NO	NO
7	YES	PA	-	NO	NO
8	NO	ZC/BF	-	YES	NO
9	YES	ZC/BF	-	YES	NO
10	NO	PA	-	YES	NO
11	YES	PA	-	YES	NO
12	NO	ZC/BF	HSC	YES	NO
13	YES	ZC/BF	HSC	YES	NO
14	NO	PA	-	YES	NO
15	YES	PA	-	YES	NO
16	NO	ZC/BF	-	NO	YES
17	YES	ZC/BF	-	NO	YES
18	NO	PA	-	NO	YES
19	YES	PA	-	NO	YES
20	NO	ZC/BF	HSC	NO	YES
21	YES	ZC/BF	HSC	NO	YES
22	NO	PA	-	NO	YES
23	YES	PA	-	NO	YES
24	NO	ZC/BF	-	YES	YES
25	YES	ZC/BF	-	YES	YES
26	NO	PA	-	YES	YES
27	YES	PA	-	YES	YES
28	NO	ZC/BF	HSC	YES	YES
29	YES	ZC/BF	HSC	YES	YES
30	NO	PA	-	YES	YES
31	YES	PA	-	YES	YES

+ 32 only for ZC/BF modes: enable delay triggering
+ 64 linear phase Softstart in power
+128 phase Softstart for IR lamps
+ 256 phase Softstart for shutdown in software ON/OFF switching

DIP 5 = OFF (Resistive load)		
141 zone1	141 zone2	141 zone3

DIP 5 = ON (Inductive load)		
32 zone1	32 zone2	32 zone3

707*	FU.tA	R/W	Max. limit of RMS current in normal op	0,0 ...999,9 A	

Model	40A	60A	100A	150A	200A	250A
Default zone 1...3	40,0	60,0	100,0	150,0	200,0	250,0

704*	bF.cY	R/W	Min. number of cycles in BF mode	1 ...10	

DIP 5 = OFF (Resistive load)		
1 zone1	1 zone2	1 zone3
DIP 5 = ON (Inductive load)		
5 zone1	5 zone2	5 zone3

NB: In case of a 3-phase load, you can set a different value from parameter FU.tA for each zone (ex. to control an unbalanced 3-phase load).

SOFTSTART or START RAMP

This type of start can be enabled either in phase control or pulse train mode and acts via control of the conduction angle. It is enabled with parameter Hd.5.

The softstart ramp starts from a zero conduction angle and reaches the angle set in parameter PS.HI in the time set in parameter PS.tm, from 0.1 to 60.0 sec.

With parameter Hd.5 (+64), you can configure a linear softstart in power, i.e., starting from zero you reach the power value corresponding to the maximum conduction angle set in PS.HI. Softstart ends before the set time if power reaches the corresponding value set in manual control or calculated by PID.

Control of maximum peak current can be enabled with parameter Hd.5 during the ramp phase; peak value is settable in parameter PS.tA. This function is useful in case of short circuit on the load of loads with high temperature coefficients to automatically adjust start time to the load.

The softstart ramp activates at the first start after power-ON and after a software reboot. It can be reactivated via software control by writing bit 108 or automatically if there are OFF conditions for a time exceeding the one settable in PS.oF (if =0 the function is as if disabled).

The ramp can also be enabled with parameter Hd.5 (+256) after a software shutdown, i.e., zero is reached in the set time from delivered power.

						zone1	zone2	zone3
630*	PS.HI	R/W	maximum phase of phase softstart ramp	0.0 ...100,0 %		100,0	100,0	100,0
705*	PS.tm	R/W	Duration of phase softstart ramp	0.1 ...60,0 s		10,0	10,0	10,0
629*	PS.oF	R/W	Minimum non-conduction time to reactivate phase softstart ramp	0 ...999 s		2	2	2
706*	PS.tA	R/W	Maximum peak current limit during phase softstart ramp	0.0 ...999,9 A				
108* bit	Restart of phase softstart ramp	R/W	OFF = Restart not enabled ON = Restart enabled					
106* bit	State of phase softstart ramp	R	OFF = Ramp not active ON = Ramp active					
107* bit	State of phase softstart ramp	R	OFF = Ramp not ended ON = Ramp ended					

Model	40A	60A	100A	150A	200A	250A
Default zone 1...3	110,0	170,0	280,0	420,0	560,0	700,0

NB: In case of a 3-phase load, you can set a different value from parameter PS.tA for each zone (ex. to control an unbalanced 3-phase load).

DELAY TRIGGERING

In firing modes ZC and BF, with inductive loads, this function inserts delay triggering in the first cycle.
The delay is expressed in degrees settable in parameter dL.t, from 0 to 90 degrees. The function is enabled with parameter Hd.5 (+32).
The function activates automatically if there are OFF conditions for a time exceeding the one settable in dL.oF (if =0 the function is as if disabled).

◊ Optimised Delay-Triggering value for transformer: 60°
◊ Optimised Delay-Triggering value for 3-phase transformer: 90°, 90°, 60°

						zone1	zone2	zone3
708*	dL.t	R/W	Delay triggering (first trigger only)	0 ... 90 °		60	60	60
738*	dL.oF	R/W	Minimum non-conduction time to reactivate delay triggering	0 ... 10000ms		10	10	10

FEEDBACK MODES

The GFW has the following power control modes:
V-voltage
V^2-squared voltage
I-current
I^2-squared current
P-power
A control mode is enabled with parameter Hd.6.

Voltage feedback (V)
To keep voltage on the load constant, this compensates possible variations in line voltage with reference to the rated voltage saved in riF.V. (expressed in Vrms).
The voltage value maintained on the load is (ref.V*P%_pid_man/100) and is indicated in the Modbus 757 register.

Voltage feedback (V^2)
To keep voltage on the load constant, this compensates possible variations in line voltage with reference to the rated voltage saved in riF.V. (expressed in Vrms).
The voltage value maintained on the load is (rif.V* $\sqrt{(P\%\_pid\_man/100)}$), and is indicated in the Modbus 757 register.

Current feedback (I)
To keep current on the load constant, this compensates possible variations in line voltage and/or variations in load impedance with reference to the rated current saved in riF.I. (expressed in Arms).
The current value maintained on the load is (rif.I*P%_pid_man/100), and is indicated in the Modbus 757 register.

Current feedback (I^2)
To keep current on the load constant, this compensates possible variations in line voltage and/or variations in load impedance with reference to the rated current saved in riF.I. (expressed in Arms).
The current value maintained on the load is (rif.I* $\sqrt{(P\%\_pid\_man/100)}$), and is indicated in the Modbus 757 register.

Power feedback P
To keep power on the load constant, this compensates both variations in line voltage and variations in load impedance with reference to the rated power saved in riF.P. (expressed in kWatt).
The current value maintained on the load is (rif.P*P%_pid_man/100), and is indicated in the Modbus 757 register.

IMPORTANT!

Feedback calibration can be activated from the digital input (parameters DIG and DIG.2) or by serial control (ref. bit113), and if requested MUST be activated only with Hd.6=0 (the required Hd.6 value can be set only after calibration) and preferably with maximum power on the load (ex. P_man or P_pid at 100%).
If you change function mode (PA, ZC, BF, HSC), you have to re-run the Feedback calibration procedure.

Voltage V (or current I or power P) feedback corrects the % of conduction with a maximum settable value in parameter Cor. V (or Cor.I or Cor.P).

For non-linear loads (ex.: Super Kanthal or Silicon Carbide) the automatic calibration procedure is NOT NECESSARY. Set the value of parameters ref.V, ref. I, ref. P based on the specific nominal of the load shown on the data-sheet (ref. GFW Installation Guide).

730*	Hd.6	R/W	Enable feedback modes	Table of feedback modes		0 zone1	0 zone2	0 zone3
731*	Cor.V	R/W	Maximum correction of voltage feedback	0.0 ...100,0 %		100,0 zone1	100,0 zone2	100,0 zone3
732*	Cor. I	R/W	Maximum correction of current feedback	0.0 ...100,0 %		100,0 zone1	100,0 zone2	100,0 zone3
733*	Cor.P	R/W	Maximum correction of power feedback	0.0 ...100,0 %		100,0 zone1	100,0 zone2	100,0 zone3
734*	riF.V	R/W	Voltage feedback reference	0.0 ...999,9 V		0,0 zone1	0,0 zone2	0,0 zone3
735*	riF. I	R/W	Current feedback reference	0.0 ...999,9 A		0,0 zone1	0,0 zone2	0,0 zone3
736*	riF.P	R/W	Power feedback reference	0.0 ...99,99 kW		0,0 zone1	0,0 zone2	0,0 zone3
741*	Fb. lt	R/W	Feedback response speed	0.1 ...5,0 % / 60msec		0,3 zona1	0,3 zona2	0,3 zona3

	Feedback ON
0	None
1	V^2 (Voltage)
2	I^2 (Current)
3	P (Power)
4	None
5	V (Linear voltage)
6	I (Linear current)

113* bit	Calibration of voltage feedback reference	R/W	OFF = Calibration not enabled ON = Calibration enabled

READ STATE

757*	Ar iF	R	Reference of Feedback	0.0 ...999,9 V 0.0 ...999,9 A 0.0 ...99,99 kW	Setpoint of V, I, P to maintain on load

NOTE: For other information see the hardware manual

HEURISTIC CONTROL POWER

It is useful to be able to limit the delivery of total power to the loads in order to avoid input peaks from the single-phase power line.

This condition occurs during switch-on phases when the machine is cold; the demand for heating power is 100% until temperatures near the setpoint are reached. It is also useful to avoid simultaneity of conduction when there is ON-OFF modulation for temperature maintenance.

The cycle time must be identical for all zones; the power percentage for each zone is limited to that necessary to maintain current within set limits.

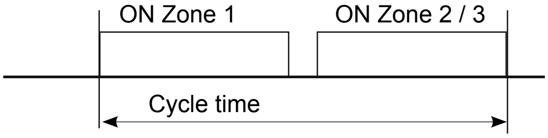
This function acts by enabling the control to search for the most appropriate input combinations.

Example 1:
4 loads 380V- 32A (zone 1), 16A (zone 2), 25A (zone 3), 40A (maximum current is 73A in case of simultaneity of conduction).
Current limit I.HEU=50A.
The following combinations of conduction are possible:
(to define the number of combinations, remember that the combinations without repetitions are = n! / (k!*(n-k)!))
I1+I2 = 48A
I1+I3 = 57A
I2+I3 = 41A
I1+I2+I3 = 73A

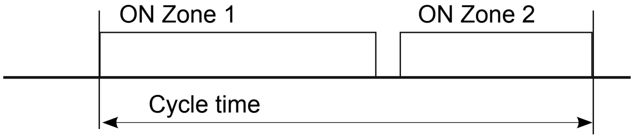
The combinations corresponding to current values below the limit value are:
I1+I2 = 48A
I2+I3 = 41A
The one with lower current is given by zone 2 and zone 3.

In the single cycle time for the enabled zones, the delivery of power may be reduced to respect the maximum current limit.
The time distribution for activation of the zones is calculated at the start of each cycle:
Ptot = P1+ P2 (if P2>P3) + P3 (if P3>P2)
Simultaneity is allowed for zones 2 and 3.

If P1= 100%, P2= 100%, P3= 100%
Ptot=200%; since Ptot>100%, the conduction time of the zone x is obtained by Px * (100/Ptot)
P1,2,3 delivered = 100%*0.5 = 50%



If P1= 100%, P2= 50%, P3= 0%
Ptot=150%; since Ptot>100%, the conduction time of the zone x is obtained by Px * (100/Ptot)
P1 delivered = 100%*0.66 = 67%
P2 delivered = 50%*0.66 = 33%
P3 delivered = 0%*0.66 = 0%



680	hd.3	R/W	*Enable heuristic power control*	*Table for enabling heuristic power*	0

	ZONE 1	ZONE 2	ZONE 3
0			
3	X	X	
5	X		X
6		X	X
7	X	X	X

NOTE: Only for GFW with CTs present and outputs OUT1...OUT3 with slow cycle time (1...200sec)

681	I.HEU	R/W	Maximum current for heuristic power control	0.0 ...999,9 A		0,0

HETEROGENEOUS POWER CONTROL

This function matches that of a thermal cutout that disconnects the load based on instantaneous input. The load is disconnected based on a preset priority.

Zone 1 has priority: in case of overload, zone 3 is disconnected, followed by zone 2, etc.

682	hd.4	R/W	*Enable heterogeneous power control*	*Table for enabling heterogeneous power*	0

	ZONE 1	ZONE 2	ZONE 3
0			
1	X		
2		X	
3	X	X	
4			X
5	X		X
6		X	X
7	X	X	X

683	I.HEt	R/W	Maximum current for heterogeneous power control	0.0 ...999,9 A		0,0

VIRTUAL INSTRUMENT CONTROL

Virtual instrument control is activated by means of parameter hd.1.

By setting parameters S.In and S.Ou you can enable the writing of some parameters via serial line, set the value of inputs and the state of outputs.

You have to enable alarm setpoints AL1, ..., AL4 when write operations are continuous, and you don't have to keep the last value in eeprom.

Enabling the PV input means being able to exclude the local Tc or RTD acquisition and replace it with the value written in the register VALUE_F.

Enabling digital input IN lets you set the state of this input, for example to run MAN/AUTO switching with the writing of bit 7 in the register V_IN_OUT.

Likewise, you can set the on/off state of outputs OUT1, ..., OUT10 and of the LEDs by writing bits in the register V_IN_OUT.

191	hd.1	R/W	Enable multiset instrument control via serial	Table for multiset/ virtual instrument		0

	Enable Multiset	Enable virtual instrument
0		
1	X	
2		X
3	X	X

224	S.In	R/W	Control inputs from serial	0 ... 255		0 zone1	0 zone2	0 zone3

Inputs	In.A	In.5	In.4	In.3	In.2	-	In.1	AL4	AL3	AL2	AL1
Bit	10	9	8	7	6	5	4	3	2	1	0

225	S.Ou	R/W	Control outputs from serial	0 ... 1023		0

Outputs	Out10	Out9	Out8	Out7	Out6	Out5	Out4	Out3	Out2	Out1
Bit	9	8	7	6	5	4	3	2	1	0

628	S.LI	R/W	Control LEDs and digital inputs from serial	0 ... 1023		0

	Input					LED				
	D2	D1	out4	out3	out2	out1	DI2	DI1	ER	RN
Bit	9	8	7	6	5	4	3	2	1	0

Table of virtual register addresses

Parameter	bit	Resource enabled	Address of image register	Format	Name of register
S.In	0 (**)	Alarm setpoint AL1	341	word	AL1_RAM (**)
	1 (**)	Alarm setpoint AL2	342	word	AL2_RAM (**)
	2 (**)	Alarm setpoint AL3	343	word	AL3_RAM (**)
	3 (**)	Alarm setpoint AL4	321	word	AL4_RAM (**)
	4	Input In.1	347	word	SERIAL_IN1 (**)
	6 (**)	Input In.2	348	word	SERIAL_IN2 (**)
	7 (**)	Input In.3	578	word	SERIAL_IN3 (**)
	8 (**)	Input In.4	579	word	SERIAL_IN4 (**)
	9 (**)	Input In.5	580	word	SERIAL_IN5 (**)
	10 (**)	Input In.A	581	word	SERIAL_INA (**)
S.Ou	0	Output OUT 1	344	word, bit 0	V_IN_OUT
	1	Output OUT 2	344	word, bit 1	V_IN_OUT
	2	Output OUT 3	344	word, bit 2	V_IN_OUT
	4	Output OUT 5 (relays)	344	word, bit 4	V_IN_OUT
	4	Output OUT 5 (continuous)	639	word	SERIAL_OUT5C*
	5	Output OUT 6 (relays)	344	word, bit 5	V_IN_OUT
	5	Output OUT 6 (continuous)	640	word	SERIAL_OUT6C*
	6	Output OUT 7 (relays)	344	word, bit 6	V_IN_OUT
	6	Output OUT 7 (continuous)	641	word	SERIAL_OUT7C*
	7	Output OUT 8 (relays)	344	word, bit 7	V_IN_OUT
	7	Output OUT 8 (continuous)	642	word	SERIAL_OUT8C*
	8	Output OUT 9	344	word, bit 8	V_IN_OUT
	9	Output OUT 10	344	word, bit 9	V_IN_OUT
S.LI	0	Led RN	351	word, bit 0	V_X_LEDS
	1	Led ER	351	word, bit 1	V_X_LEDS
	2	Led D1	351	word, bit 2	V_X_LEDS
	3	Led D2	351	word, bit 3	V_X_LEDS
	4	Led O1	351	word, bit 4	V_X_LEDS
	5	Led O2	351	word, bit 5	V_X_LEDS
	6	Led O3	351	word, bit 6	V_X_LEDS
	7	Led O4	351	word, bit 7	V_X_LEDS
	8	Input D1	344	word, bit 10	V_IN_OUT
	9	Input D2	344	word, bit 11	V_IN_OUT

HW/SW INFORMATION

The following data registers can be used to identify the controller HW/SW and check its operation.

122	UPd	R	*Software version code*
85	Err	R	*Self-diagnosis* **error code for main input**
606	Er.2	R	*Self-diagnosis* **error code for auxiliary input 2**
550	Er.3	R	*Self-diagnosis* **error code for auxiliary input 3**
551	Er.4	R	*Self-diagnosis* **error code for auxiliary input 4**
552	Er.5	R	*Self-diagnosis* **error code for auxiliary input 5**

Table of main input errors

0	No Error
1	Lo (process variable value < Lo.S)
2	Hi (process variable value > Hi.S)
3	ERR [third wire interrupted for PT100 or input values below minimum limits (ex. for TC with connection error)]
4	SBR (probe interrupted or input values beyond maximum limits)

190	C.Hd	R	Hardware configuration codes

Table of hardware configuration codes

bit	
0	= 1 COOL OUTPUT absent
1	= 1 COOL OUTPUT relay
2	= 1 COOL OUTPUT logic
3	= 1 COOL OUTPUT continuous 0...20mA / 0...10V
4	= 1 COOL OUTPUT triac 250Vac 1A
5	-
6	= GFW-M no power
7	= 1 GFW-M 40A
8	= 1 GFW-M 60A
9	= 1 GFW-M 100A
10	= 1 GFW-M 150A
11	= 1 GFW-M 200A
12	= 1 GFW-M 250A
13	= 1 GFW-M El.Fuse

508	C.Hd1	R	Hardware configuration codes 1

Table of hardware configuration codes 1

bit	
0	= 1 INPUT AUX absent
1	= 1 INPUT AUX TC / 60mV
2	-
3	= 1 FIELDBUS ETH4 (ProfiNet)
4	= 1 FIELDBUS ETH5
5	= 1 FIELDBUS ETH6
6	= 1 FIELDBUS absent
7	= 1 FIELDBUS Modbus
8	= 1 FIELDBUS Profibus
9	= 1 FIELDBUS CanOpen
10	= 1 FIELDBUS DeviceNet
11	= 1 FIELDBUS Ethernet
12	= 1 FIELDBUS Euromap66
13	= 1 FIELDBUS ETH3
14	= 1 FIELDBUS ETH2 (Ethercat)
15	= 1 FIELDBUS ETH1 (Ethernet IP)

543	C.Hd2	R	Hardware configuration codes 2

Table of hardware configuration codes 2

bit	
0	= 1 GFW-E1 no power
1	= 1 GFW-E1 40A
2	= 1 GFW-E1 60A
3	= 1 GFW-E1 100A
4	= 1 GFW-E1 150A
5	= 1 GFW-E1 200A
6	= 1 GFW-E1 250A
7	= 1 GFW-E1 El. Fuse
8	= 1 GFW-E2 no power
9	= 1 GFW-E2 40A
10	= 1 GFW-E2 60A
11	= 1 GFW-E2 100A
12	= 1 GFW-E2 150A
13	= 1 GFW-E2 200A
14	= 1 GFW-E2 250A
15	= 1 GFW-E2 El. Fuse

693 697	UPd.F	R	**Fieldbus software version**
695	Cod.F	R	**Fieldbus node**
696	bAU.F	R	**Fieldbus baudrate**

Profibus	
bAu.F	**baudrate**
0	**12.00 Mbit/s**
1	**6.00 Mbit/s**
2	**3.00 Mbit/s**
3	**1.50 Mbit/s**
4	**500.00 Kbit/s**
5	**187.50 Kbit/s**
6	**93.75 Kbit/s**
7	**45.45 Kbit/s**
8	**19.20 Kbit/s**
9	**9.60 Kbit/s**

Canopen	
bAu.F	**baudrate**
0	**1000 Kbit/s**
1	**800 Kbit/s**
2	**500 Kbit/s**
3	**250 Kbit/s**
4	**125 Kbit/s**
5	**100 Kbit/s**
6	**50 Kbit/s**
7	**20 Kbit/s**
8	**10 Kbit/s**

Devicenet	
bAu.F	**baudrate**
0	**125 Kbit/s**
1	**250 Kbit/s**
2	**500 Kbit/s**

Ethernet	
bAu.F	**baudrate**
0	**100 Mbit/s**
1	**10 Mbit/s**

346		R	*Jumper*

Table of jumper states

bit		OFF	ON
0	State jumper S1		
1	State jumper S2		
2	State jumper S7-1: (*)		
3	State jumper S7-2: (*)		
4	State jumper S7-3: (*)		
5	State jumper S7-4: (*)		
6	State jumper S7-5:	resistive load	inductive load
7	State jumper S7-6:	-	Configuration parameters of default
8	State jumper S7-7:	GFX4/GFW	Simulation 4 GFX

S7- 1	**S7- 2**	**S7- 3**	**S7- 4**	**(*) FUNCTION MODES**
OFF	OFF	OFF	OFF	3 single-phase loads
OFF	ON	OFF	OFF	3 independent single-phase loads in open delta
ON	ON	OFF	OFF	3-phase load open delta / star with neutral
ON	ON	ON	OFF	3-phase load closed delta
ON	OFF	OFF	ON	3-phase star load without neutral
ON	OFF	OFF	OFF	3-phase star load without neutral with BIFASE control
ON	OFF	ON	OFF	3-phase closed star load with BIFASE control

120		R	Manufact - Trade Mark (Gefran)	Name of manufacturer	5000
121		R	Device ID (GFW)	Product ID	214

197	Ld.St	R/W	*RN LED status function*	16
619	Ld.2	R/W	*ER LED status function*	12
620	Ld.3	R/W	Function of LED DI1	6
621	Ld.4	R/W	Function of LED DI2	11

Table of LED functions

Val.	Function
0	RUN
1	MAN/AUTO controller
2	LOC / REM
3	HOLD
4	Selftuning on
5	Autotuning on
6	Repeat digital input INDIG1
7	Serial 1 dialog
8	State of OUT 2 zone 1
9	Softstart running
10	Indication of SP1...SP2 (SP1 with pilot input inactive and LED off)
11	Repeat digital input INDIG2
12	Input in error (LO, Hi, Err, Sbr)
13	Serial 2 dialog
14	Repeat digital input INDIG3
+ 16	LED flashing if active (code 8 excluded)

622	Ld.5	R/W	Function of LED O1	1
623	Ld.6	R/W	Function of LED O2	2
624	Ld.7	R/W	Function of LED O3	3
625	Ld.8	R/W	Function of LED Button	4

Table of OUT LED functions

0	Disabled
1	Repetition of state OUT 1
2	Repetition of state OUT 2
3	Repetition of state OUT 3
4	State key
5	Repetition of state OUT 5
6	Repetition of state OUT 6
7	Repetition of state OUT 7
8	Repetition of state OUT 8
9	Repetition of state OUT 9
10	Repetition of state OUT 10

+ 16 LED flashing if active

LED status refers to the corresponding parameter, with the following special cases:
- LED RN (green) on: hotkey functionality
- LED RN (green) + LED ER (red) both flashing rapidly: autobaud in progress
- LED ER (red) on: error in one of main inputs (Lo, Hi, Err, Sbr)
- LED ER (red) flashing: temperature alarm ((OVER_HEAT or TEMPERATURE_SENSOR_BROKEN) or alarm of SHORT_CIRCUIT_CURRENT or SSR_SAFETY or FUSE_OPEN (only for singlephase configuration).
- LED ER (red) + LED Ox (yellow) both flashing: HB alarm or POWER_FAIL in zone x
- All LEDs flashing rapidly: ROTATION123 alarm (only for threephase configuration)
- All LEDs flashing rapidly except LED DI1: jumper configuration not provided
- All LEDs flashing rapidly except LED DI2: 30%_UNBALANCED_ERROR alarm (only for threephase configuration)
- All LEDs flashing rapidly except LED O1: SHORT_CIRCUIT_CURRENT alarm (only for threephase configuration)
- All LEDs flashing rapidly except LED O2: TRIPHASE_MISSING_LINE_ERROR alarm (only for threephase configuration)
- All LEDs flashing rapidly except LED O3: SSR_SAFETY alarm (only for threephase configuration)
- All LEDs flashing rapidly except LED BUT: FUSE_OPEN alarm (only for threephase configuration)

305*		R/W	Current state (STATUS_W)	*Table of state settings*	0 zone1	0 zone2	0 zone3
698*		R	State saved in eeprom (STATUS_W_EEP)		0 zone1	0 zone2	0 zone3

bit	
0	-
1	Select SP1/SP2 (*)
2	Start/Stop Selftuning (*)
3	Select ON/OFF
4	Select AUTO/MAN
5	Start/Stop Autotuning (*)
6	Select LOC/REM (*)

(*) only for zone 1 (GFW-M)

467*		R	State (STATUS)

Table of state

bit	
0	AL.1 or AL.2 or AL.3 or AL.4 or ALHB.TA1 or ALHB.TA2 or ALHB.TA3 or Power Fault
1	Input Lo
2	Input Hi
3	Input Err
4	Input Sbr
5	heat
6	cool
7	LBA
8	AL.1
9	AL.2
10	AL.3
11	AL.4
12	ALHB or Power Fault
13	ON/OFF
14	AUTO/MAN
15	LOC/REM

469*		R	State 1 (STATUS1)

Table of state 1

bit	
0	AL.1 or AL.2 or AL.3 or AL.4 or ALHB.TA1 or ALHB.TA2 or ALHB.TA3 or Power Fault
1	Input Lo
2	Input Hi
3	Input Err
4	Input Sbr
7	LBA
8	AL.1
9	AL.2
10	AL.3
11	AL.4
12	ALHB.TA1
13	ALHB.TA2
14	ALHB.TA3
15	Selftuning on

632*		R	State 2 (STATUS2)

Table of state 2

bit	
0	AL.1
1	AL.2
2	AL.3
3	AL.4
4	AL.HB1
5	AL.HB2
6	AL.HB3
7	AL.Lo
8	AL.Hi
9	AL.Err
10	AL.Sbr
11	AL.LBA
12	AL.Power

633		R	State 3 (STATUS3)	*Table of state 3*

bit	
3	AL.SSR short 1
4	AL.SSR short 2
5	AL.SSR short 3
6	No voltage 1
7	No voltage 2
8	No Voltage 3
9	No current 1
10	No current 2
11	No current 3

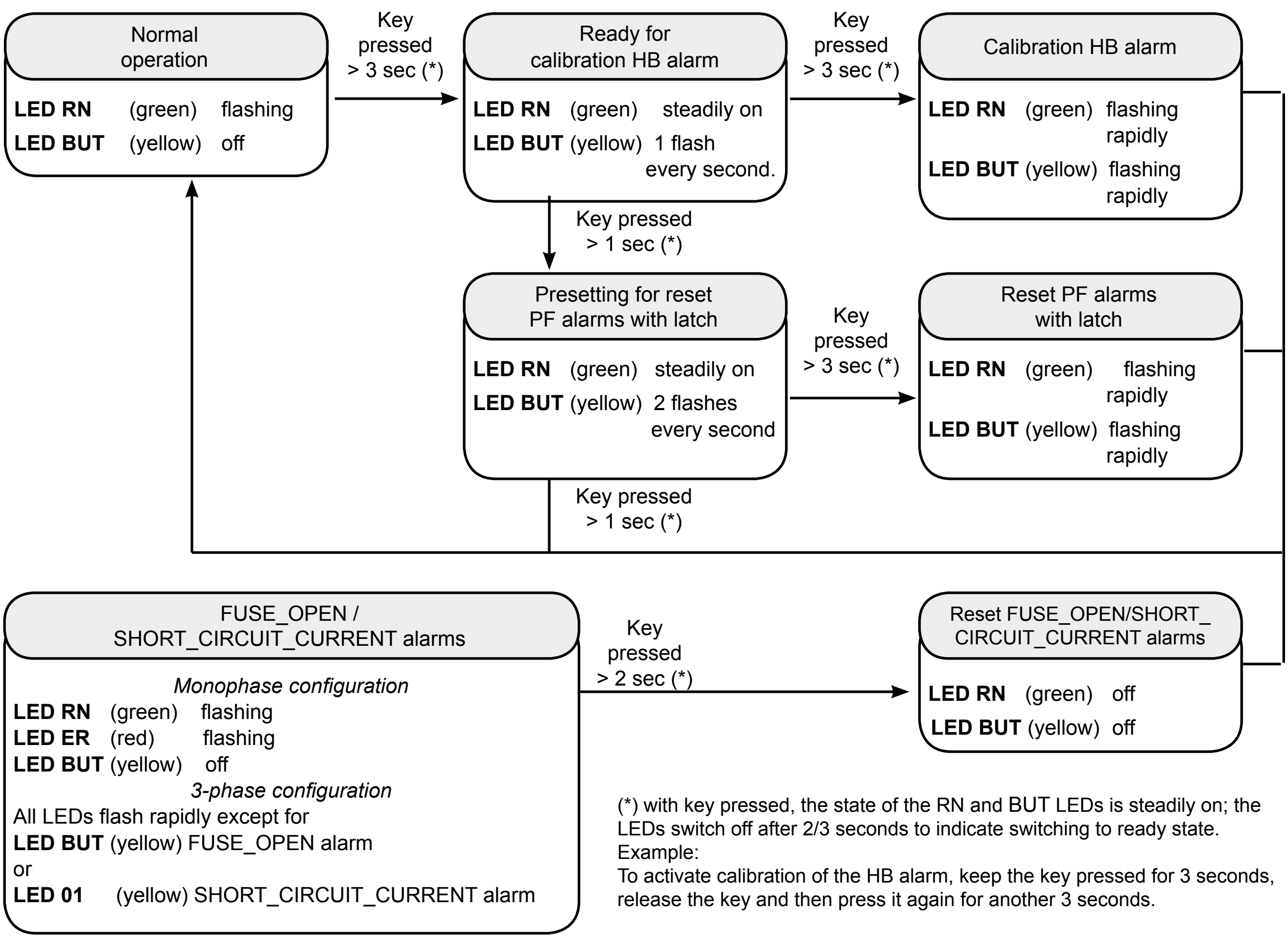
634		R	State 4 (STATUS4)	*Table of state 4*

bit	
0	Temperature sensor broken
1	over heat
2	phase_softstart_active
3	phase_softstart_end
4	frequency_warning or monophase_missing_line_warning
5	60Hz
6	short_circuit_current in softstart di fase
7	over_peak_current in softstart di fase
8	over_rms_current a regime
9	SSR_Safety (24V fan presence or SSR hardware over temperature)
10	Fuse open
11	Current polarity check
12	over_peak_current_projection in softstart di fase

702		R	**Voltage status**	*Table of voltage status*

bit	
0	frequency_warning
1	10% unbalanced_line_warning
2	20% unbalanced_line_warning
3	30% unbalanced_line_warning
4	rotation123_error
5	three-phase_missing_line_error
6	60Hz

Functionality key



(*) with key pressed, the state of the RN and BUT LEDs is steadily on; the LEDs switch off after 2/3 seconds to indicate switching to ready state.
Example:
To activate calibration of the HB alarm, keep the key pressed for 3 seconds, release the key and then press it again for another 3 seconds.

INSTRUMENT CONFIGURATION SHEET

PARAMETERS

INSTALLATION OF MODBUS SERIAL NETWORK

Definition of parameter				Note	Assigned value
46	Cod	R	Device identification code		
45	bAu	R/W	Select Baudrate - Serial 1		
626	bAu.2	R/W	Select Baudrate - Serial 2		
47	PAr	R/W	Select parity - Serial 1		
627	PAr.2	R/W	Select parity - Serial 2		

ANALOG INPUT

Definition of parameter				Note	Assigned value
573	tP.A	R/W	analog input		
574	L.S.A	R/W	Minimum scale limit analog input		
575	H.S.A	R/W	Maximum scale limit analog input		
577	oFS.A	R/W	Offset correction for analog input		
572	In.A	R	Value of the ingegneristico reading analog input		
576	FLt.A	R/W	Low pass digital filter analog input		

MAIN INPUT PID

Definition of parameter				Note	Assigned value
400	tYP.	R/W	Probe, signal, enable, custom linearization and main input scale		
403	dP.S	R/W	Decimal point position for input scale		
401	Lo.S	R/W	Minimum scale limit for main input		
402	HI.S	R/W	Maximum scale limit for main input		
519 23	oFS.	R/W	Main input offset correction		
0 470	P.V.	R	Read of process variable (PV) engineering value		
349	DPV	R	Read of engineering value of process variable (PV) filtered by FLd		
85	Err	R	Self-diagnosis error code for main input		
24	FLt	R/W	low pass digital filter for input signal		
179	FLd	R/W	Digital filter on oscillations of input signal		
86	S.00	R/W	Engineering value attributed to Point 0 (minimum value of input scale)		
87	S.01	R/W	Engineering value attributed to Point 1		
88	S.02	R/W	Engineering value attributed to Point 2		
89	S.03	R/W	Engineering value attributed to Point 3		

90	5.04	R/W	Engineering value attributed to Point 4			
91	5.05	R/W	Engineering value attributed to Point 5			
92	5.06	R/W	Engineering value attributed to Point 6			
93	5.07	R/W	Engineering value attributed to Point 7			
94	5.08	R/W	Engineering value attributed to Point 8			
95	5.09	R/W	Engineering value attributed to Point 9			
96	5.10	R/W	Engineering value attributed to Point 10			
97	5.11	R/W	Engineering value attributed to Point 11			
98	5.12	R/W	Engineering value attributed to Point 12			
99	5.13	R/W	Engineering value attributed to Point 13			
100	5.14	R/W	Engineering value attributed to Point 14			
101	5.15	R/W	Engineering value attributed to Point 15			
102	5.16	R/W	Engineering value attributed to Point 16			
103	5.17	R/W	Engineering value attributed to Point 17			
104	5.18	R/W	Engineering value attributed to Point 18			
105	5.19	R/W	Engineering value attributed to Point 19			
106	5.20	R/W	Engineering value attributed to Point 20			
107	5.21	R/W	Engineering value attributed to Point 21			
108	5.22	R/W	Engineering value attributed to Point 22			
109	5.23	R/W	Engineering value attributed to Point 23			
110	5.24	R/W	Engineering value attributed to Point 24			
111	5.25	R/W	Engineering value attributed to Point 25			
112	5.26	R/W	Engineering value attributed to Point 26			
113	5.27	R/W	Engineering value attributed to Point 27			
114	5.28	R/W	Engineering value attributed to Point 28			
115	5.29	R/W	Engineering value attributed to Point 29			
116	5.30	R/W	Engineering value attributed to Point 30			
117	5.31	R/W	Engineering value attributed to Point 31			

118	S.32	R/W	Engineering value attributed to Point 32 (maximum value of input scale))	
293	S.33	R/W	Engineering value attributed to minimum value of the input scale	
294	S.34	R/W	Engineering value attributed to maximum value of the input scale.	
295	S.35	R/W	Engineering value of input signal corresponding to temperature of 50°C.	

LOAD CURRENT VALUE

746*	L.tA1	R	Minimum limit of CT ammeter input scale (phase1)	
747	L.tA2	R	Minimum limit of CT ammeter input scale (phase 2)	With 3-phase load
748	L.tA3	R	Minimum limit of CT ammeter input scale (phase 3)	With 3-phase load
405*	H.tA1	R	Maximum limit of CT ammeter input scale (phase 1)	
413	H.tA2	R	Maximum limit of CT ammeter input scale (phase 2)	With 3-phase load
414	H.tA3	R	Maximum limit of CT ammeter input scale (phase 3)	With 3-phase load
220*	o.tA1	R/W	Offset correction CT input (phase 1)	
415	o.tA2	R/W	Offset correction CT input (phase 2)	
416	o.tA3	R/W	Offset correction CT input (phase 3)	
227* 473 - 139	I.tA1	R	Instantaneous CT input value (phase 1)	
490	I.tA2	R	Instantaneous CT input value (phase 2)	With 3-phase load
491	I.tA3	R	Instantaneous CT input value (phase 3)	With 3-phase load
468*	I.1on	R	CT input value with output on (phase 1)	
498	I.2on	R	CT input value with output on (phase 2)	With 3-phase load
499	I.3on	R	CT input value with output on (phase 3)	With 3-phase load
219*	Ft.tA	R/W	CT input digital filter (phases 1, 2 and 3)	
709*	I.tAP	R	Peak ammeter input during phase softstart ramp	
716*	coS.F	R	Power factor in hundredths	
753*	Ld.A	R	Current on load	
754	Ld.At	R	Current on 3-phase load	

VALUE OF LOAD VOLTAGE

751*	Ld.U	R	Voltage on load
752	Ld.Ut	R	Voltage on 3-phase load

LINE VOLTAGE VALUE

453*	L.tV 1	R	Minimum limit of TV voltmeter input scale (phase1)	
454	L.tV2	R	Minimum limit of TV voltmeter input scale (phase 2)	With 3-phase load
455	L.tV3	R	Minimum limit of TV voltmeter input scale (phase 3)	With 3-phase load
410*	H.tV 1	R	Maximum limit of TV voltmeter input scale (phase 1)	
417	H.tV2	R	Maximum limit of TV voltmeter input scale (phase 2)	With 3-phase load
418	H.tV3	R	Maximum limit of CT voltmeter input scale (phase 3)	With 3-phase load
411*	o.tU 1	R/W	Offset correction voltmeter transformer input TV (phase 1)	
419	o.tU2	R/W	Offset correction voltmeter transformer input TV (phase 2)	With 3-phase load
420	o.tU3	R/W	Offset correction voltmeter transformer input TV (phase 3)	With 3-phase load
232* 485	I.tU 1	R	Voltmeter input value (phase 1)	
492	I.tU2	R	Voltmeter input value (phase 2)	With 3-phase load
493	I.tU3	R	Voltmeter input value (phase 3)	With 3-phase load
322*	I.UF 1	R	Value filtered Voltmeter input (phase 1)	
496	I.UF2	R	Value filtered Voltmeter input (phase 2)	With 3-phase load
497	I.UF3	R	Value filtered Voltmeter input (phase 3)	With 3-phase load
412*	Ft.tU	R/W	Digital filter TV auxiliary input (phase 1, 2, 3)	
315*	FrEq	R	Voltage frequency in tenths of Hz	

POWER ON LOAD

719*	Ld.P	R	Power on load	
720	Ld.P.t	R	Power on 3-phase load	
749*	Ld. I	R	Impedance on load	
750	Ld. I.t	R	Impedance on 3-phase load	
531*	Ld.E 1	R	Energia sul carico	
541	Ld.E I.t	R	Energia sul carico trifase	
510*	Ld.E2	R	Energia sul carico	
541	Ld.E2.t	R	Energia sul carico trifase	
114* bit	Azzeramento Ld.E 1	R/W	OFF = - ON = Azzeramento Ld.E1	
115* bit	Azzeramento Ld.E2	R/W	OFF = - ON = Azzeramento Ld.E2	

AUXILIARY ANALOG INPUTS (LIN/TC)

194	AI.2	R/W	Select type of auxiliary input sensor 2		
553	AI.3	R/W	Select type of auxiliary sensor input 3		
554	AI.4	R/W	Select type of auxiliary sensor input 4		
555	AI.5	R/W	Select type of auxiliary sensor input 5		
181	tP.2	R/W	Definition of auxiliary analog input function 2		
677	dP.2	R/W	Decimal point position for auxiliary input scale 2		
568	dP.3	R/W	Decimal point position for the auxiliary input scale 3		
569	dP.4	R/W	Decimal point position for the auxiliary input scale 4		
570	dP.5	R/W	Decimal point position for the auxiliary input scale 5		
404	LS.2	R/W	Minimum limit auxiliary input scale		
556	LS.3	R/W	Minimum limit of auxiliary input scale 3		
557	LS.4	R/W	Minimum limit of auxiliary input scale 4		
558	LS.5	R/W	Minimum limit of auxiliary input scale 5		
603	HS.2	R/W	Maximum limit auxiliary input scale 2		
559	HS.3	R/W	Maximum limit of auxiliary input scale 3		
560	HS.4	R/W	Maximum limit of auxiliary input scale 4		
561	HS.5	R/W	Maximum limit of auxiliary input scale 5		
605	oFS.2	R/W	Offset correction for auxiliary input 2		
565	oFS.3	R/W	Offset for auxiliary input correction 3		
566	oFS.4	R/W	Offset for auxiliary input correction 4		
567	oFS.5	R/W	Offset for auxiliary input correction 5		
602	In.2	R	Value of auxiliary input 2		
547	In.3	R	Value of auxiliary input 3		
548	In.4	R	Value of auxiliary input 4		
549	In.5	R	Value of auxiliary input 5		
606	Er.2	R	Error code for self-diagnosis of auxiliary input 2		
550	Er.3	R	Error code for self-diagnosis of auxiliary input 3		
551	Er.4	R	Error code for self-diagnosis of auxiliary input 4		
552	Er.5	R	Error code for self-diagnosis of auxiliary input 5		
604	FLt.2	R/W	Digital filter for auxiliary input 2		
562	FLt.3	R/W	Digital filter for auxiliary input 3		

563	FLt.4	R/W	Digital filter for auxiliary input 4			
564	FLt.5	R/W	Digital filter for auxiliary input 5			

DIGITAL INPUTS

140	dIG.	R/W	Function of digital input			
618	dIG.2	R/W	Function of digital input 2			
694	dIG.3	R/W	Digital input 3 function			
317		R	State of digital inputs INPUT DIG			
68 bit	STATE OF DIGITAL INPUT 1	R	OFF = Digital input 1 off ON = Digital input 1 on			
92 bit	STATE OF DIGITAL INPUT 2	R	OFF = Digital input 2 off ON = Digital input 2 on			
67 bit	STATE of DIGITAL INPUT 3	R	OFF = Digital input 3 off ON = Digital input 3 on			
518	In.PWM	R	PWM input value			

GENERIC ALARMS AL1, AL2, AL3 and AL4

215	A1.r	R/W	Select reference variable alarm 1			
216	A2.r	R/W	Select reference variable alarm 2			
217	A3.r	R/W	Select reference variable alarm 3			
218	A4.r	R/W	Select reference variable alarm 4			
12 475 - 177	AL.1	R/W	Setpoint alarm 1 (scale points)			
13 476 - 178	AL.2	R/W	Setpoint alarm 2 (scale points)			
14 52 - 479	AL.3	R/W	Setpoint alarm 3 (scale points)			
58 480	AL.4	R/W	Setpoint alarm 4 (scale points)			
27 187	HY.1	R/W	Hysteresis for alarm 1			
30 188	HY.2	R/W	Hysteresis for alarm 2			
53 189	HY.3	R/W	Hysteresis for alarm 3			
59	HY.4	R/W	Hysteresis for alarm 4			
406	A1.t	R/W	Alarm type 1			
407	A2.t	R/W	Alarm type 2			
408 54	A3.t	R/W	Alarm type 3			
409	A4.t	R/W	Alarm type 4			
46 bit	AL1 direct/inverse	R/W				
47 bit	AL1 absolute/relative	R/W				
48 bit	AL1 normal/symmetrical	R/W				
49 bit	AL1 disabled at switch on	R/W				
50 bit	AL1 with memory	R/W				

54 bit	AL2 direct/inverse	R/W	
55 bit	AL2 absolute/relative	R/W	
56 bit	AL2 normal/symmetrical	R/W	
57 bit	AL2 disabled at switch on	R/W	
58 bit	AL2 with memory	R/W	
36 bit	AL3 direct/inverse	R/W	
37 bit	AL3 absolute/relative	R/W	
38 bit	AL3 normal/symmetrical	R/W	
39 bit	AL3 disabled at switch on	R/W	
40 bit	AL3 with memory	R/W	
70 bit	AL4 direct/inverse	R/W	
71 bit	AL4 absolute/relative	R/W	
72 bit	AL4 normal/symmetrical	R/W	
73 bit	AL4 disabled at switch on	R/W	
74 bit	AL4 with memory	R/W	
25 20 - 28 - 142	Lo.L	R/W	Lowest settable limit SP, SP remote and absolute alarms
26 21 - 29 - 143	HI.L	R/W	Highest settable limit SP, SP remote and absolute alarms
195*	AL.n	R/W	Select number of enabled alarms
140	dIG.	R/W	Digital input function
618	dIG.2	R/W	Digital input function 2
79 bit	Reset alarm latch	R/W	
4 bit	STATE OF ALARM 1	R	OFF = Alarm off ON = Alarm on
5 bit	STATE OF ALARM 2	R	OFF = Alarm off ON = Alarm on
62 bit	STATE OF ALARM 3	R	OFF = Alarm off ON = Alarm on
69 bit	STATE OF ALARM 4	R	OFF = Alarm off ON = Alarm on
318		R	States of alarm ALSTATE IRQ

LBA ALARM (Loop Break Alarm)

195*	AL.n	R/W	Select number of enabled alarms
44	Lb.t	R/W	Delay time for LBA alarm activation
119	Lb.P	R/W	Limit of supplied power in presence of LBA alarm
81 bit	Reset LBA alarm	R/W	
8 bit	STATE OF LBA ALARM	R	OFF = LBA off ON = LBA alarm on

195*	AL.n	R/W	**Select number of enabled alarms**				
57*	Hb.F	R/W	**HB alarm function**				
56*	Hb.t	R/W	**Delay time for HB alarm activation**				
55*	A.Hb1	R/W	HB alarm setpoint (ammeter input scale points - Phase 1)				
502	A.Hb2	R/W	HB alarm setpoint (ammeter input scale points - Phase 2)	With three-phase load			
503	A.Hb3	R/W	HB alarm setpoint (ammeter input scale points - Phase 3)	With three-phase load			
737*	Hb.P	R/W	Percentage HB alarm setpoint of current read in HB calibration				
112* bit	Calibration HB alarm setpoint	R/W	OFF = Calibration not enabled ON = Calibration enabled				
742*	Hb.tA	R/W	CT read in HB calibration				
452*	Hb.tV	R/W	TV read in HB calibration				
743*	Hb.Pw	R/W	Ou.P power in calibration				
758*	Ir.tA.0	R/W	HB Calibration with IR lamp: current at 100% conduction				
759*	Ir.tA.1	R/W	HB Calibration with IR lamp: current at 50% conduction				
760*	Ir.tA.2	R/W	HB Calibration with IR lamp: current at 30% conduction				
761*	Ir.tA.3	R/W	HB Calibration with IR lamp: current at 20% conduction				
767*	Ir.tA.4	R/W	HB Calibration with IR lamp: current at 15% conduction				
768*	Ir.tA.5	R/W	HB Calibration with IR lamp: current at 10% conduction				
769*	Ir.tA.6	R/W	HB Calibration with IR lamp (only in mode PA): current at 5% conduction				
382*	Ir.tA.7	R/W	HB Calibration with IR lamp (only in mode PA): current at 3% conduction				
383*	Ir.tA.8	R/W	HB Calibration with IR lamp (only in mode PA): current at 2% conduction				
384*	Ir.tA.9	R/W	HB Calibration with IR lamp (only in mode PA): current at 1% conduction				
445*	Ir.tV.0	R/W	HB Calibration with IR lamp: voltage at 100% conduction				
446*	Ir.tV.1	R/W	HB Calibration with IR lamp: voltage at 50% conduction				
447*	Ir.tV.2	R/W	HB Calibration with IR lamp: voltage at 30% conduction				
448*	Ir.tV.3	R/W	HB Calibration with IR lamp: voltage at 20% conduction				
449*	Ir.tV.4	R/W	HB Calibration with IR lamp: voltage at 15% conduction				
450*	Ir.tV.5	R/W	HB Calibration with IR lamp: voltage at 10% conduction				

451*	Ir.tV.6	R/W	HB Calibration with IR lamp (only in mode PA): voltage at 5% conduction					
390*	Ir.tV.7	R/W	HB Calibration with IR lamp (only in mode PA): voltage at 3% conduction					
391*	Ir.tV.8	R/W	HB Calibration with IR lamp (only in mode PA): voltage at 2% conduction					
392*	Ir.tV.9	R/W	HB Calibration with IR lamp (only in mode PA): voltage at 1% conduction					
744*	Hb.tr	R	HB alarm setpoint as function of power on load					
26* bit	STATE OF HB ALARM or POWER_FAULT	R	OFF = Alarm off ON = Alarm on					
76* bit	State of HB alarm phase 1TA	R	OFF = Alarm off ON = Alarm on					
77 bit	State of HB alarm phase 2TA	R	OFF = Alarm off ON = Alarm on					
78 bit	State of HB alarm phase 3TA	R	OFF = Alarm off ON = Alarm on					
504		R	States of alarm HB ALSTATE_HB (for 3-phase loads)					
512*		R	States of alarm ALSTATE (for single-phase loads)					
318*		R	State of alarms ALSTATE IRQ					

ALARM SBR - ERR (Probe in short or connection error)

229	rEL	R/W	Fault action (in case of broken probe) Sbr, Err Only for main input			
228	FA.P	R/W	Fault action power (supplied in condition of broken probe)			
85	Err	R	Self-diagnosis error code for main input			
9 bit	STATE OF INPUT IN SBR	R	OFF = - ON = Input in SBR			

Power Fault ALARMS (SSR_SHORT, NO_VOLTAGE and NO_CURRENT)

660*	hd.2	R/W	Enable POWER_FAULT alarms	
661	dG.t	R/W	Refresh rate SSR-SHORT	
662*	dG.F	R/W	Time filter for alarms NO_VOLTAGE and NO_CURRENT	
105 bit	Reset SSR_SHORT / NO_ VOLTAGE / NO_CUR- RENT alarms	R/W		
96* bit	State of alarm SSR_SHORT phase 1	R	OFF = Alarm off ON = Alarm on	
97 bit	State of alarm SSR_SHORT phase 2	R	OFF = Alarm off ON = Alarm on	With 3-phase load
98 bit	State of alarm SSR_SHORT phase 3	R	OFF = Alarm off ON = Alarm on	With 3-phase load
99* bit	State of alarm NO_VOLTAGE phase 1	R	OFF = Alarm off ON = Alarm on	
100 bit	State of alarm NO_VOLTAGE phase 2	R	OFF = Alarm off ON = Alarm on	With 3-phase load
101 bit	State of alarm NO_VOLTAGE phase 3	R	OFF = Alarm off ON = Alarm on	With 3-phase load
102* bit	State of alarm NO_CURRENT phase 1	R	OFF = Alarm off ON = Alarm on	
103 bit	State of alarm NO_CURRENT phase 2	R	OFF = Alarm off ON = Alarm on	With 3-phase load
104 bit	State of alarm NO_CURRENT phase 3	R	OFF = Alarm off ON = Alarm on	With 3-phase load

ALARM due to overload

655*		R	INNTC_SSR
534*		R	INNTC_LINE
535*		R	INNTC_LOAD

FUSE_OPEN AND SHORT_CIRCUIT_CURRENT ALARMS

456	Fr.n	R/W	*Number of replay in case of FUSE_OPEN / SHORT_ CIRCUIT_CURRENT*
109* bit	FUSE_OPEN / SHORT_ CIRCUIT_CURRENT RESET ALARMS	R/W	OFF = - ON = Alarms reset FUSE_OPEN / SHORT_CIRCUIT_CURRENT
634*		R	State 4 (STATUS4)

OUTPUTS

160*	rL.1	R/W	Allocation of reference signal		
163*	rL.2	R/W	Allocation of reference signal		
166*	rL.3	R/W	Allocation of reference signal		
170*	rL.4	R/W	Allocation of reference signal		
171*	rL.5	R/W	Allocation of reference signal		
172*	rL.6	R/W	Allocation of reference signal		
152* 9	Ct.1	R/W	OUT 1 (Heat) cycle time		
159*	Ct.2	R/W	OUT 2 (Cool) cycle time		
308* 319		R	State rL.x (MASKOUT_RL)		
12* bit	STATE rL.1	R	OFF = Signal off ON = Signal on		
13* bit	STATE rL.2	R	OFF = Signal off ON = Signal on		
14* bit	STATE rL.3	R	OFF = Signal off ON = Signal on		
15* bit	STATE rL.4	R	OFF = Signal off ON = Signal on		
16* bit	STATE rL.5	R	OFF = Signal off ON = Signal on		
17* bit	STATE rL.6	R	OFF = Signal off ON = Signal on		
607	out.1	R/W	Allocation of physical output OUT 1		
608	out.2	R/W	Allocation of physical output OUT 2		
609	out.3	R/W	Allocation of physical output OUT 3		
611	out.5	R/W	Allocation of physical output OUT 5		
612	out.6	R/W	Allocation of physical output OUT 6		
613	out.7	R/W	Allocation of physical output OUT 7		
614	out.8	R/W	Allocation of physical output OUT 8		
615	out.9	R/W	Allocation of physical output OUT 9		
616	out.10	R/W	Allocation of physical output OUT 10		
82 bit	State of output OUT1	R	OFF = Output off ON = Output on		
83 bit	State of output OUT2	R	OFF = Output off ON = Output on		
84 bit	State of output OUT3	R	OFF = Output off ON = Output on		
85 bit	State of output OUT4	R	OFF = Output off ON = Output on		
86 bit	State of output OUT5	R	OFF = Output off ON = Output on		
87 bit	State of output OUT6	R	OFF = Output off ON = Output on		
88 bit	State of output OUT7	R	OFF = Output off ON = Output on		
89 bit	State of output OUT8	R	OFF = Output off ON = Output on		

90 bit	State of output OUT9	R	OFF = Output off ON = Output on
91 bit	State of output OUT10	R	OFF = Output off ON = Output on
664		R	State outputs (MASKOUT_OUT)

SETPOINT SETTING

138 16 - 472	SP	R/W	Local setpoint		
181	tP.2	R/W	Auxiliary analog input function		
18 136 - 249	SP.r	R/W	Remote setpoint (SET Gradient for manual power correction)		
25 20 - 28 - 142	Lo.L	R/W	Lowest settable limit SP, SP remote and absolute alarms		
26 21 - 29 - 143	H I.L	R/W	Highest settable limit SP, SP remote and absolute alarms		
10 bit	LOCAL / REMOTE	R/W	OFF = Enable local setpoint ON = Enable remote setpoint		
305*		R/W	State (STATUS_W)		
1 137 - 481	SPA	R	Active setpoint		
4		R	Deviation (SPA - PV)		

SETPOINT CONTROL

234 22	G.SP	R/W	Set Gradient		
259	G.S2	R/W	Set Gradient for SP2		
265	Hot	R/W	Select special functions		
191	hd. 1	R/W	Enable multiset instrument control via serial		
230 482	SP. 1	R/W	Setpoint 1		
231 483	SP.2	R/W	Setpoint 2		
140	d IG.	R/W	Digital input function		
618	d IG.2	R/W	Digital input function 2		
75 bit	SELECT SP1 / SP2	R/W	OFF = Select SP1 ON = Select SP2		
305*		R/W	State (STATUS_W)		

PID HEAT/ COOL CONTROL

617*	SPU	R/W	Power reference
180	Ctr	R/W	Control type
5 148 - 149	h.Pb	R/W	Proportional band for heating or hysteresis ON/OFF
7 150	h. It	R/W	Integral heating time
8 151	h.dt	R/W	Derivative heating time
6	c.Pb	R/W	Proportional band for cooling or hysteresis ON/OFF
76	c. It	R/W	Integral cooling time
77	c.dt	R/W	Derivative cooling time
513	C.ME	R/W	Select cooling fluid
152 9	Ct. 1	R/W	Cycle time OUT 1 (Heat)
159	Ct.2	R/W	Cycle time OUT 2 (Cool)
2* 132 - 471	Ou.P	R	Value control outputs (+Heat / -Cool)
39 484	c.SP	R/W	Cooling setpoint relative to heating setpoint
78	rSt	R/W	Manual reset (value added to PID input)
516	P.rS	R/W	Reset power (value added directly to PID output)
79	Ar.S	R/W	Antireset (limits integral PID action)
80	FFd	R/W	Feedforward (value added to PID output after processing)
42 146	h.PH	R/W	Maximum limit heating power
254	h.PL	R/W	Min. limit heating power (not available for double action heat/cool)
43	c.PH	R/W	Maximum limit cooling power
255	c.PL	R/W	Min. limit cooling power (not available for double action heat/cool)
765*	P.PEr	R/W	Percentage of output power
766*	P.oFS	R/W	Offset of output power
763*	G.out	R/W	Gradient for output control
764*	Lo.P	R/W	Uscita minima di innesco

AUTOMATIC/MANUAL CONTROL

252*		R/W	MANUAL_POWER
2* 132 - 471	Ou.P	R	Value control outputs (+Heat / -Cool)
140	d IG.	R/W	Digital input function
618	d IG.2	R/W	Digital input function 2
1* bit	AUTO/MAN	R/W	OFF = Automatic ON =Manual
305*		R/W	State (STATUS_W)

HOLD FUNCTION

140	d IG.	R/W	Digital input function
618	d IG.2	R/W	Digital input function 2
64 bit	HOLD	R/W	OFF = hold off ON = hold on

MANUAL POWER CORRECTION

505*	r IF	R/W	Line voltage
506*	Cor	R/W	Manual power correction based on line voltage
18 136 - 249	SP.r	R/W	Remote setpoint (SET Gradient for power correction

AUTOTUNING

31	S.tu	R/W	Enable selftuning, autotuning, softstart
140	d IG.	R/W	Digital input function
618	d IG.2	R/W	Digital input function 2
29 bit	AUTOTUNING	R/W	OFF = Stop Autotuning ON = Start Autotuning
28 bit	AUTOTUNING STATE	R	OFF = Autotuning in Stop ON = Autotuning in Start
68 bit	DIGITAL INPUT STATE 1	R	OFF = Digital input 1 off ON = Digital input 1 on
92 bit	DIGITAL INPUT STATE 2	R	OFF = Digital input 2 off ON = Digital input 2 on
296		R	Enable autotuning and selftuning state (FLG_PID)
305*		R/W	State (STATUS_W)

SELFTUNING

31	S.tu	R/W	Enable selftuning, autotuning, softstart
140	dIG.	R/W	Digital input function
618	dIG.2	R/W	Digital input function 2
3 bit	SELFTUNING	R/W	OFF = Stop Selftuning ON = Start selftuning
0 bit	SELFTUNING STATE	R	OFF = Selftuning in Stop ON = Selftuning in Start
68 bit	DIGITAL INPUT STATE 1	R	OFF = Digital input 1 off ON = Digital input 1 on
92 bit	DIGITAL INPUT STATE 2	R	OFF = Digital input 2 off ON = Digital input 2 on
296		R	Enable autotuning and selftuning state (FLG_PID)
305*		R/W	State (STATUS_W)

SOFTSTART

31	S.tu	R/W	Enable selftuning, autotuning, softstart
147	SoF	R/W	Softstart time
63 bit	SOFTSTART STATE	R	OFF = Softstart off ON = Softstart on

START MODE

699*	P.ont	R/W	Start mode at Power-On

SOFTWARE SHUTDOWN

140	dIG.	R/W	Digital input function
618	dIG.2	R/W	Digital input function 2
700	oFF.t	R/W	Software OFF
11 bit	SOFTWARE ON/OFF	R/W	OFF = On software ON =Off software
68 bit	DIGITAL INPUT STATE 1	R	OFF = Digital input 1 off ON = Digital input 1 on
92 bit	DIGITAL INPUT STATE 2	R	OFF = Digital input 2 off ON = Digital input 2 on
305*		R/W	State (STATUS_W)

FAULT ACTION POWER

265	Hot	R/W	Select special functions
228	F.A.P	R/W	Fault action power (supplied in conditions of broken probe)
26* bit	STATE OF HB ALARM OR POWER_FAULT	R	OFF = Alarm off ON = Alarm on
80 bit	State of power alarm (special function)	R	OFF = Alarm off ON = Alarm on

POWER ALARM

261	b.St	R/W	Stability band (special power alarm function)
262	b.PF	R/W	Power alarm band (special power alarm function)
260	PF.t	R/W	Power alarm delay time (special function)
160*	rL.1	R/W	Allocation of reference signal
163*	rL.2	R/W	Allocation of reference signal
166*	rL.3	R/W	Allocation of reference signal - Output OR
170*	rL.4	R/W	Allocation of reference signal - Output AND
171*	rL.5	R/W	Allocation of reference signal - Output OR
172*	rL.6	R/W	Allocation of reference signal - Output AND

PREHEATING SOFTSTART

31	S.tu	R/W	Enable selftuning, autotuning, softstart
263	SP.S	R/W	Softstart setpoint (special function)
264	So.P	R/W	Softstart power (special function)
147	SoF	R/W	Softstart time
63 bit	STATE OF SOFTSTART	R	OFF = Softstart in Stop ON = Softstart in Start

HEATING OUTPUT (fast cycle)

160*	rL.1	R/W	Allocation of reference signal
163*	rL.2	R/W	Allocation of reference signal

TRIGGER MODES

703*	Hd.S	R/W	Enable trigger modes
707*	Fu.tA	R/W	Maximum limit of RMS current at normal operation
704*	bF.CY	R/W	Minimum number of cycles of BF modes

SOFTSTART

630*	PS.H1	R/W	Maximum phase of phase softstart ramp
705*	PS.tr	R/W	Duration of phase softstart ramp
629*	PS.oF	R/W	Minimum non-conduction time to reactivate phase softstart ramp
706*	PS.tA	R/W	Maximum peak current limit during phase softstart ramp
108* bit	Restart of phase softstart ramp	R/W	OFF = Restart not enabled ON=Restart enabled
106* bit	State of softstart ramp from phase	R	OFF = Ramp not ended ON = ramp ended
107* bit	State of softstart ramp from phase	R	OFF = Ramp not ended ON = ramp ended

DELAY TRIGGERING

708*	dL.t	R/W	Delay triggering (first trigger only)		
738*	dL.oF	R/W	Minimum non-conduction time to reactivate delay triggering		

FEEDBACK MODES

730*	Hd.6	R/W	Enable feedback modes		
731*	Cor.U	R/W	Maximum correction of voltage feedback		
732*	Cor. I	R/W	Maximum correction of current feedback		
733*	Cor.P	R/W	Maximum correction of power feedback		
734*	r IF.U	R/W	Voltage feedback reference		
735*	r IF. I	R/W	Current feedback reference		
736*	r IF.P	R/W	Power feedback reference		
741*	Fb. It	R/W	Feedback response speed		
113* bit	Calibration of selected feedback reference	R/W	OFF=Calibration non enabled ON= Calibration enabled		
757*	Ar IF	R	Feedback	Setpoint of V, I, P to maintain on load	

HEURISTIC POWER CONTROL

680	hd.3	R/W	Enable heuristic power control		
681	I.HEU	R/W	Maximum current for heuristic power control		

HETEROGENEOUS POWER CONTROL

682	hd.4	R/W	Enable heterogeneous power control		
683	I.HEt	R/W	Maximum current for heterogeneous power control		

VIRTUALINSTRUMENTCONTROL

191	hd. 1	R/W	Enable multiset instrument control via serial		
224*	S. In	R/W	Control inputs from serial		
225	S.Ou	R/W	Control outputs from serial		
628	S.L I	R/W	Control LEDs and digital inputs from serial		

122	UPd	R	Software version code			
85	Err	R	Self-diagnosis error code for main input			
606	Er.2	R	Self-diagnosis error code for auxiliary input 2			
550	Er.3	R	Self-diagnosis error code for auxiliary input 3			
551	Er.4	R	Self-diagnosis error code for auxiliary input 4			
552	Er.5	R	Self-diagnosis error code for auxiliary input 5			
190	C.Hd	R	Hardware configuration codes			
508	C.Hd1	R	Hardware configuration codes 1			
543	C.Hd2	R	Hardware configuration codes 2			
693 697	UPd.F	R	Fieldbus software version			
695	Cod.F	R	Fieldbus node			
696	bAU.F	R	Fieldbus baudrate			
346		R	State of jumper			
120		R	Manufact - Trade Mark (Gefran)			
121		R	Device ID (GFW)			
197	Ld.St	R/W	RN status LED function			
619	Ld.2	R/W	ER status LED function			
620	Ld.3	R/W	DI1 LED function			
621	Ld.4	R/W	DI2 LED function			
622	Ld.5	R/W	O1 LED function			
623	Ld.6	R/W	O2 LED function			
624	Ld.7	R/W	O3 LED function			
625	Ld.8	R/W	O4 LED function			
305*		R/W	State (STATUS_W)			

467*		R	State (STATUS)
469*		R	State 1 (STATUS1)
632*		R	State 2 (STATUS2)
633*		R	State 3 (STATUS3)
634*		R	State 4 (STATUS4)
702		R	Voltage status

KEYPAD USE

This charter describes the optional GFW-OP keypad and use mode to display and program parameters.

← Signal led

← Liquid crystal display
5 alphameric lines of
21 characters each

← Pad keypad

Description

The program keypad is used to display the state and diagnostic parameters during operating period; on the back is present a magnetic material strip to fix it on GFW-master frontal or on a metal surface (ex. Electrical panel door). The keypad is equipped with a connection cable of 70 centimeters.

Membrane keyboard

The following table describes the keypad and its functions:

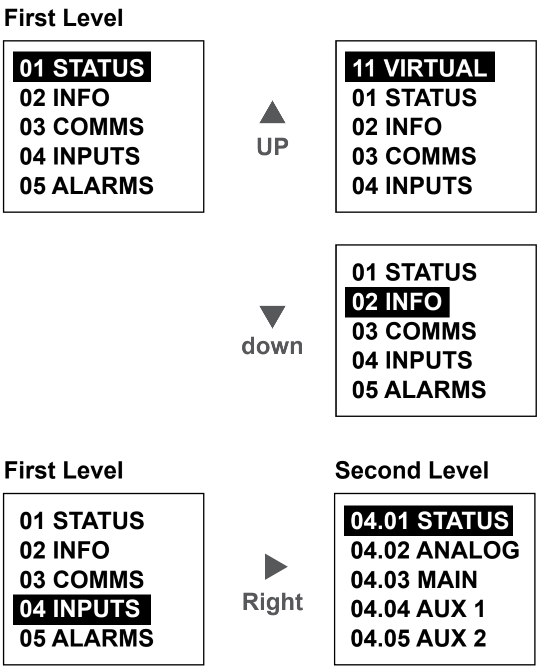
Symble	Reference	Description
ESC	Escape	Comes back to the higher menu or submenu. Exits from a parameter, or a parameter list. Allows to exit from a message requiring its use.
SAVE		No function
FIND		No function
RST		No function
CUST		No function
DISP		No function
E	Enter	Enters the submenu or the selected parameter, or selects an operation. It is used during the parameter change to confirm the new set value.
^	Up	Moves the selection in a menu or a parameter list highwards. During a parameter change, increases the figure value under the cursor.
v	Down	Moves the selection in a menu or a parameter list downwards. During a parameter change, decreases the figure value under the cursor.
<	Left	Comes back to top menu. During a parameter change, moves the cursor verso rightwards.
>	Right	Enters the submenu or the selected parameter. During a parameter change, moves the cursor verso rightwards.

Leds meaning:

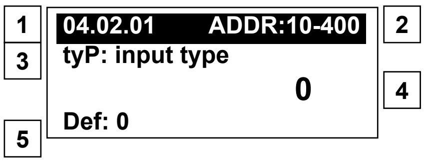
LEDs	Colour	Led meaning
BRK	Yellow	Led is on when GFW is OFF software
CNT	Yellow	Led is on when GFW is in manual operating
EN	Green	Led is on when during power supply
ILIM	Red	This led flashes when GFW reaches a current limit condition (if enabled). During normal operation this led is off.
N=0	Yellow	Led is on when during softstart ramp
AL	Red	Led is on when GFW signals an alarm trigger

Netsurfing

Scan of first and second level menus:



Parameter display



(1) Indication of menu and of parameter position

(2) Modubus address of parameter (node - address 16 bits or address 1 bit)

(3) Parameter description

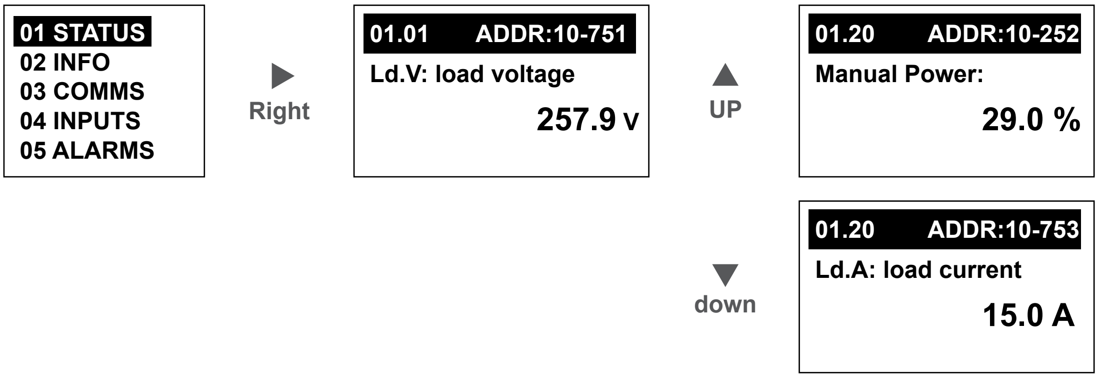
(4) Depends on the parameter type:

- Numerical parameter: displays the parameter numerical value, in the requested format and measurement unit.

(5) This position displays:

- Numerical parameter: displays the minimum and maximum default values of parameter. These values are displayed in order by pressing key ►
- Binary parameter: displays the parameter state (ON-OFF, AUTO-MAN, ...)
- Error signals and conditions:
  Out of range: you are trying to enter a value outside the min and max limits.

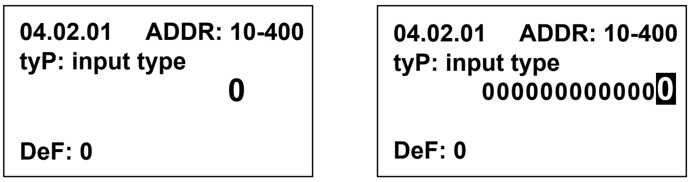
Scan parameters



Change parameters

- To access to change mode press key E when the parameter to changed is displayed.
- To save the parameter value, after changing it, press again key E.
- To exit from change mode without saving the value, press key ESC.
- The operations to execute to change the value depend on the type of parameter, as described below.

Numerical parameters



- When E is pressed, to access to change mode, the cursor on number corresponding to unit is activated.
- Use keys ◄ and ► to move cursor on all the numbers, included the non-signifiant zeroes, which are not normally displayed.
- With keys ▲ and ▼ the number under cursor is increased or decreased.
- Press E to confirm the change or ESC to cancel it.

GEFRAN spa
via Sebina, 74
25050 Provaglio d'Iseo (BS) Italy
Tel. +39 0309888.1
Fax +39 0309839063
info@gefran.com
http://www.gefran.com